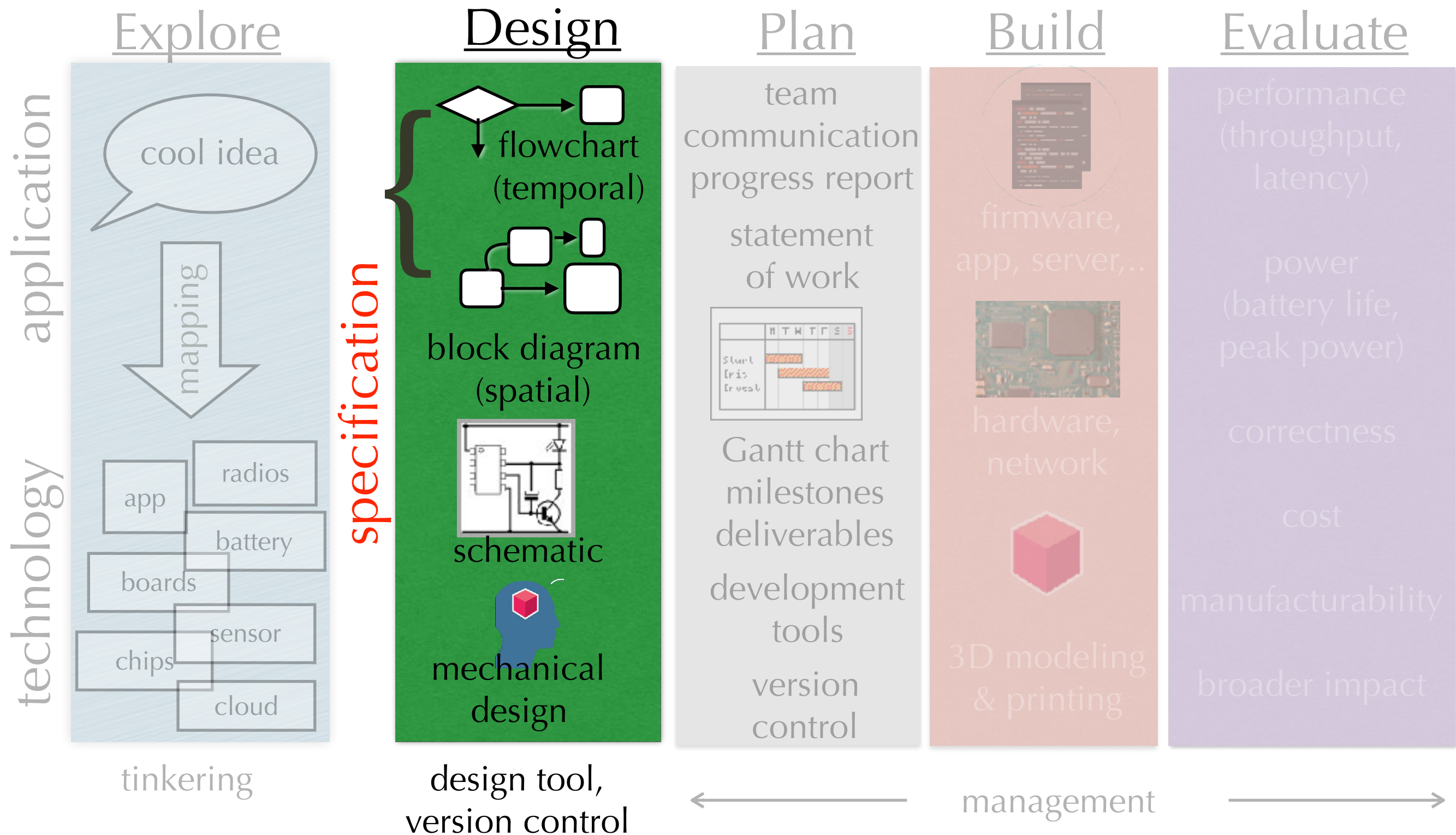


EECS 159A/CSE 181A

MCU-based

System Design

From Spec to Design



Abstraction-based Design

- Identify the level of abstraction for a design task
 - Abstraction means hiding details
- Why abstraction?
 - Separation of concerns
 - When designing at one level, don't want to have to worry about details at another level
- Why not abstraction?
 - Potentially less efficient, but could be improved by “cross-layer optimization”

Layers of Concern

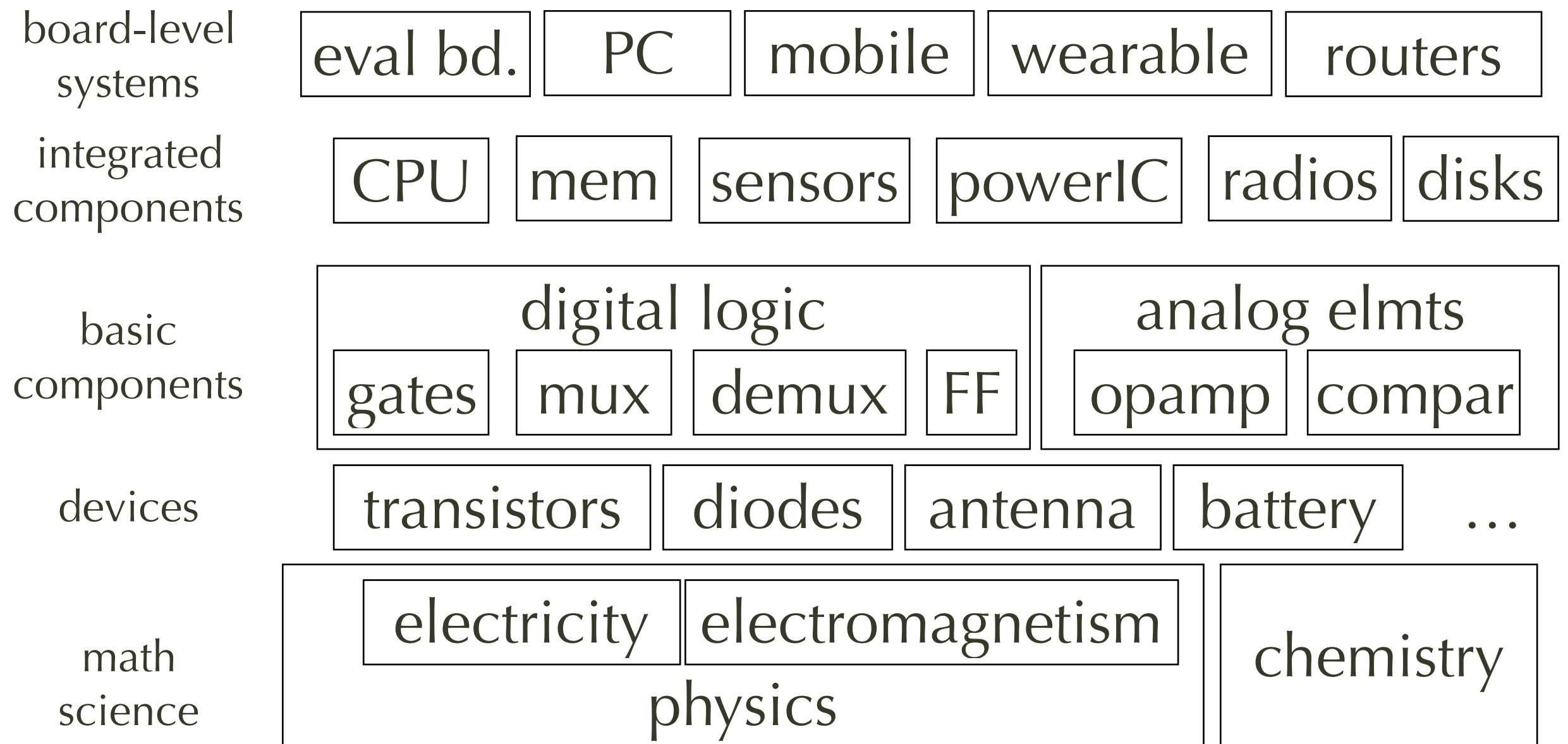
- Abstraction layers

- Application
- Protocol Stack
- Runtime
- Driver
- Hardware
- Electrical

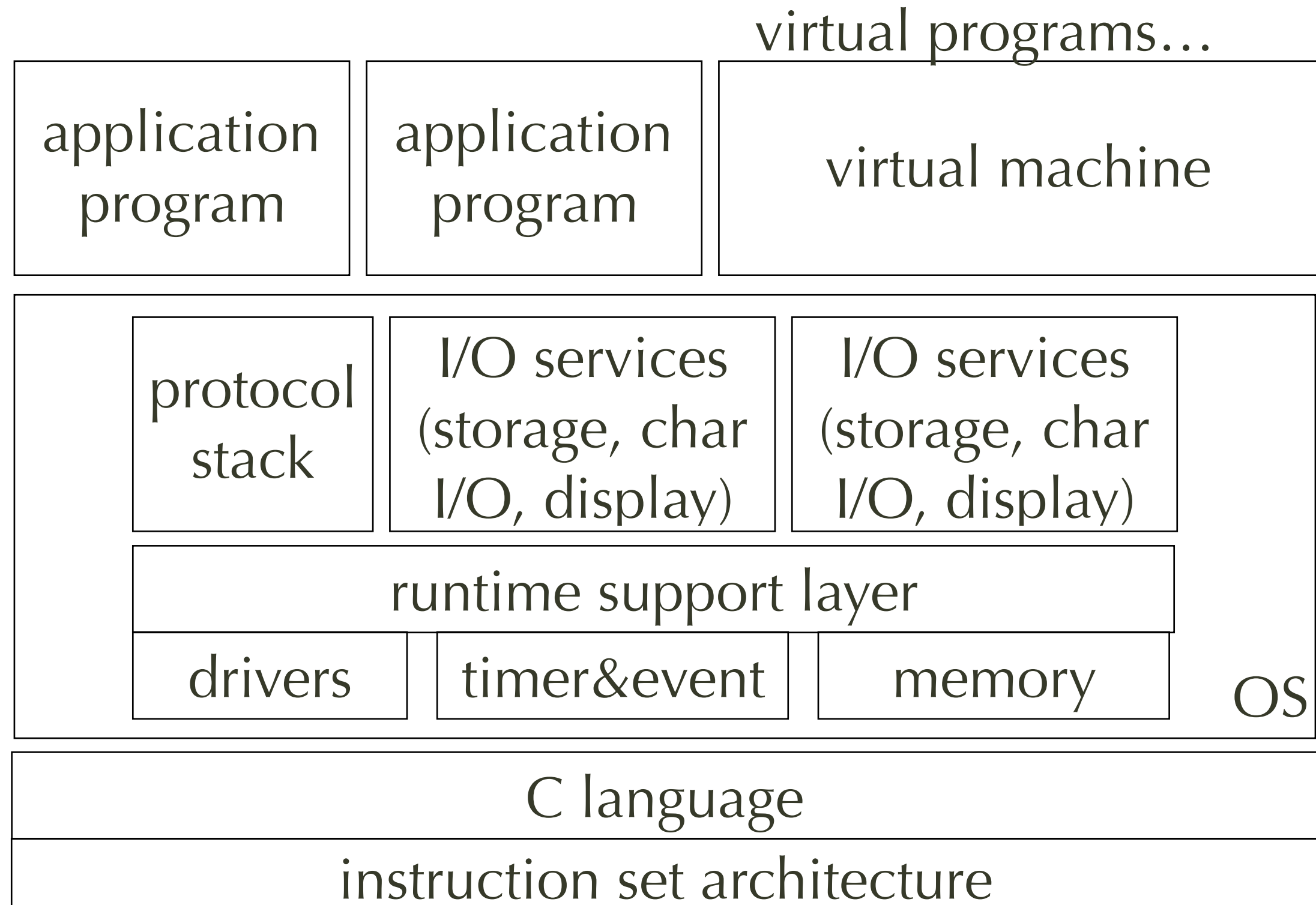
- Domains

- networking
- communication
- software architecture
- hardware architecture
- power and energy

Layers of Abstraction: hardware



Levels of Abstraction: software



Abstraction Layers in your design?

- Hardware

- Existing board with add-on peripherals
- Custom board, custom circuit

- Software

- Existing operating system vs. “bare-metal”
- Existing software library vs. own code
- Existing virtual machine vs. own interpreter

MCU-centric design

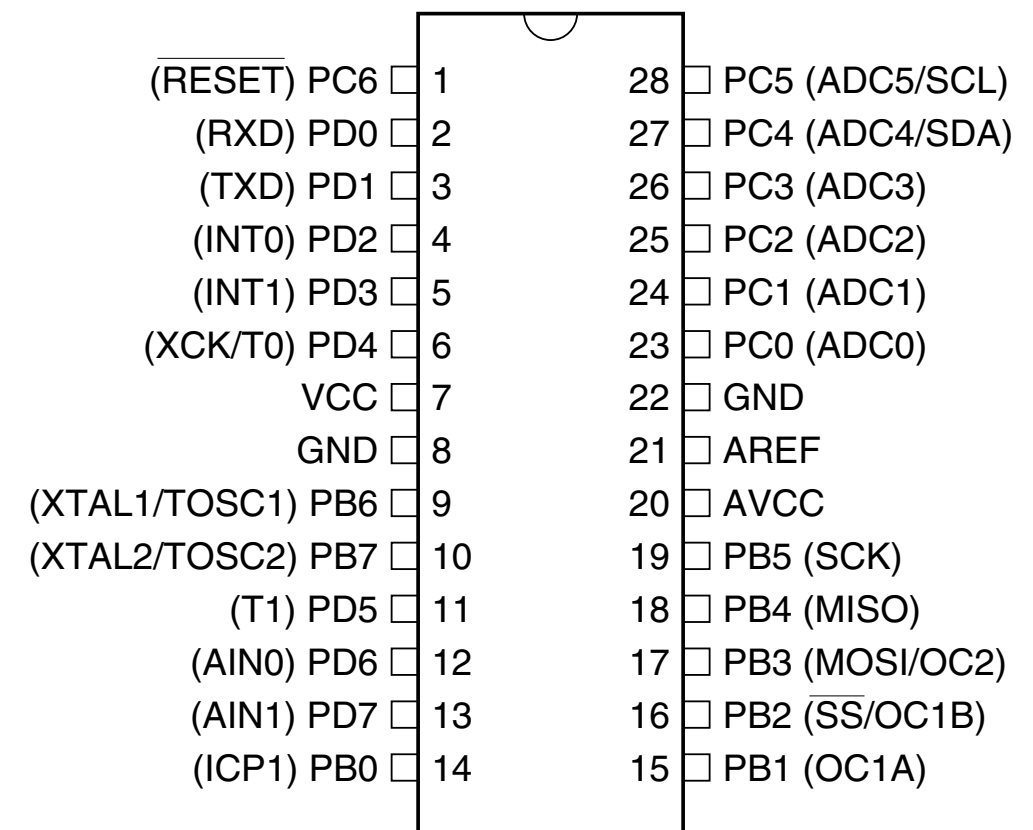
- A convenient starting level of abstraction
 - Centered on a microcontroller unit (MCU)
 - Down to some electrical level
 - Up to several layers of software
- Why MCU?
 - Lets you write software to control hardware
 - Networking or communication capability
 - Possible code reuse

CPU vs. MCU

- CPU ("Central Processing Unit")
 - Processor; main memory is external
 - Bus interface: address, data, control (incl. interrupt)
- MCU (Microcontroller unit)
 - Processor + memory + I/O controllers
 - May have built-in I2C, SPI, UART, USB, Ethernet, DMA, LCD controller, PWM, RF transceivers, ...

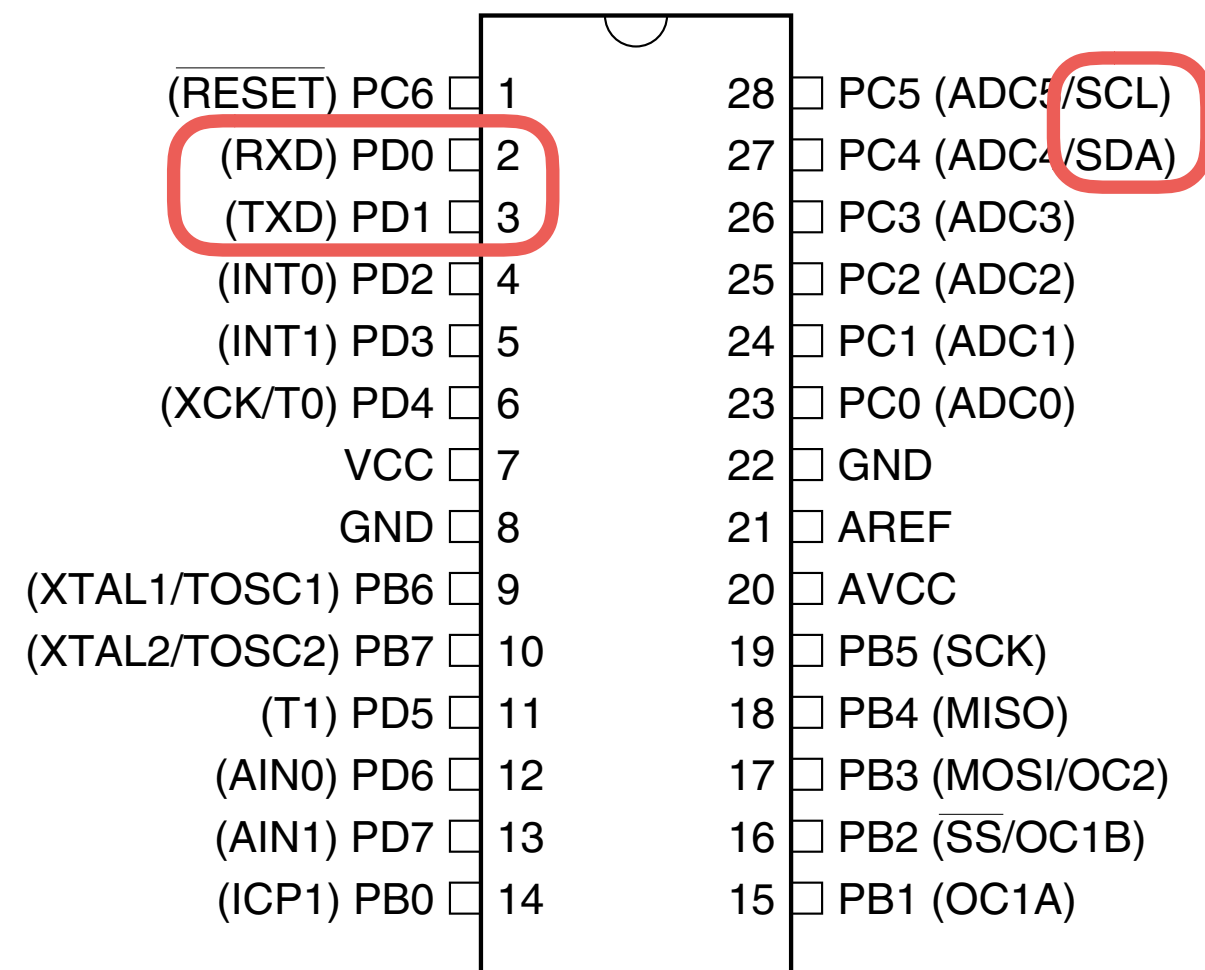
Case Study MCU: ATmega8

- 8-bit MCU by ATMEL
 - 8 KB flash, 512B EEPROM, 1KB SRAM
 - 3 PWM channels
 - 8 channels of 10-bit ADC
 - UART, SPI, I2C, watchdog timer, 23 GPIO pins
 - 0-16 MHz, 4.5-5.5V supply
 - Power: Active 3.6 mA, Idle 1.0 mA, off .5μA
- used in original Arduino board



Resource Allocation on MCU

- Certain pins are overloaded
- Need to select one out of multiple functions
- e.g., using serial port (RxD, TxD) => can't use PD0, PD1 as GPIO pins
- Others can be shared
- e.g., I2C (SCL, SDA) can be shared by multiple I2C devices

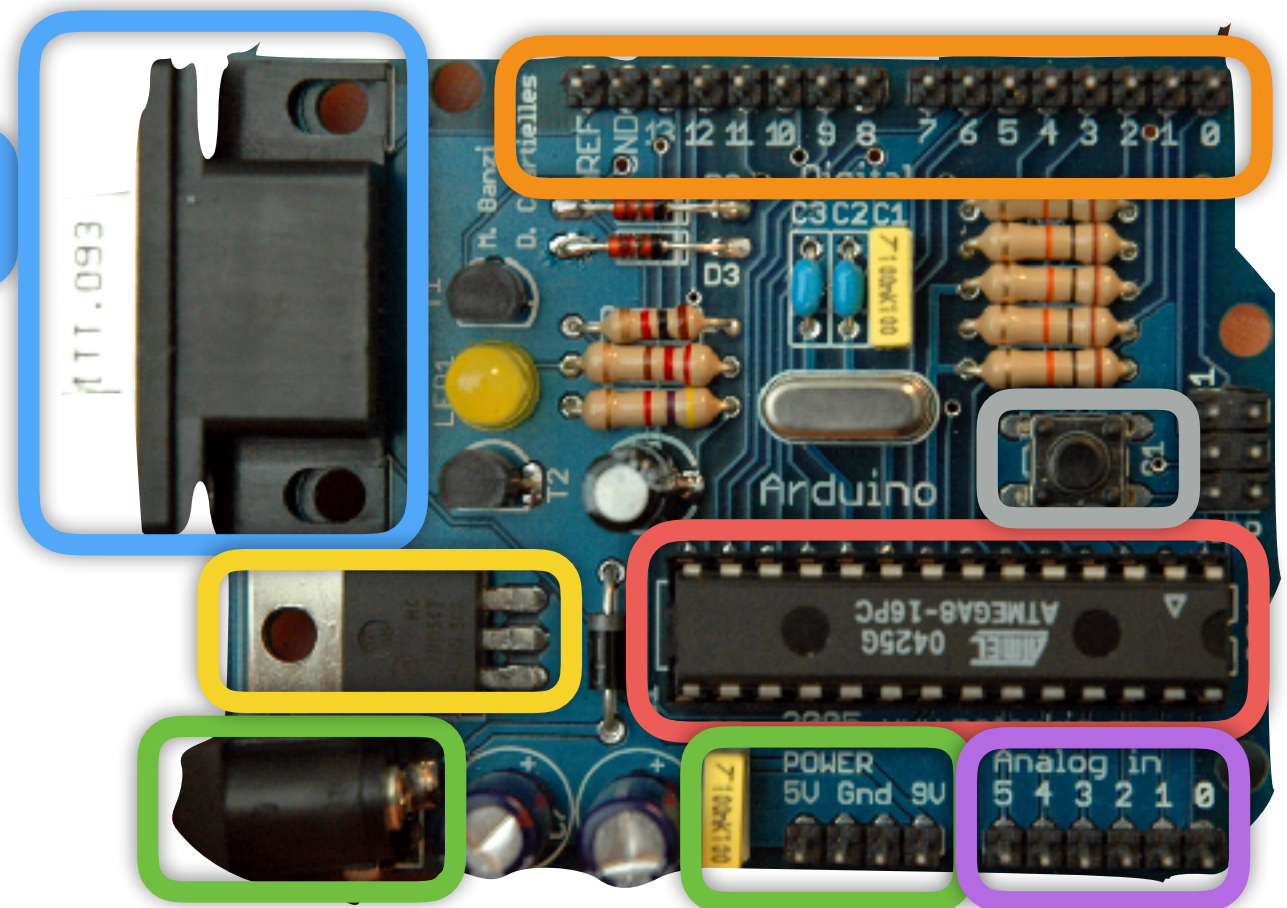


Communication Interfaces

- “Low-level” interfaces
 - UART, I2C, SPI, I2S, ...
 - transfers bytes or sequences of bytes
- “Multi-level” interfaces
 - USB, FireWire, Ethernet, WiFi, Bluetooth, ...
 - Why? because of protocol stack to deal with
 - plug-and-play, connection or pairing,
 - scheduling, routing, arbitration, ...

MCU vs. Board

- MCU is almost always on a board
- example: early Arduino board
 - ATmega8 MCU
 - Connectors for
 - power, ADC, serial, I/O expansion
 - voltage regulator
 - button, and more...



Connecting Peripherals to an MCU

- MCU on a board is just the beginning
- Usually need additional peripherals, if not already on-chip or on-board
 - User input and output (e.g., keypad, display)
 - Sensor (e.g., barcode reader, magstripe reader)
 - Storage (e.g., SD card, USB flash drive)
 - Communication (e.g., WiFi, Bluetooth, Ethernet, serial port, USB, ...)
 - Real-time clock

Card Readers

- Card interface: barcode, magstripe, RFID
 - How it decodes the data isn't important, unless you are decoding it yourself
- Computer interface: RS-232 or USB?
others?
- This is what matters the most in MCU
- Choose MCU with the interfacing capability

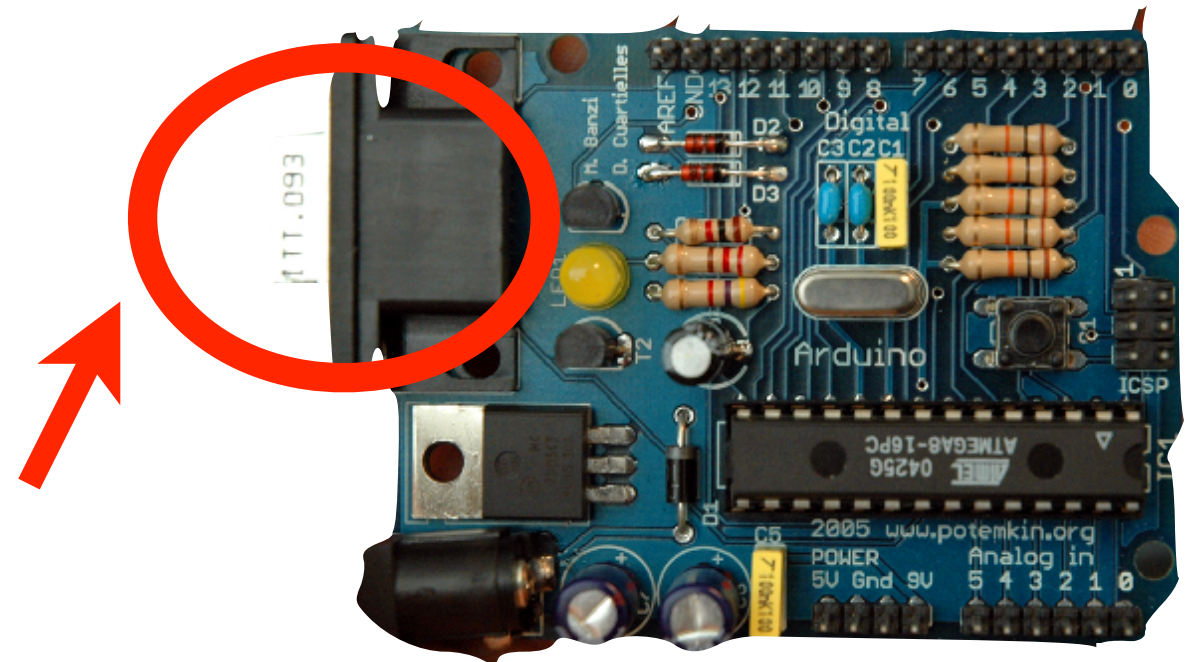
Example card reader to MCU interface

a magstripe reader



DB-9 connector
for RS-232 port

an evaluation board
for the M52259 MCU



can the target board
handle the interface?

what baud rate?

what data or command format?

Example: ID card scanner — Sensor

Card Reader

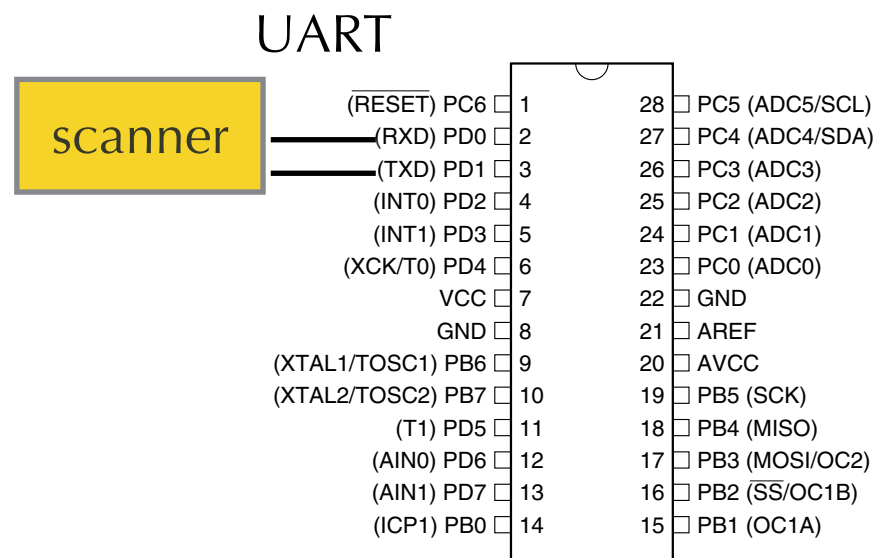
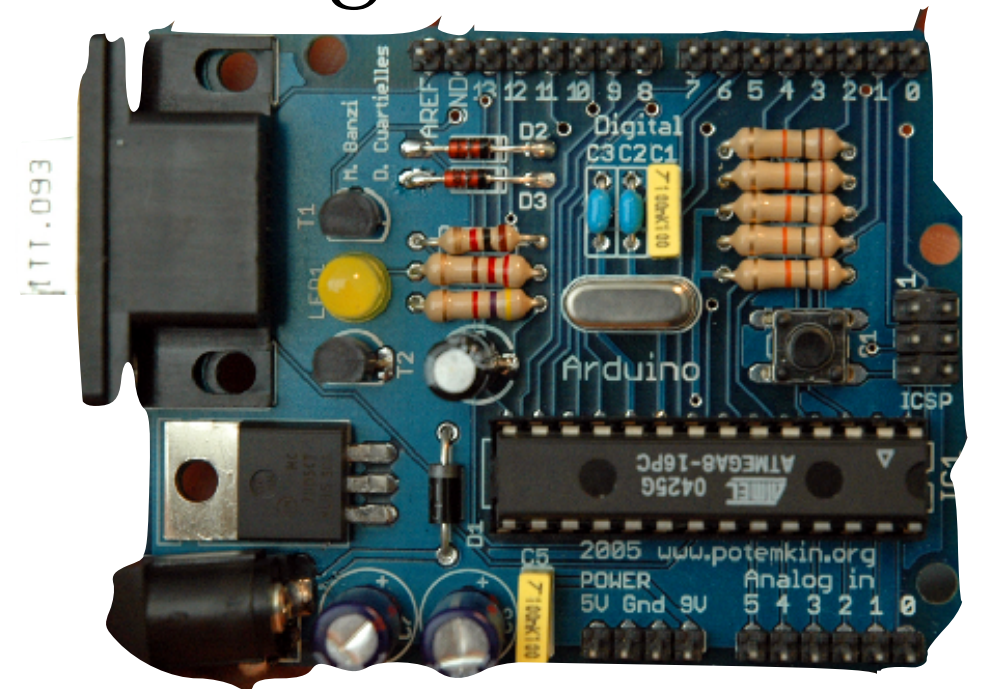


USB

how to connect
when the target
board doesn't
have USB?



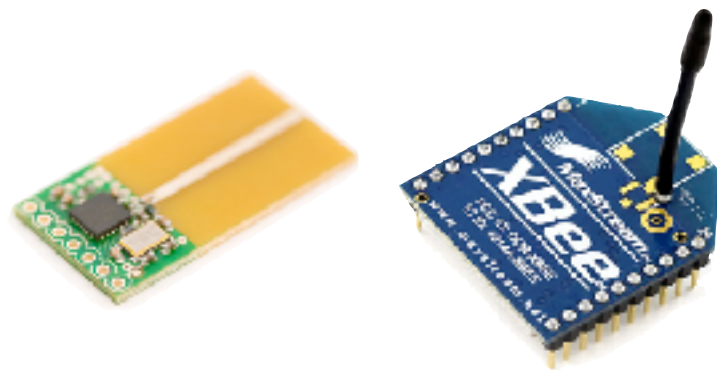
target board



- 1) serial to USB converter (e.g., FTDI)
- 2) use another MCU board with built-in USB (master) controller

Example: ID card scanner — Communication

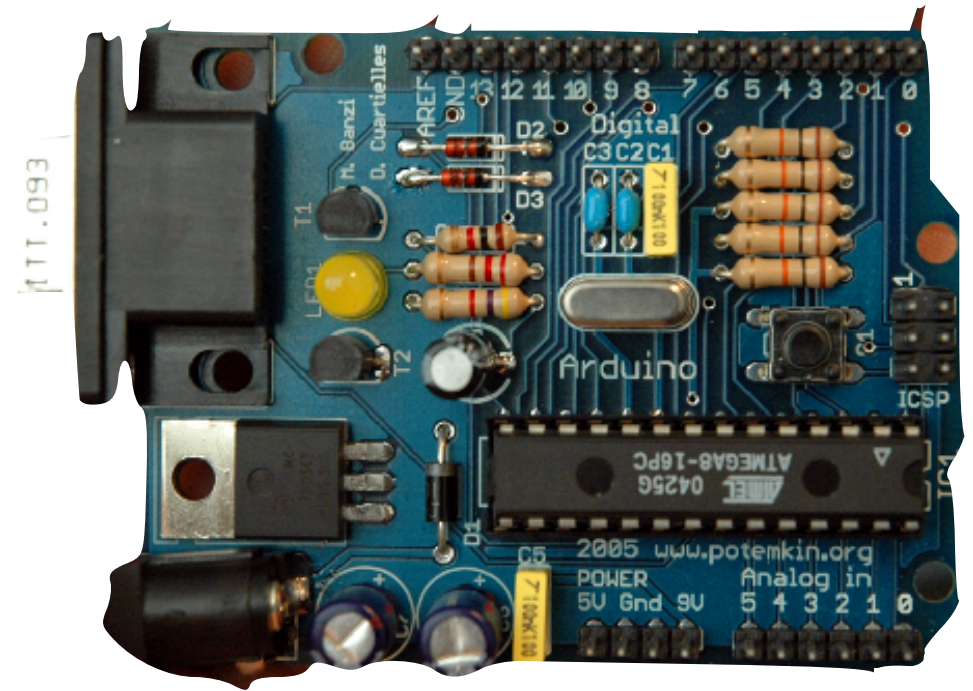
Wireless Interface:
on-chip, on-board,
or add-on?



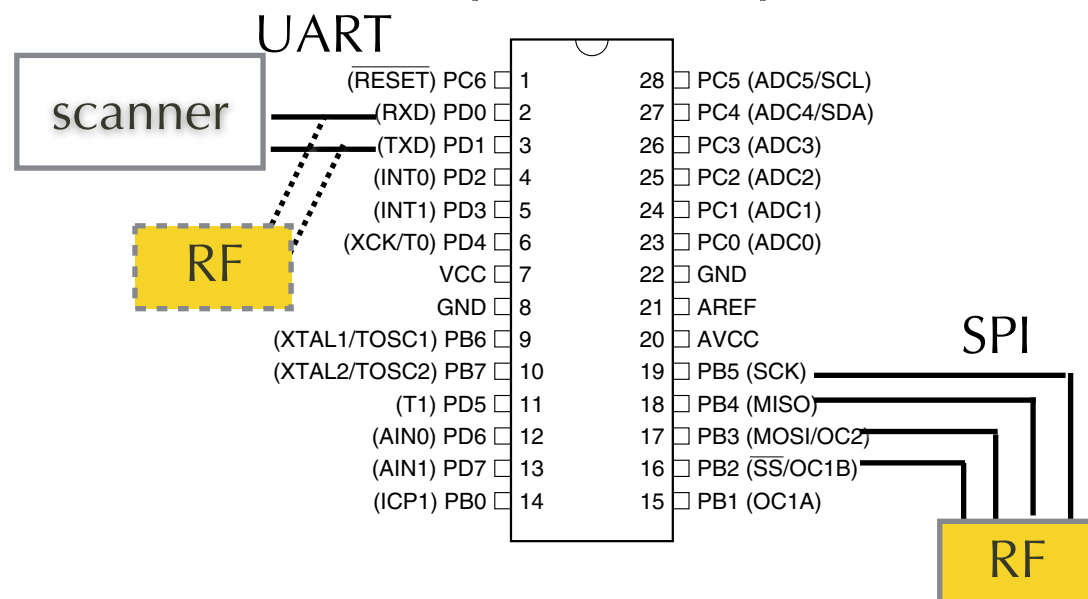
SPI?
UART?



target board



UART => already used by scanner!



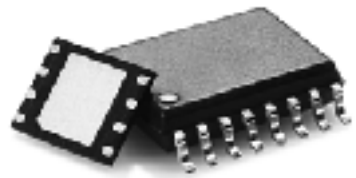
Do you have another
“port” on the MCU to
connect to this
comm. module?

Example: ID card scanner — Flash memory



SD card

- no SD port on Arduino
- could use SPI mode

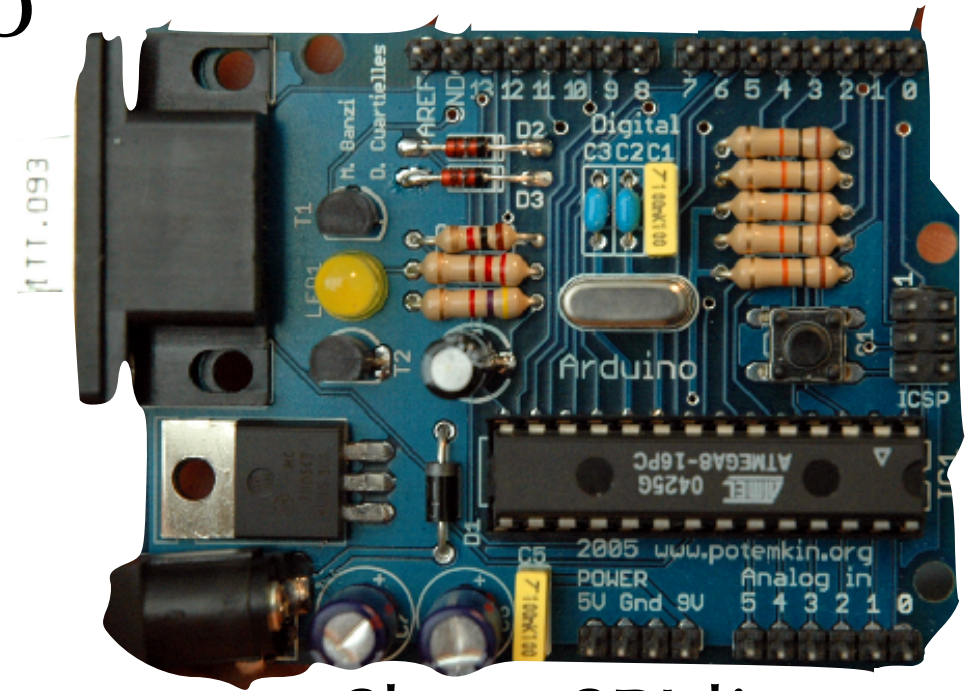


Serial flash (SPI)

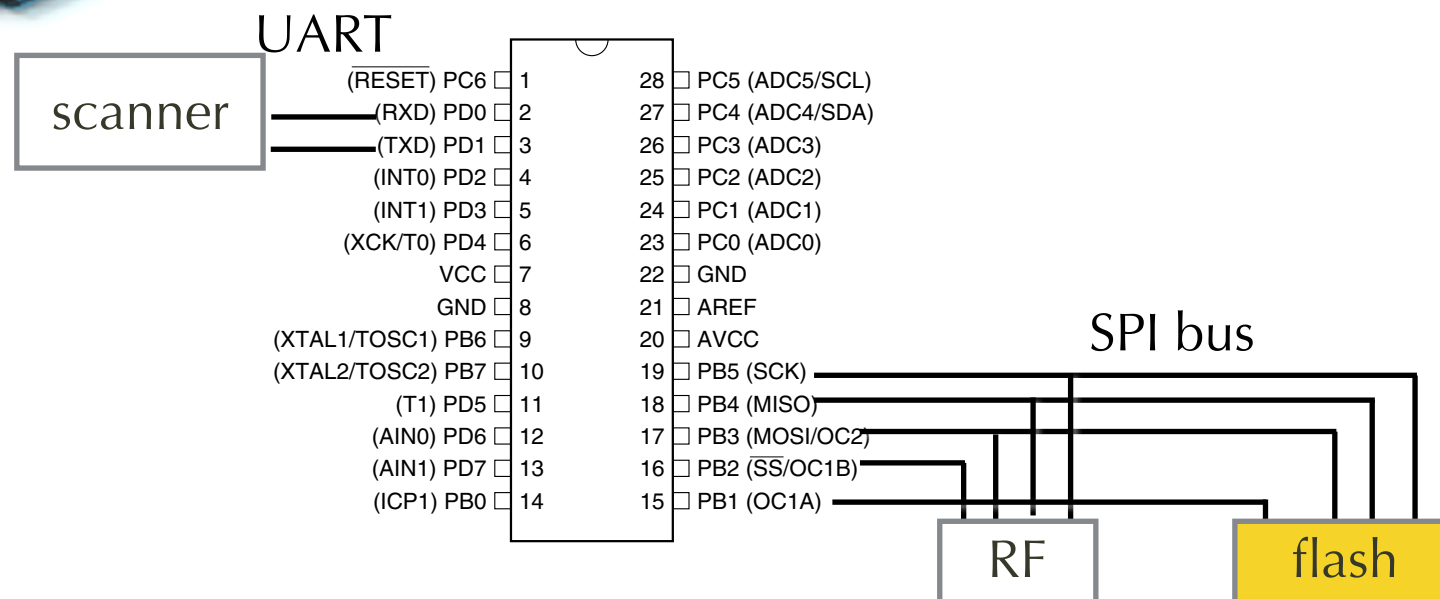


USB? probably not

target board

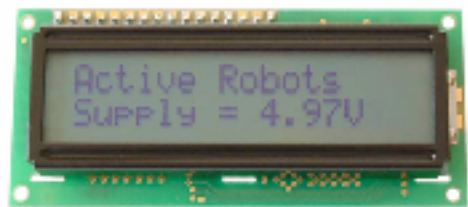


Share SPI lines
between RF & flash,
separate chip-select



Example: ID card scanner — User I/O

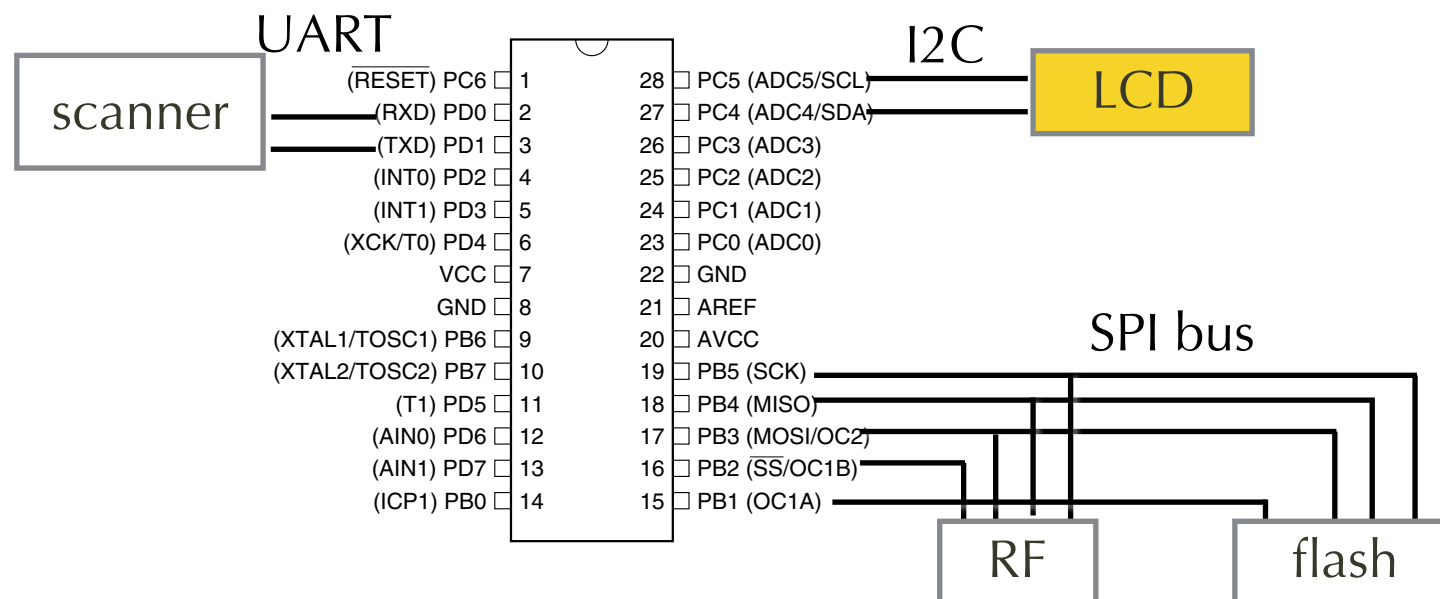
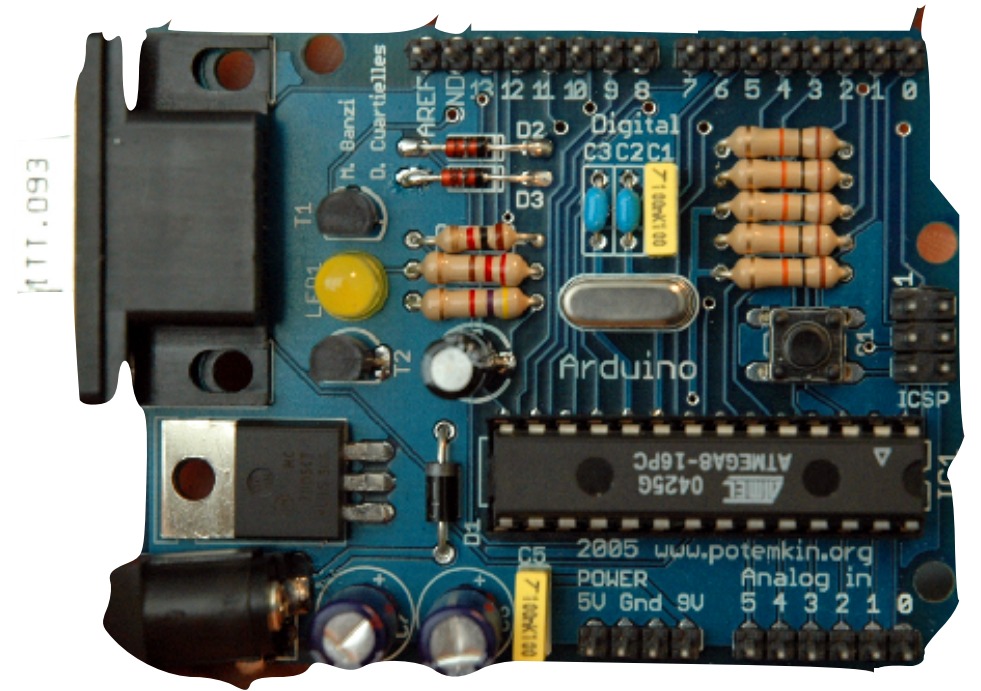
LCD, Keypad



GPIO, I2C



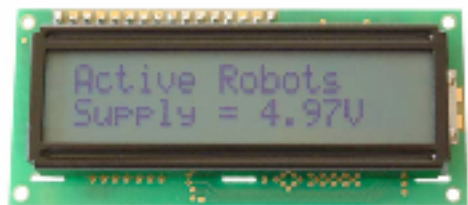
target board



LCD:
Choice of I2C (2 pins)
vs. GPIO (4 or 7 wires)

Example: ID card scanner — User I/O

LCD, Keypad



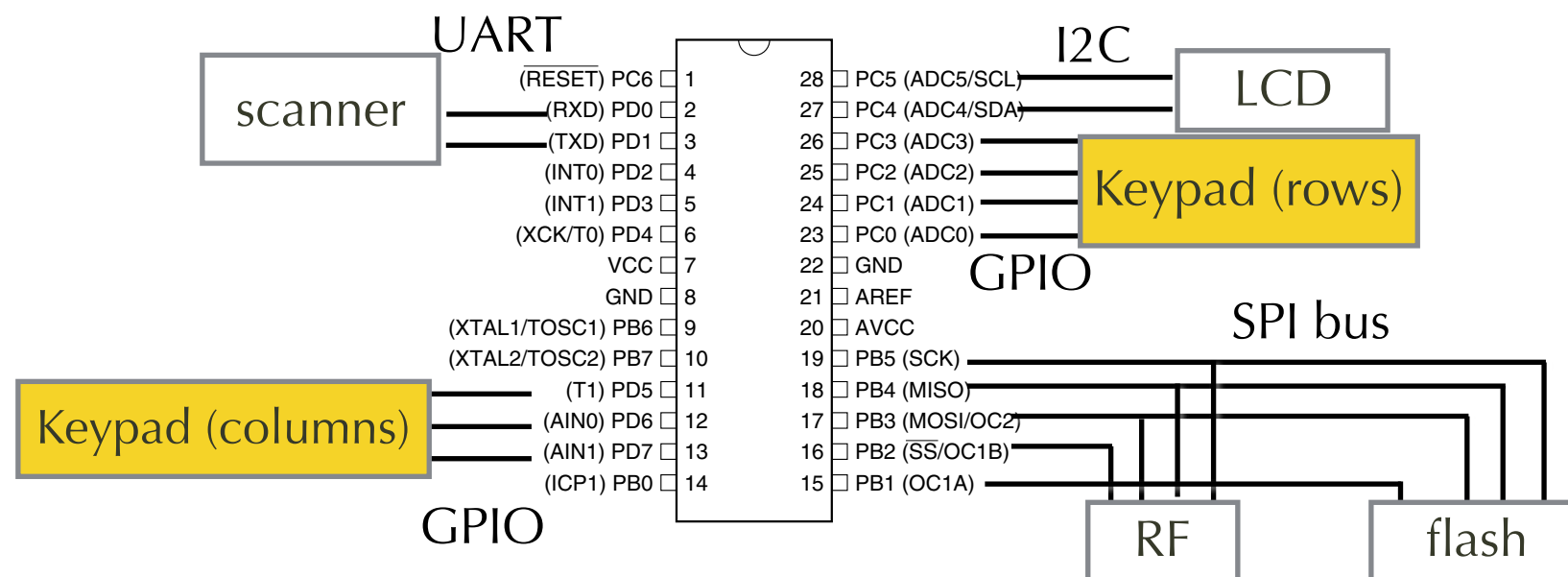
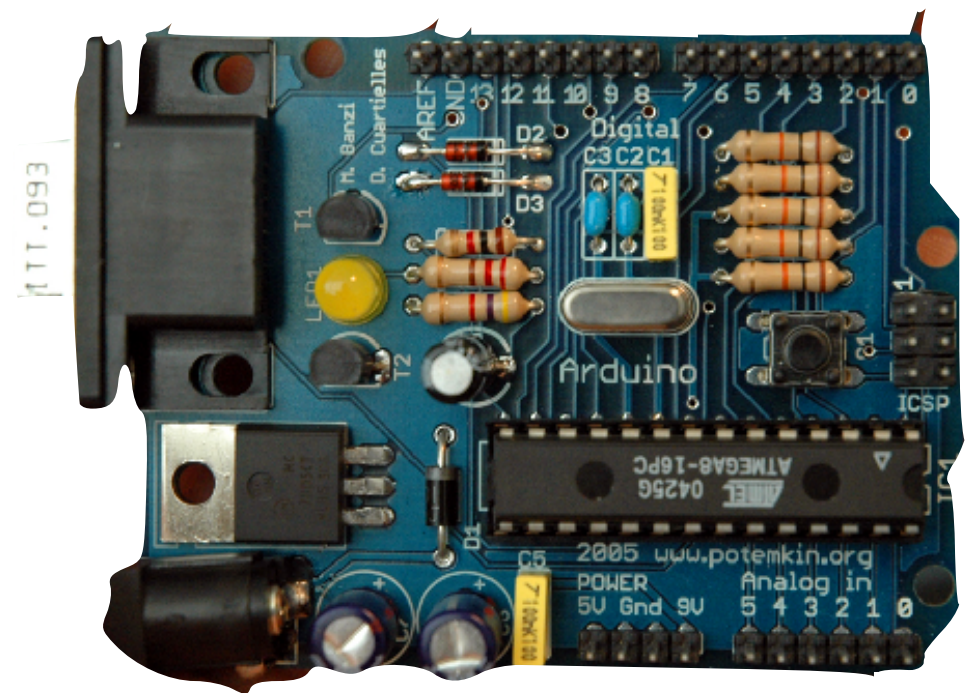
GPIO, I2C



4+3 GPIO



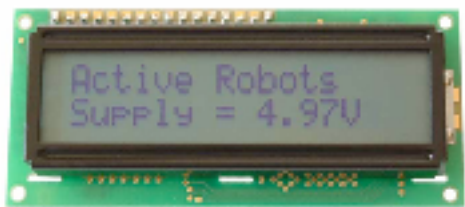
target board



row-column scanning

Example: ID card scanner — User I/O

LCD, Keypad



GPIO, I2C



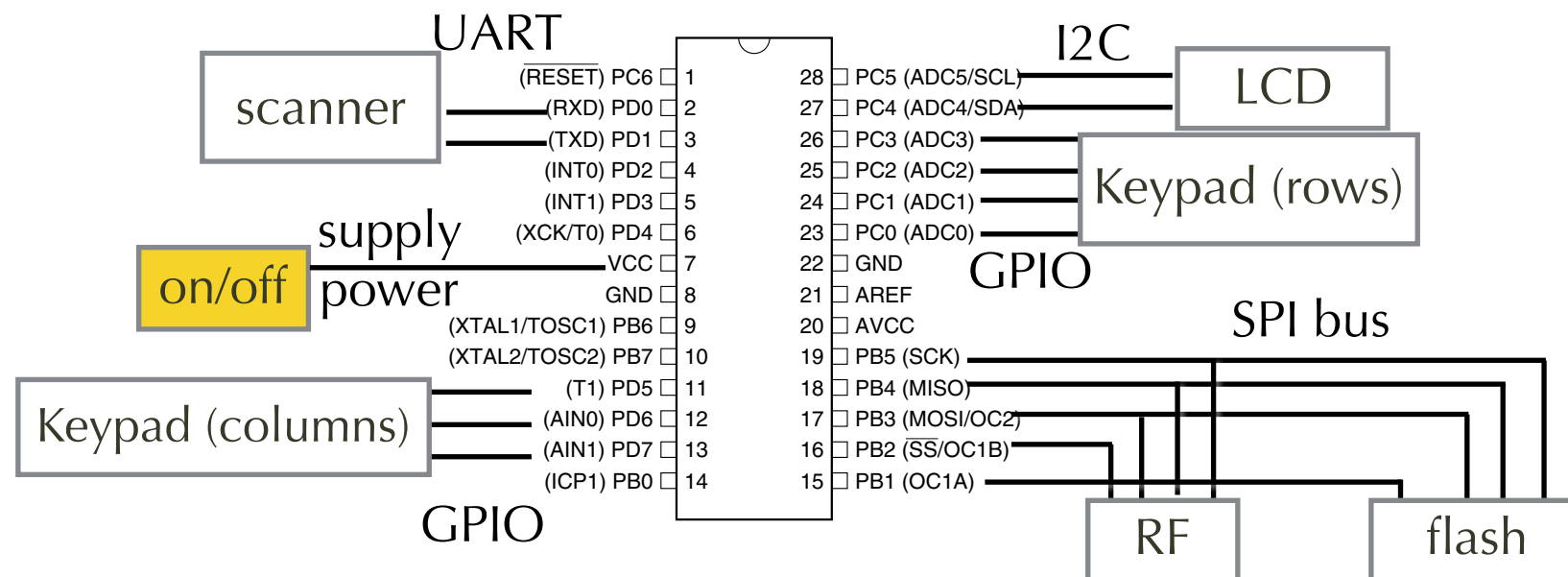
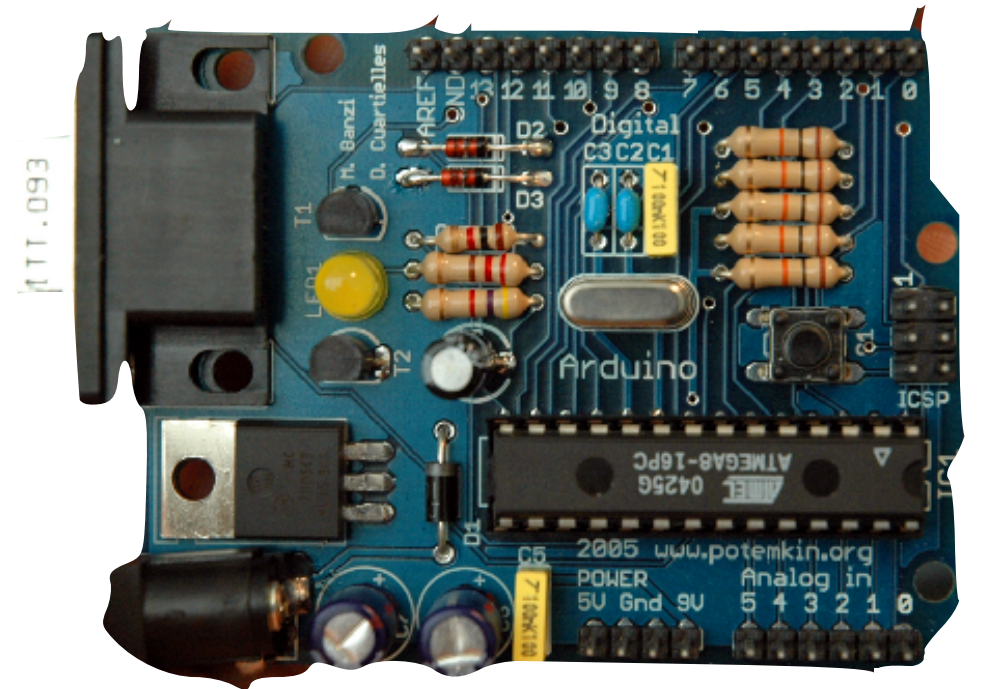
4+3 GPIO



power on/off



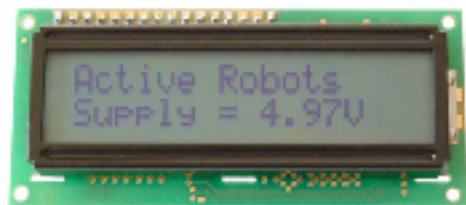
target board



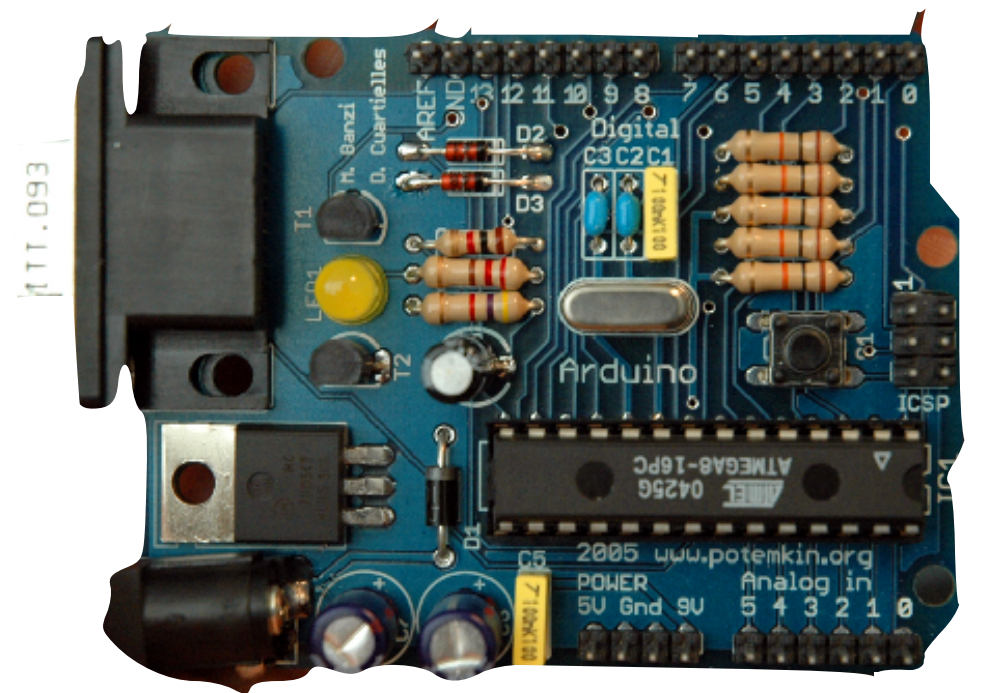
Could be a SPST switch,
cuts off power completely;
or could be a triac,
long-hold to power on/off.
(e.g., LTC2954)

Example: ID card scanner — User I/O

LCD, Keypad



target board

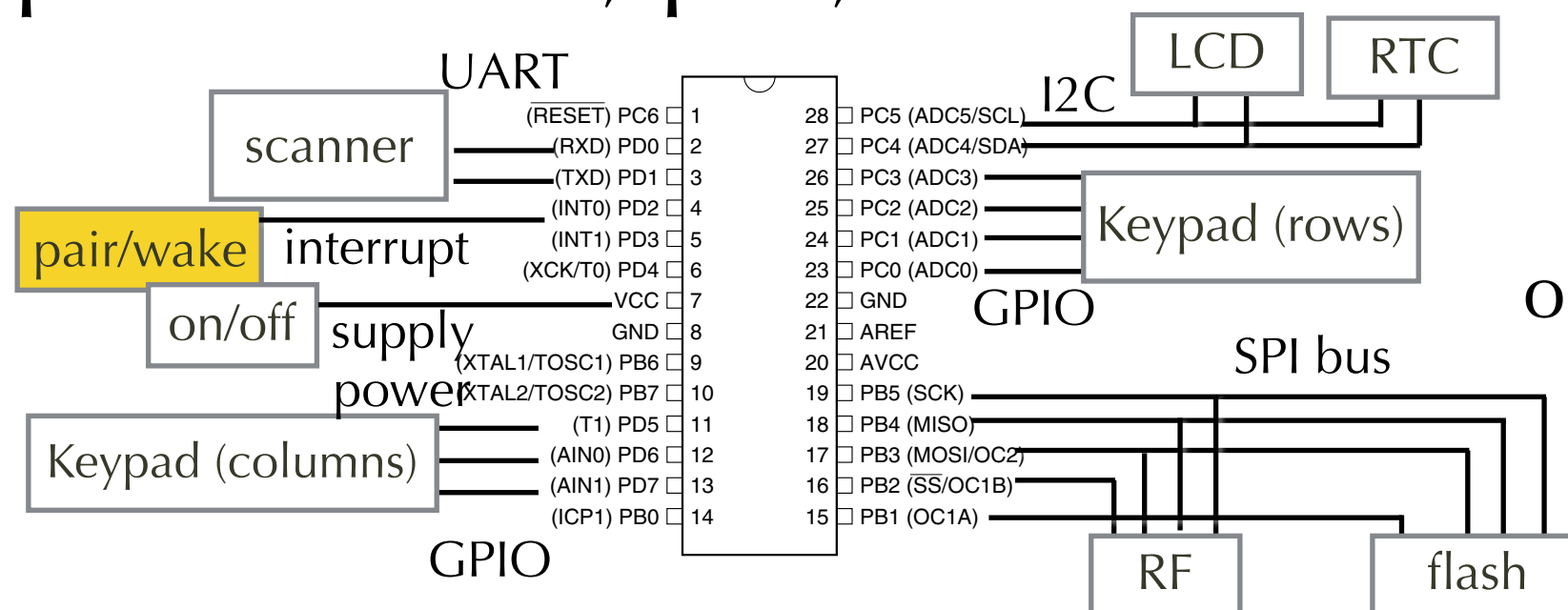


GPIO, I2C

4+3 GPIO



power on/off, pair, wake



should be interrupt driven,
or the RF module may already
handle button & LED

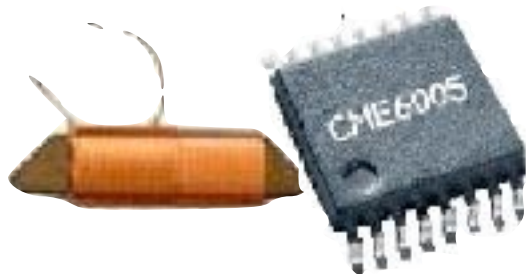
Example: ID card scanner — Real-time Clock

Battery-
backed
RTC



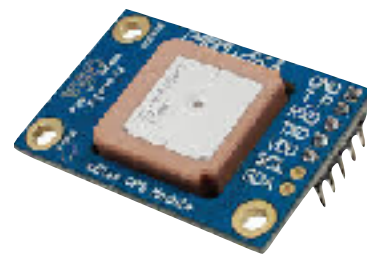
I2C

atomic time
(WWVB)
broadcast



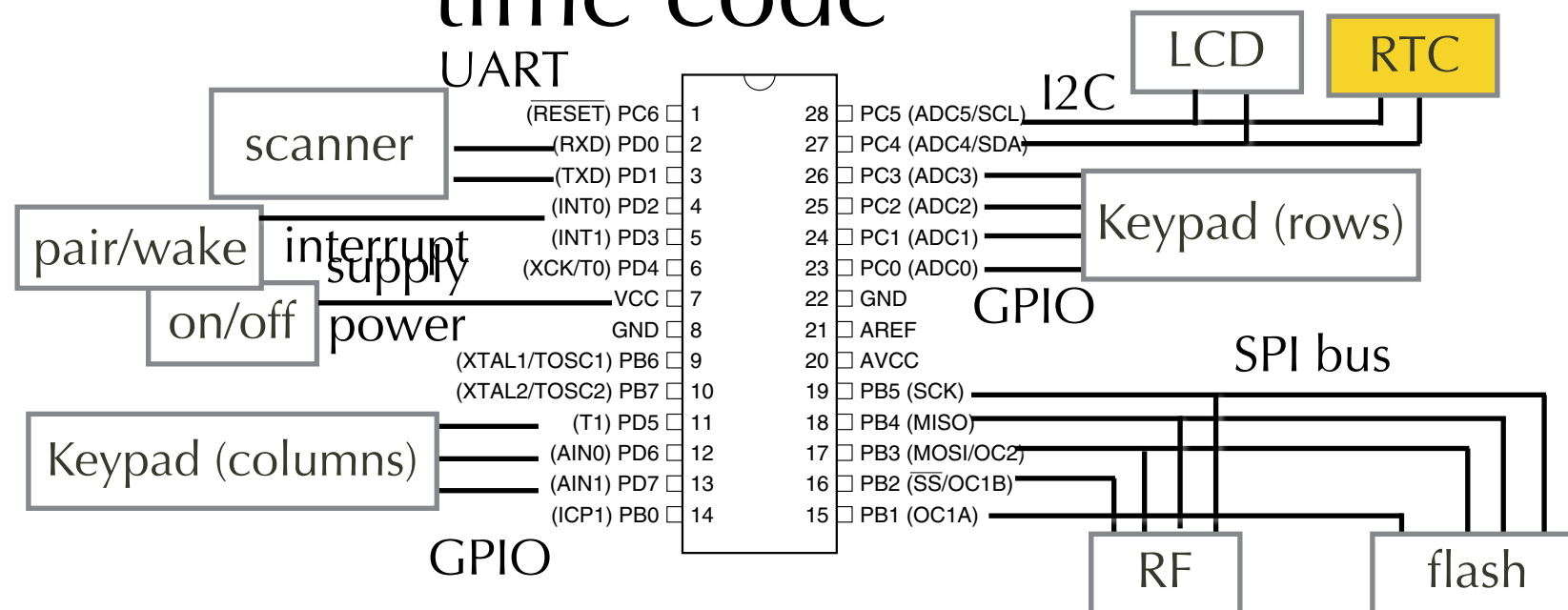
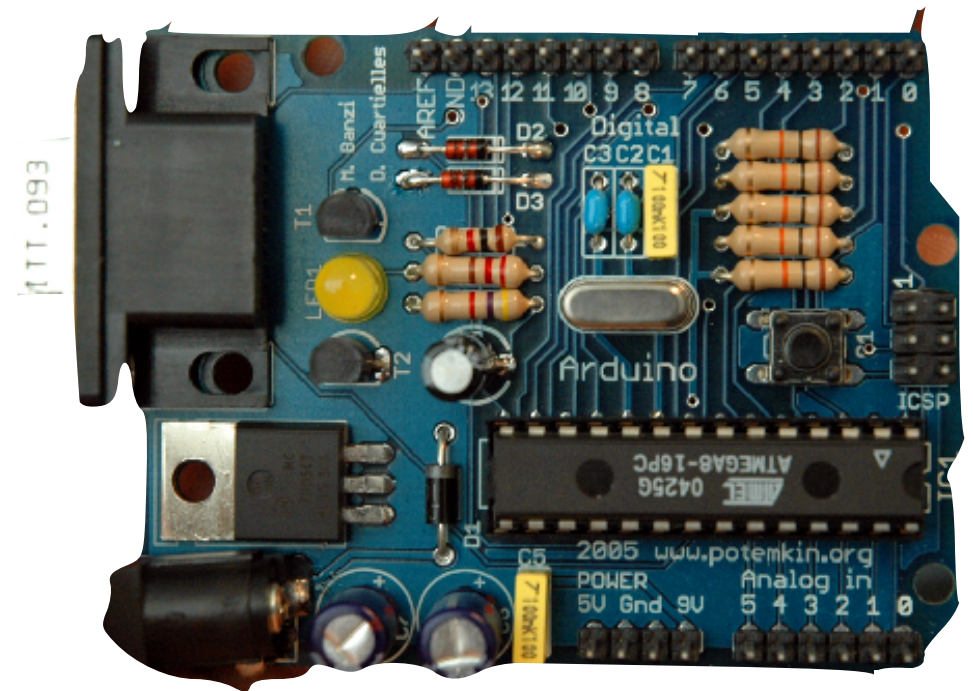
bit-serial
time code

GPS
receiver



UART, I2C

target board

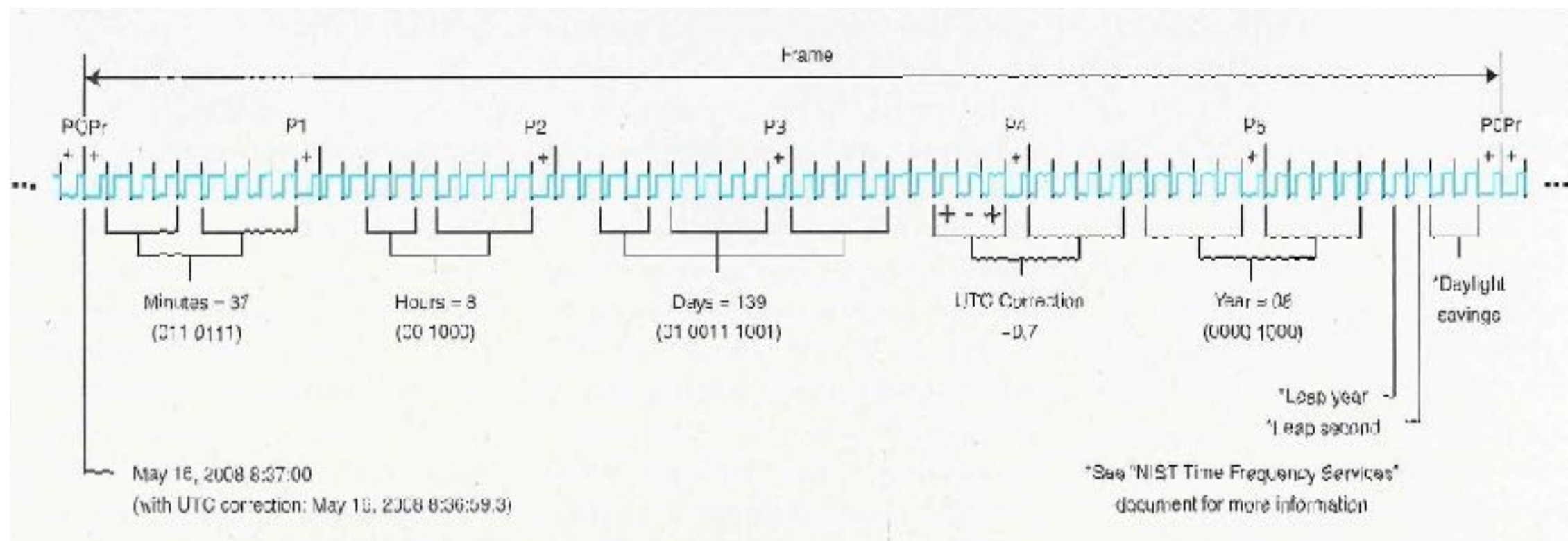


Atomic time broadcast

[Time encoding of WWVB]

- Binary "0" : 0.2s (Low), 0.8 s(High)
- Binary "1" : 0.5s (Low), 0.5s (High)
- Position Maker : 0.8s (Low), 0.2s(High) – indicate the start of frame

=> it takes 60 sec to send of get one frame using falling edge capture of MCU.



Example: ID card scanner — Power Source

AC adapter?
battery pack?
Rechargeable?



4 AA =>
6V or 4.8V

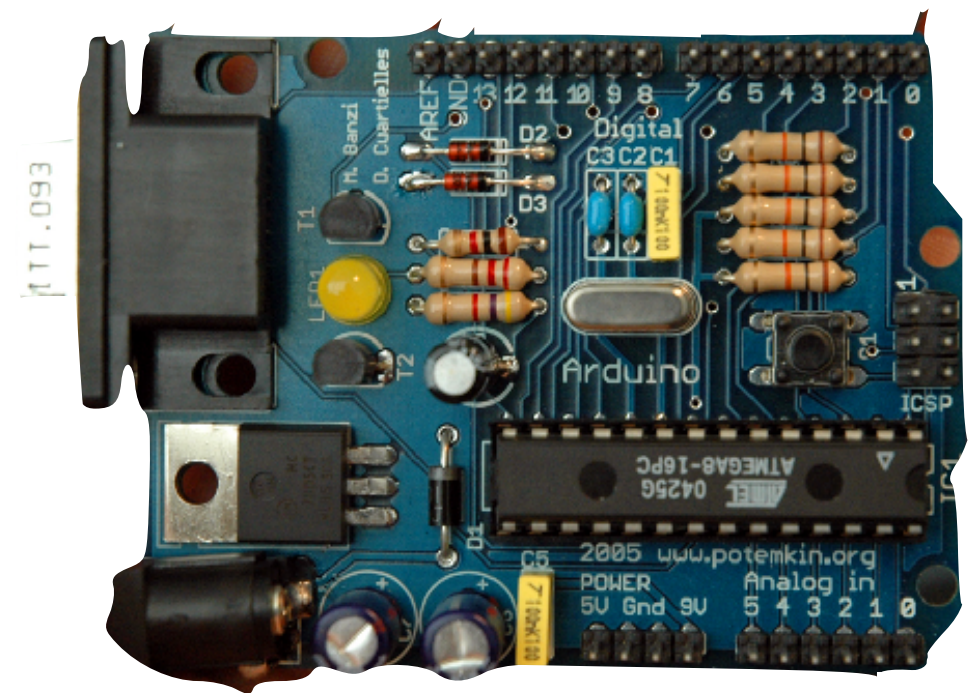


Li-Po =>
4.2V



Coin-cell
=> 3V

target board

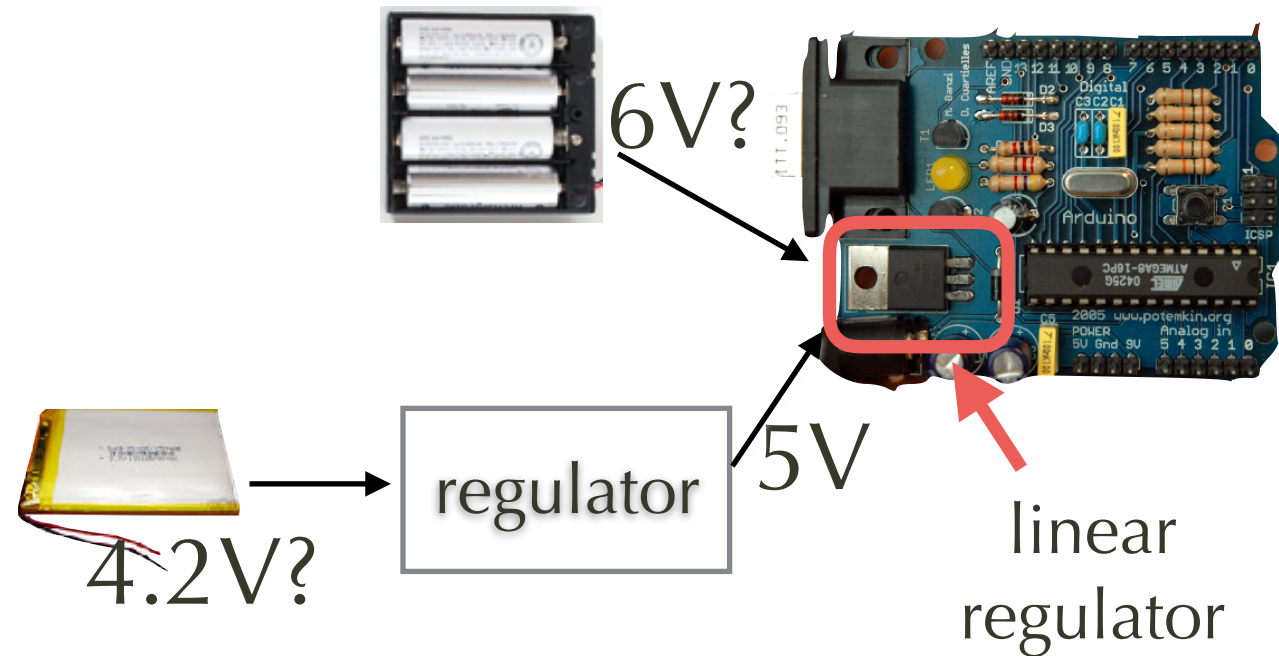


Does the supply support the
required voltage and can
output sufficient current?
How many mAh if battery?

Resolving Differences in Interfaces: Supply Power

- Linear regulators

- caps voltage at a max
- very stable power
- lower efficiency (~60%)



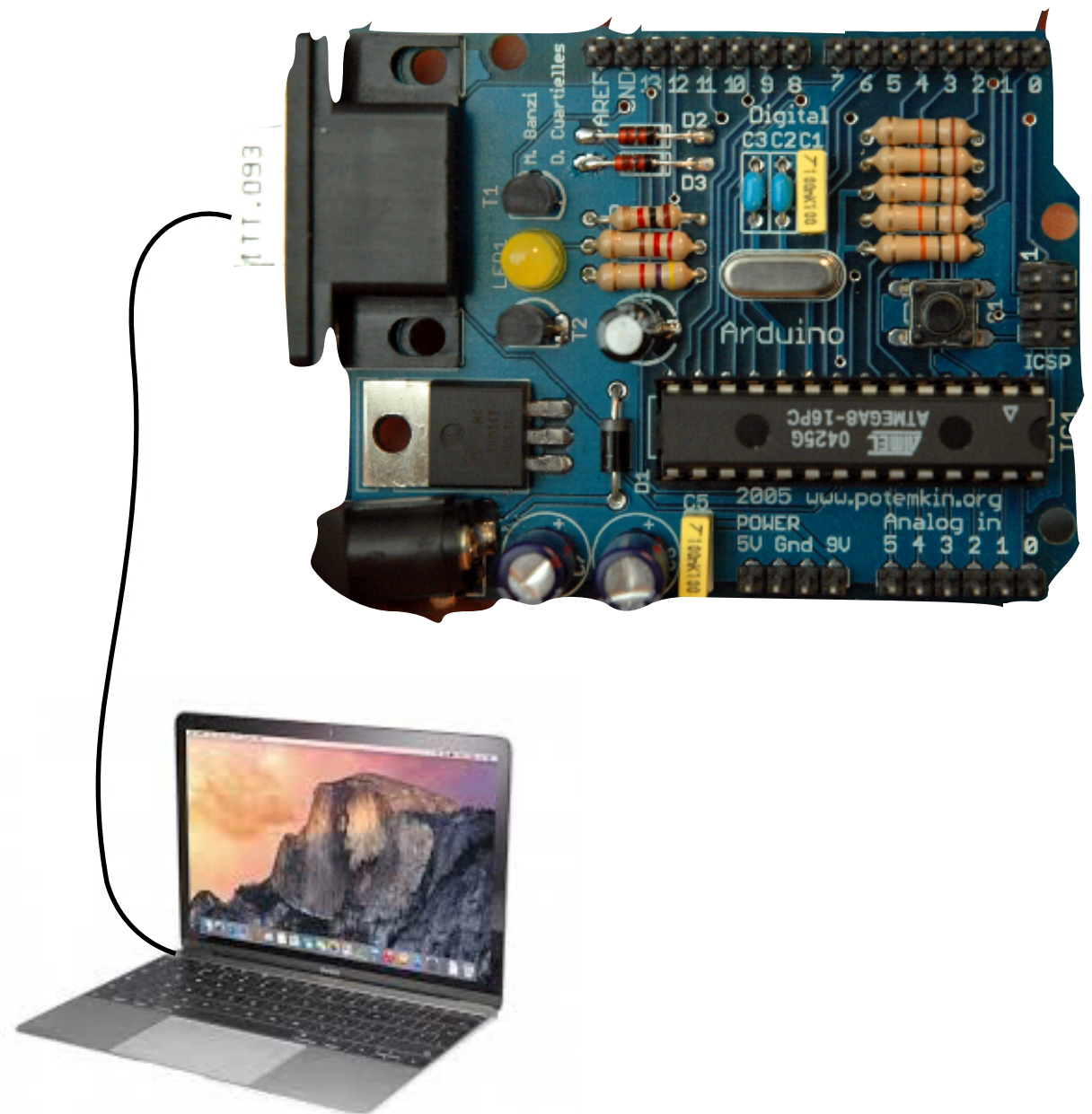
- Switching regulators, aka DC-DC converters

- buck, boost, or buck-boost converters
- higher efficiency (>90%)
- slightly noisy power (ripples)

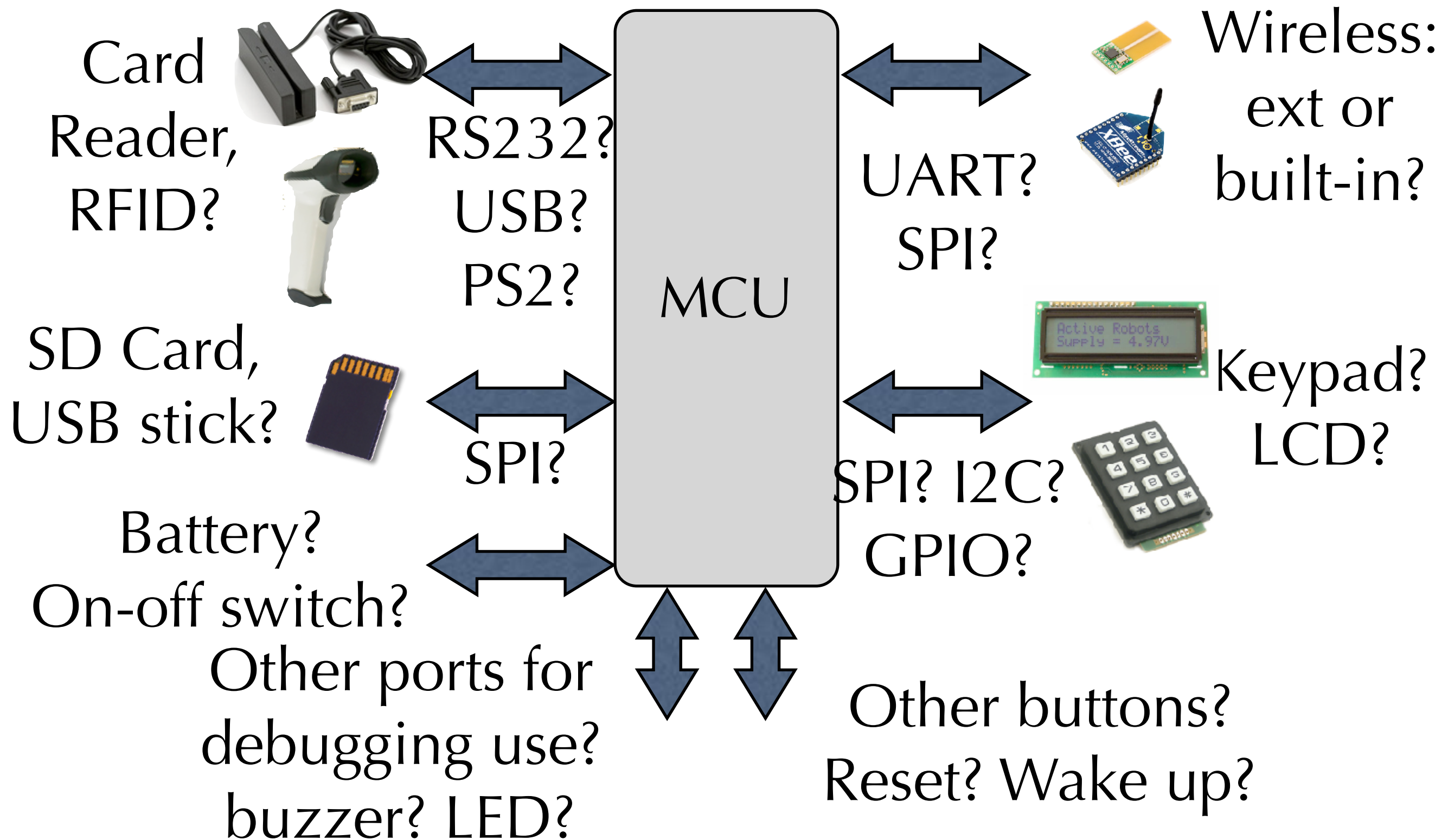
Example: ID card scanner — Firmware & Debugging Interface

- Usually JTAG
 - flashing, stepping, ...
- Bootloader
 - serial port (ISP)?
 - USB? SD Card?
 - over wireless?
- Debugging
 - printf? LED?

target board



Summary of peripheral interfaces



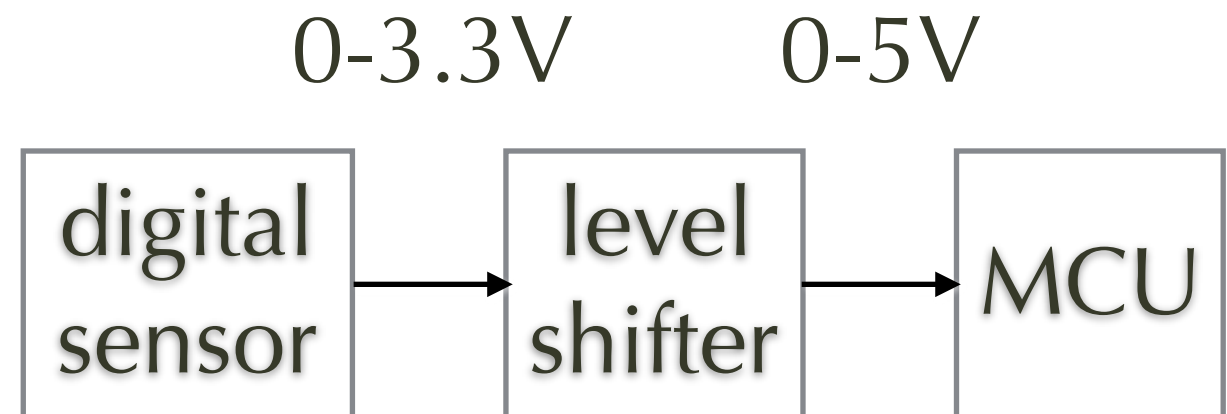
Feasibility

- Enough I/O resources (pins)?
 - digital? analog? serial port? bus? interrupt?
- Enough power? (voltage, current)
 - Active mode, sleep mode
- Enough memory?
 - Code flash?
 - Data RAM?

Resolving differences in signal voltage & current

- Voltage level translator

- unidirectional
- bidirectional
- direction-controlled
- logic level



- Buffer driver

- driving voltage and current on a (bus) line or load (e.g., LED)
- Inverting or noninverting
- UART: CMOS to RS-232 (-25V to +25V)

What if there are not enough GPIO pins?

- Use a multiplexer or demultiplexer
 - Select 1 out of N signals to input or output
 - Requires $\log_2 N$ signals to select
=> not always feasible
 - Can be Digital or Analog Mux or Demux
- Or just pick another MCU w/more pins
 - Could increase size, cost, power consumption
 - May need to switch to another MCU family

Requirements vs. Constraints

- Your (hardware) design may fulfill the required functions, but...
- Does it satisfy all constraints?
 - Enough energy? (battery life)
 - System weight? Size?
 - Latency? Performance?
 - BOM Cost?
- If not, you may need to start over with another MCU

Consider other MCU boards when

- Need to meet requirements
 - I/O and communication capabilities
 - processing capabilities
 - memory capacities
 - power consumption
- Consider other constraints
 - cost of board
 - physical size and weight

Existing MCU Boards

- Reusable hardware and software
 - Hardware: circuit board with MCU, sensor, actuator,
 - Software: runtime support, library, tools
 - Reusable over a range of applications
- Why existing MCU boards (“platform”)?
 - Avoid re-inventing the wheel by customizing
 - A lot of details to get right (e.g., RF, power)
 - Better reuse of code and modules

Arduino - Bluno

- Arduino Uno plus BLE coprocessor
 - MCU sends AT commands to control BLE
 - Uses Arduino software development environment
 - Can add other Arduino shields
- Not as power-efficient as single-chip solution



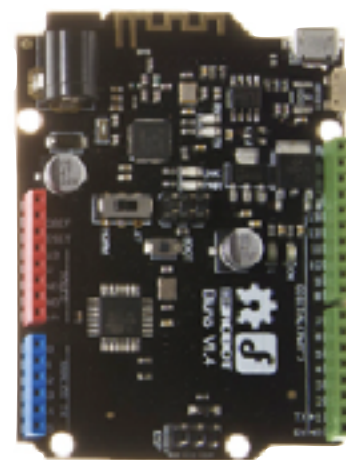
UNO

+



BLE

=



BLUNO



BeagleBoard

<http://beagleboard.org>

- Original BeagleBoard
 - TI OMAP3530 (ARM Cortex A8)@720MHz
 - Ethernet, USB, HDMI, SD card
- BeagleBoard Black (~\$55)
 - TI AM3359 (Cortex A8)@1 GHz
 - 512MB DDR3 RAM, 4GB flash storage
 - 600-1000 mW active, 5-7mW sleep
 - Ethernet, μ USB, μ HDMI, μ SD

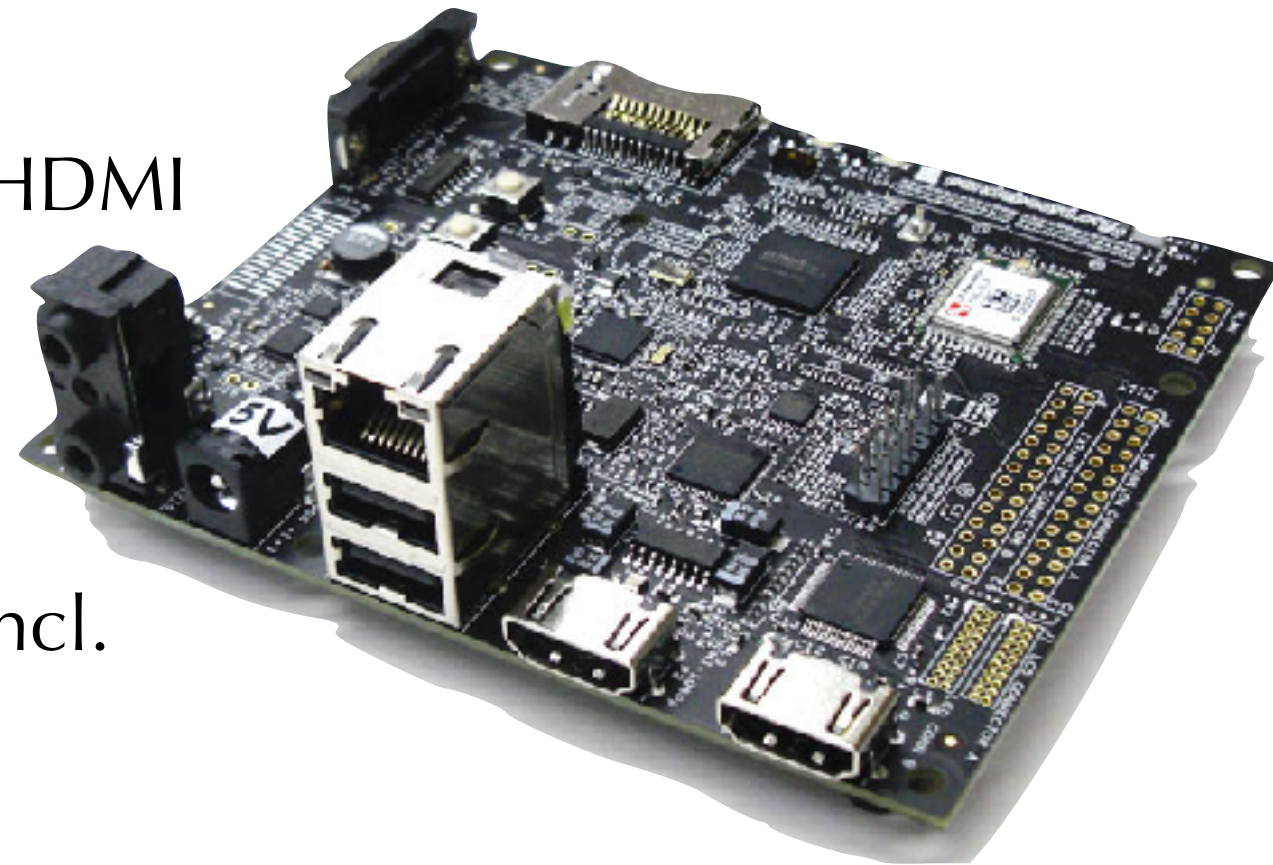


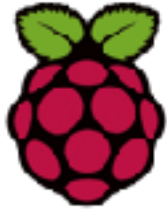


PandaBoard

<http://pandaboard.org>

- OMAP 4 or OMAP 5
 - Dual-core ARM Cortex A9 @1GHz or 1.2 GHz
 - 1GB RAM, Full HD video, 2 HDMI
- Network interfaces
 - Wi-Fi: 802.11b/g/n
 - Bluetooth BR/EDR and BT4 (incl. BLE)
 - Fast Ethernet
- SD card





Raspberry Pi

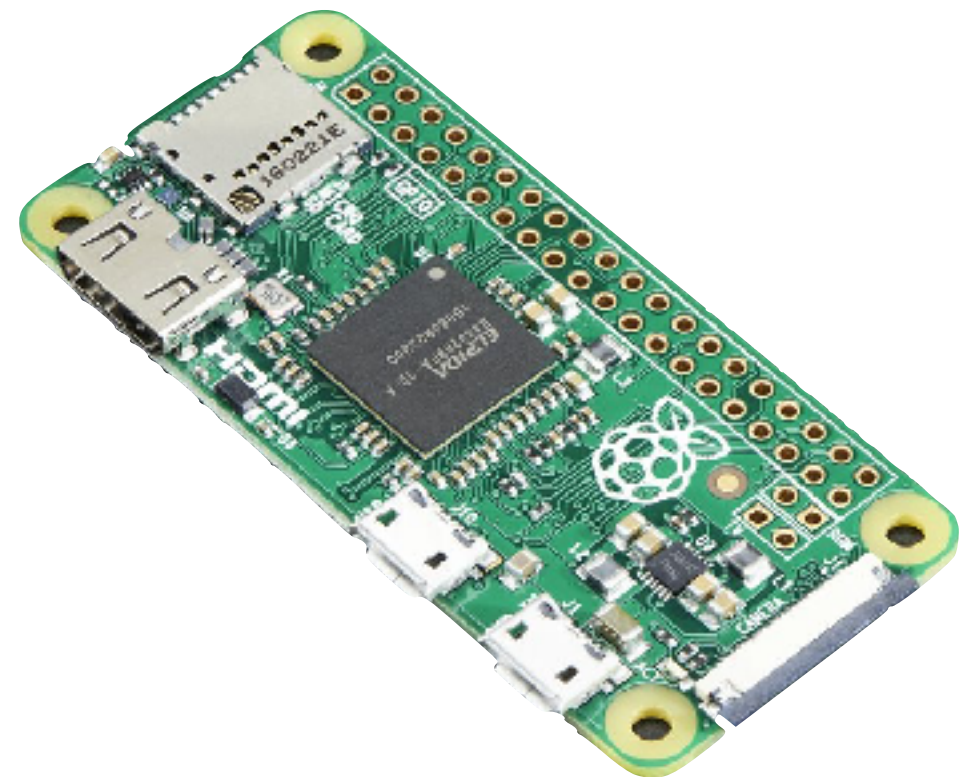
<http://www.raspberrypi.org>

- MCU: Broadcom BCM2835
- RAM
 - 256MB SDRAM (earlier),
512MB in Model B (2014)
- Ethernet, 2 USB
- HDMI out, audio jack
- 4GB eMMC flash



Raspberry Pi Zero

- Single-core 1 GHz processor chip
- Micro SD card slot
- Mini HDMI port
- Two micro USB ports (one for power, one for USB),
- 512MB of RAM
- $65 \times 31 \times 5 \text{ mm}^3$
- 9 grams

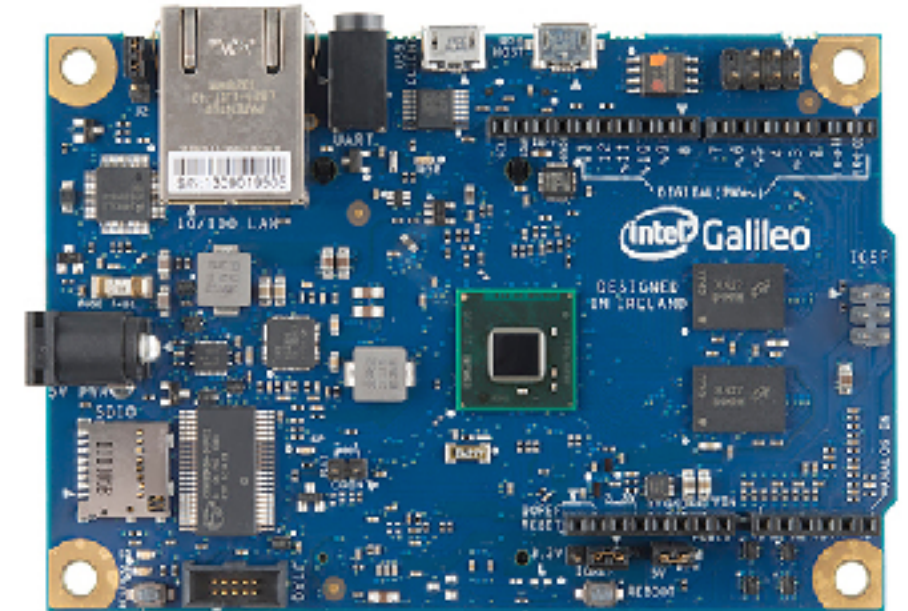


~\$5

Intel Galileo

<http://www.intel.com/content/www/us/en/do-it-yourself/galileo-maker-quark-board.html>

- Intel's response to Raspberry Pi
- Arduino Certified
 - Can use Arduino Shield 3
 - Supports Arduino SDK
- MCU: Quark X1000 SoC
 - essentially Pentium core, 400 MHz
 - 10/100 Ethernet, MicroSD, USB, RS-232
- 8MB NOR flash, 256 MB DDR3 RAM
- No HDMI...

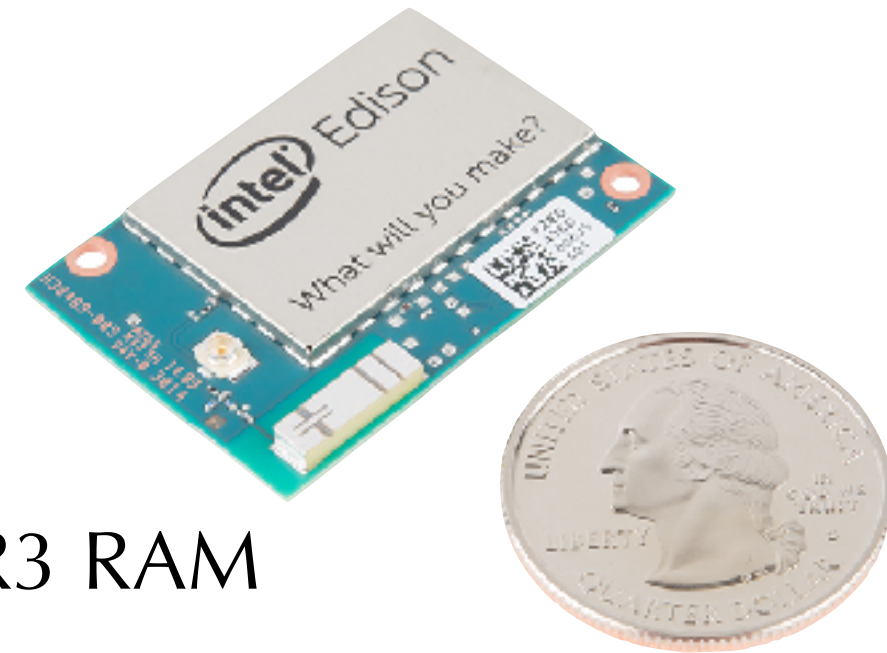


Intel Edison

<http://www.intel.com/content/www/us/en/do-it-yourself/edison.html>

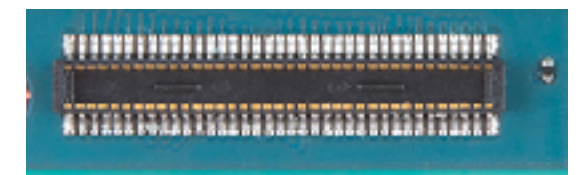
- Processors

- Quark MCU @100 MHz
- Dual-core ATOM CPU @500MHz
- 4 GB NAND flash (eMMC), 1GB DDR3 RAM



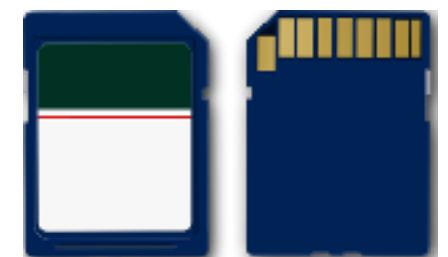
- Wi-Fi and BLE

- 70-pin wired connector on back



- Dimensions

- $35.5 \times 25.0 \times 3.9 \text{ mm}^3$ — just slightly larger than SD card @ 32×24



TI Sensor Tag

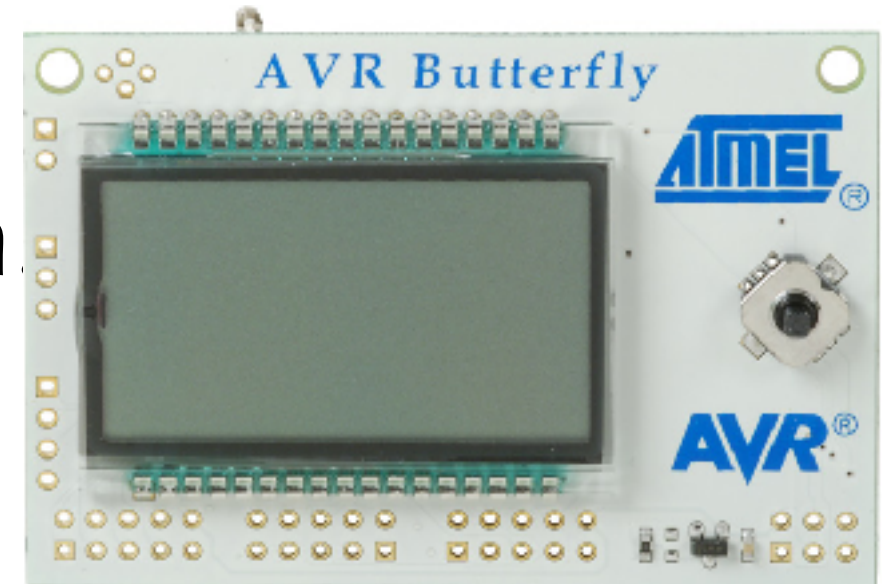
<http://www.ti.com/sensortag>

- Based on CC2541
- Rich sensors
 - temperature, humidity, pressure
 - acceleration, gyro, magnetometer
- Powered by CR2032 coin cell
- Over-the-air download (OAD)
 - can download iBeacon profile
- Programmable or ready-to-use firmware
- Limited expandability



AVR Butterfly

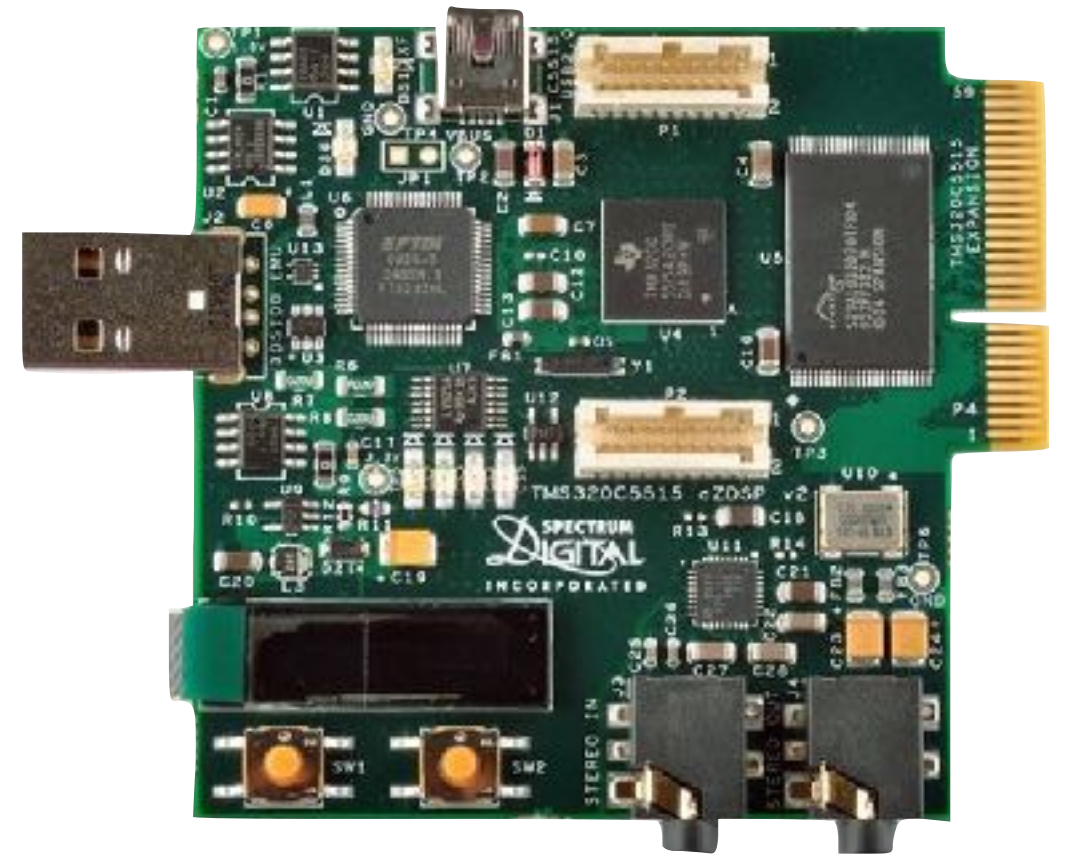
- \$20, MCU with LCD, temp/light sensor, tone gen joystick, prototyping area
- 512K flash over SPI
- Comes w/ a *bootloader* over serial port
- ATMega 169 MCU:
 - UART, SPI, USI, PWM, 8ch/10-bit ADC, Timer/counter, built-in LCD driver, GPIO



Evaluation Options for TI C5515 fixed-point DSP



\$395



\$79

Can't find what you need?

- Build your own board!
 - but this may be the more expensive option
- Start with evaluation kit if possible
 - Chip on a board with connectors and prototyping area
 - Connect boards to test out functionality
- Expect to iterate a few times to work out all issues