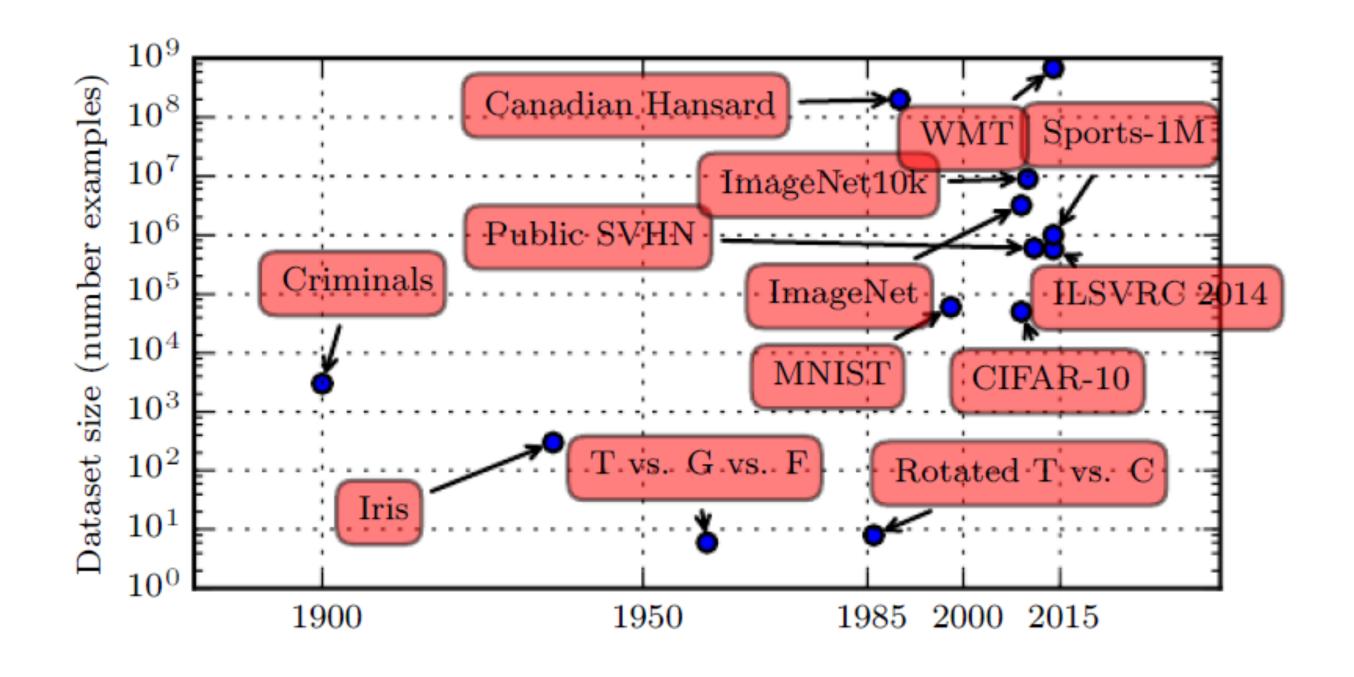
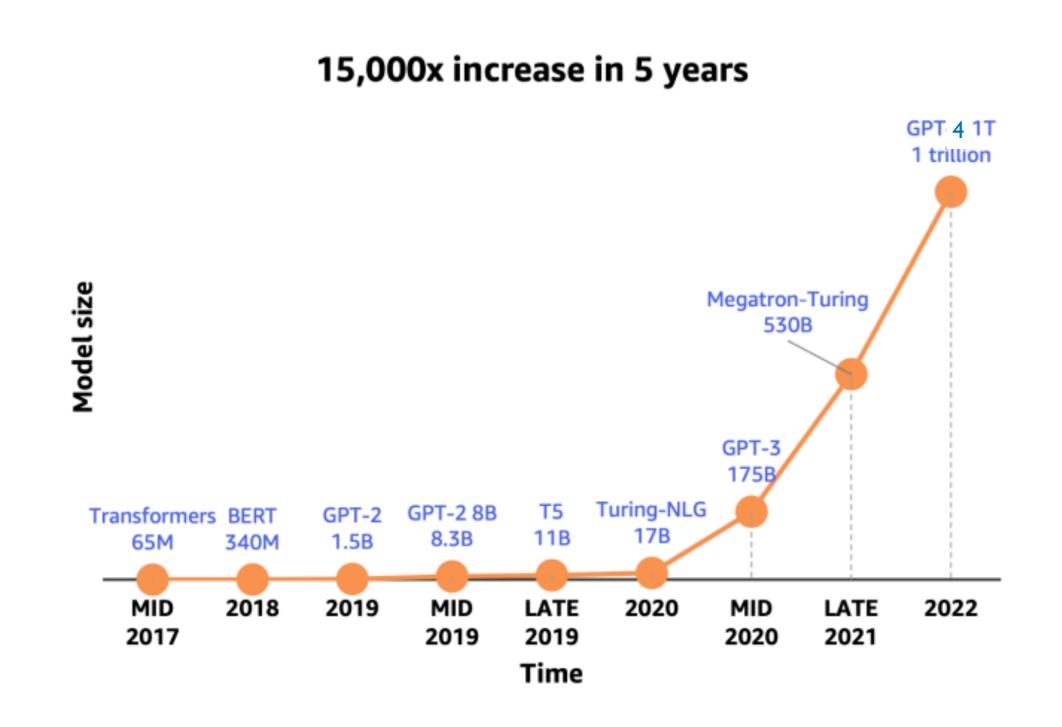
# Lecture 13: Networking and Deep Learning

CS 234 / NetSys 210:Advanced Computer Networks
Sangeetha Abdu Jyothi



#### Rapid Growth



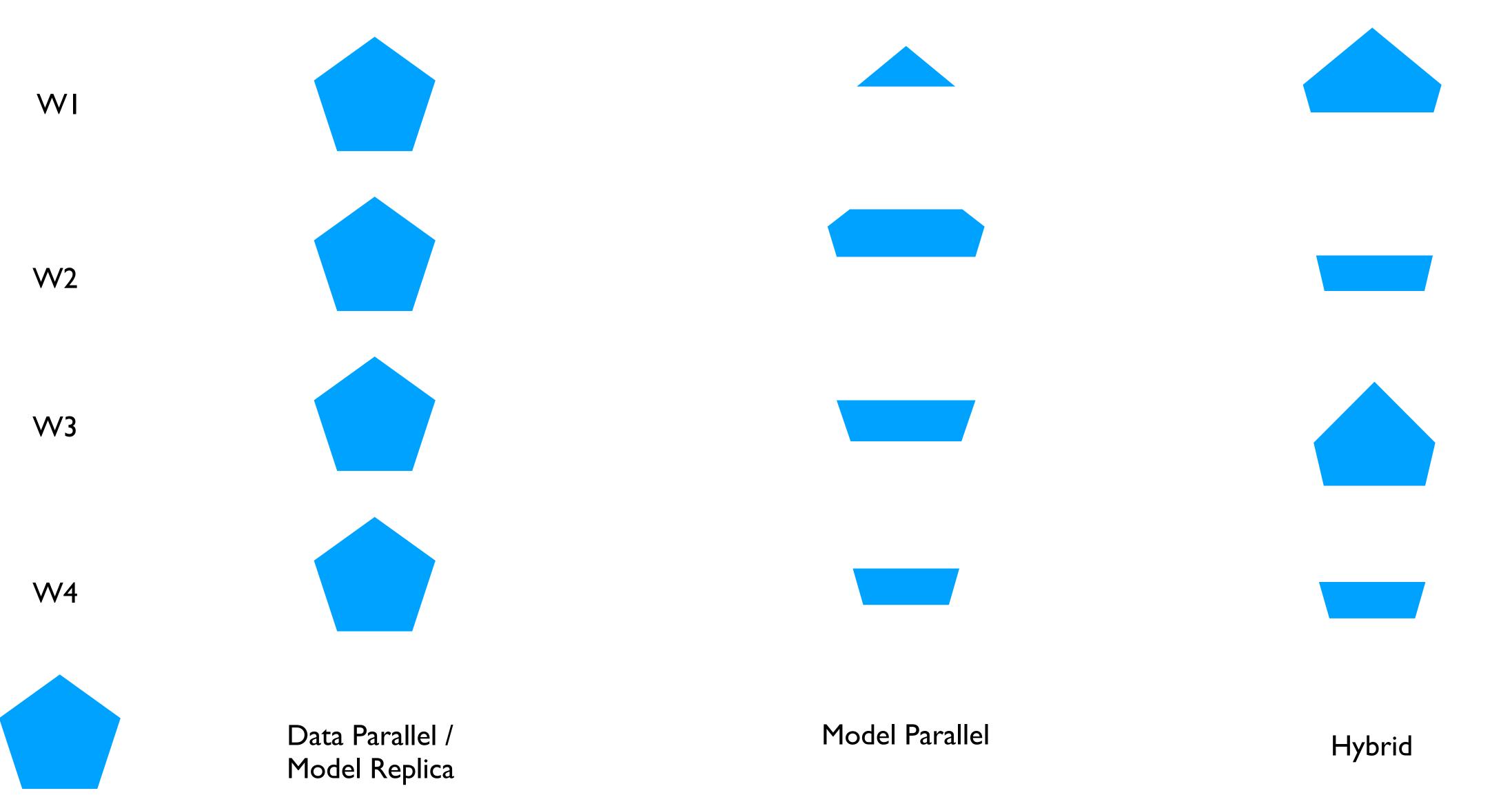


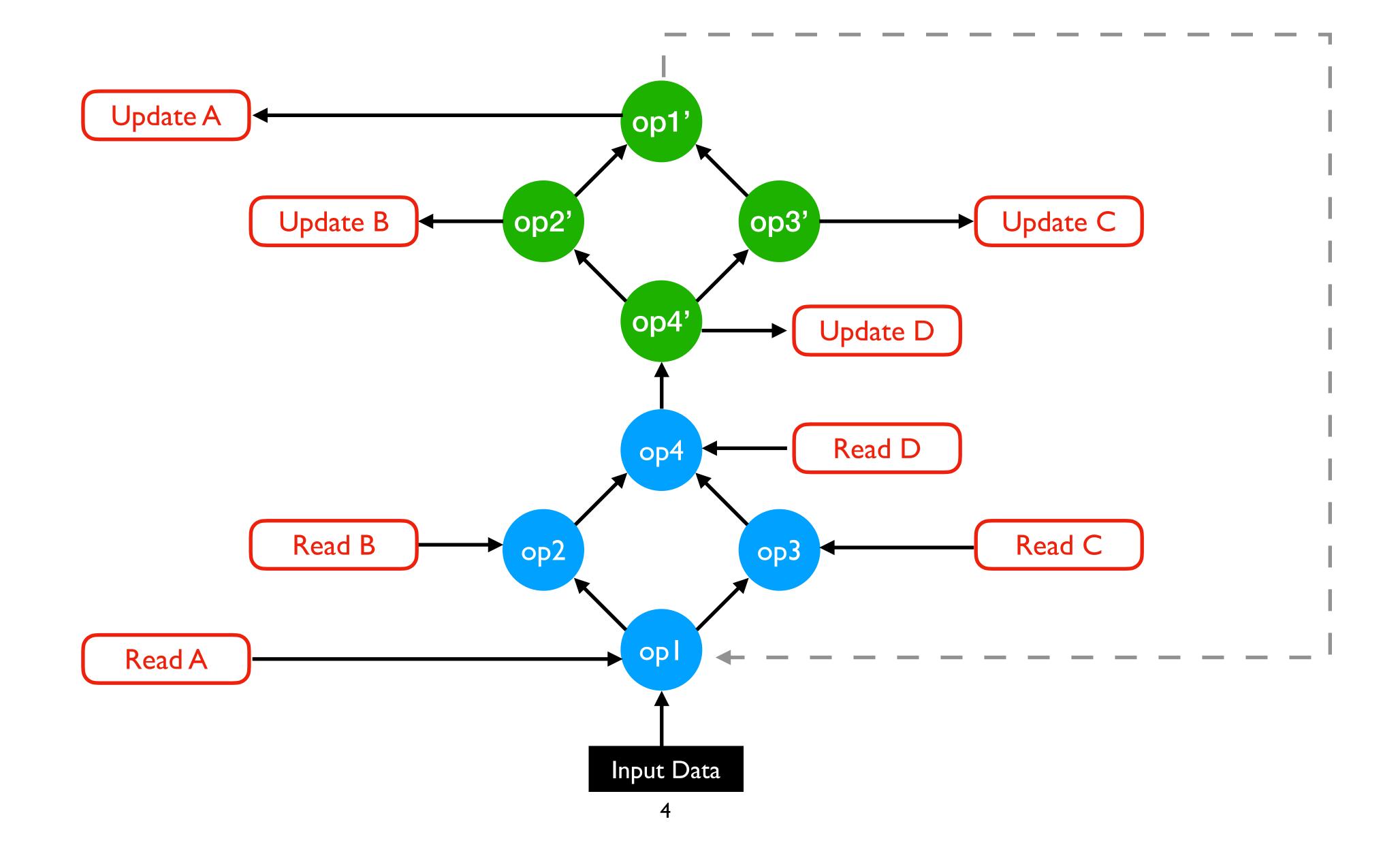
Datasets and Models are rapidly growing in size



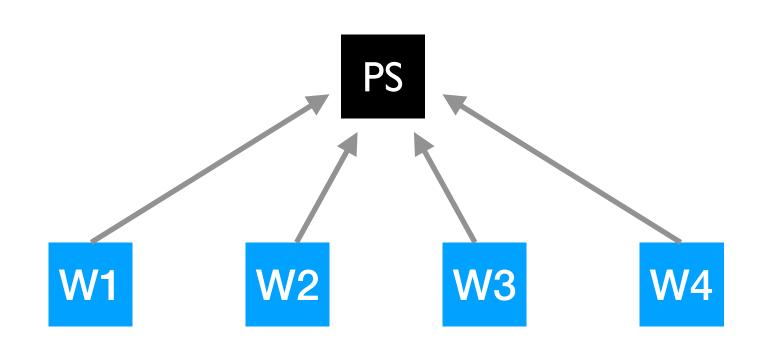
Distributed training is necessary

#### Distribution Patterns

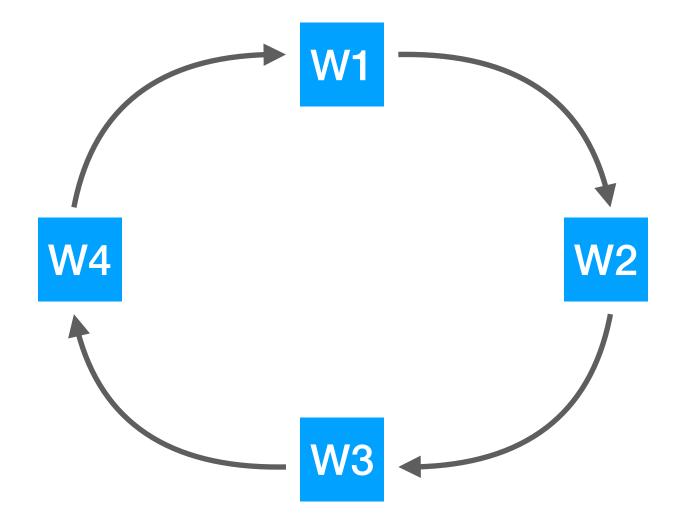




## Popular Modes of Network Aggregation



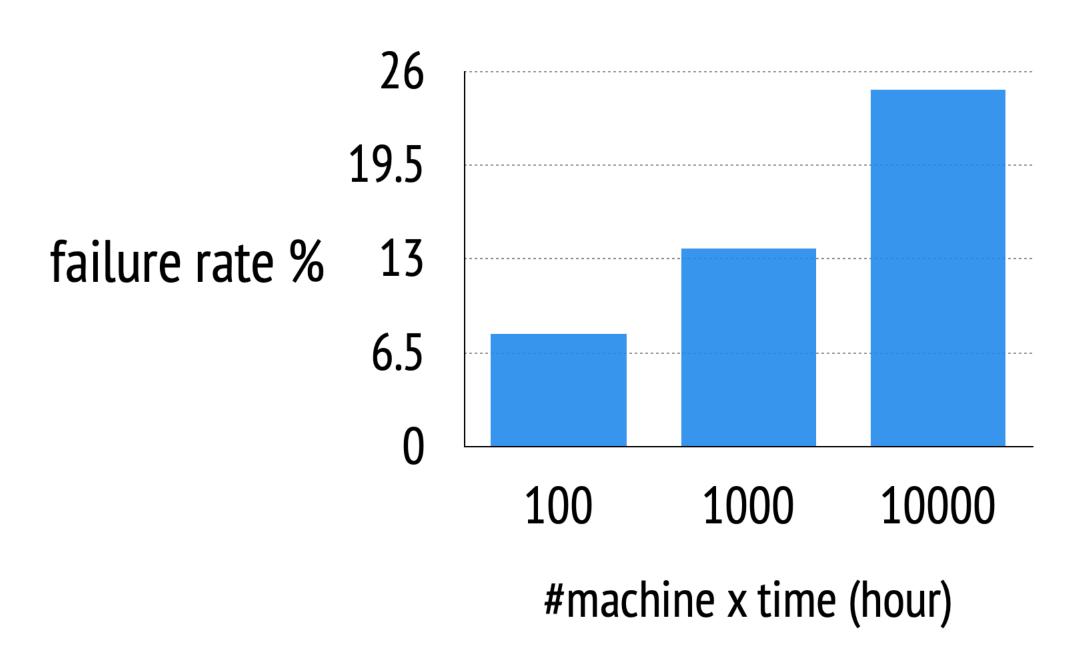
Parameter Server



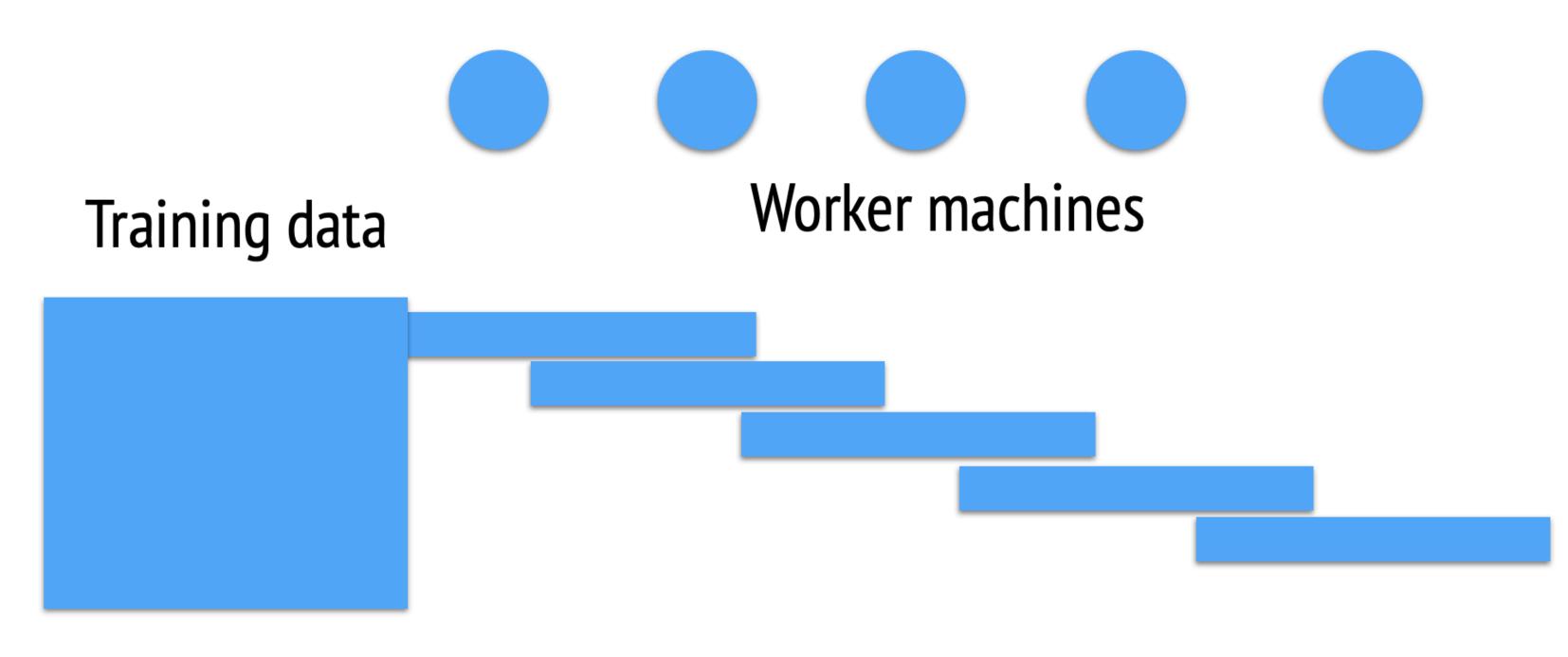
Decentralized Aggregation

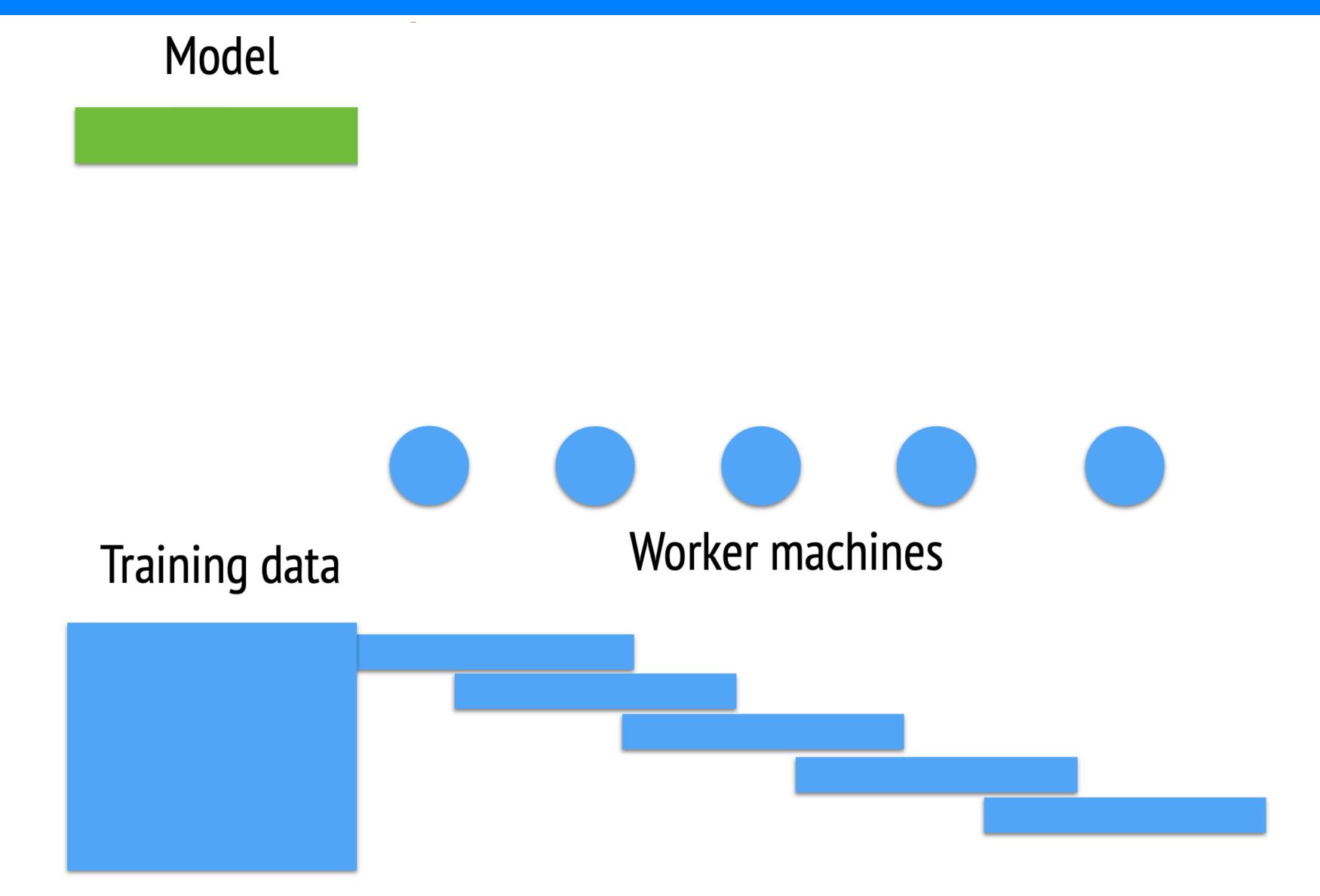
## Parameter Server [OSDI'14]

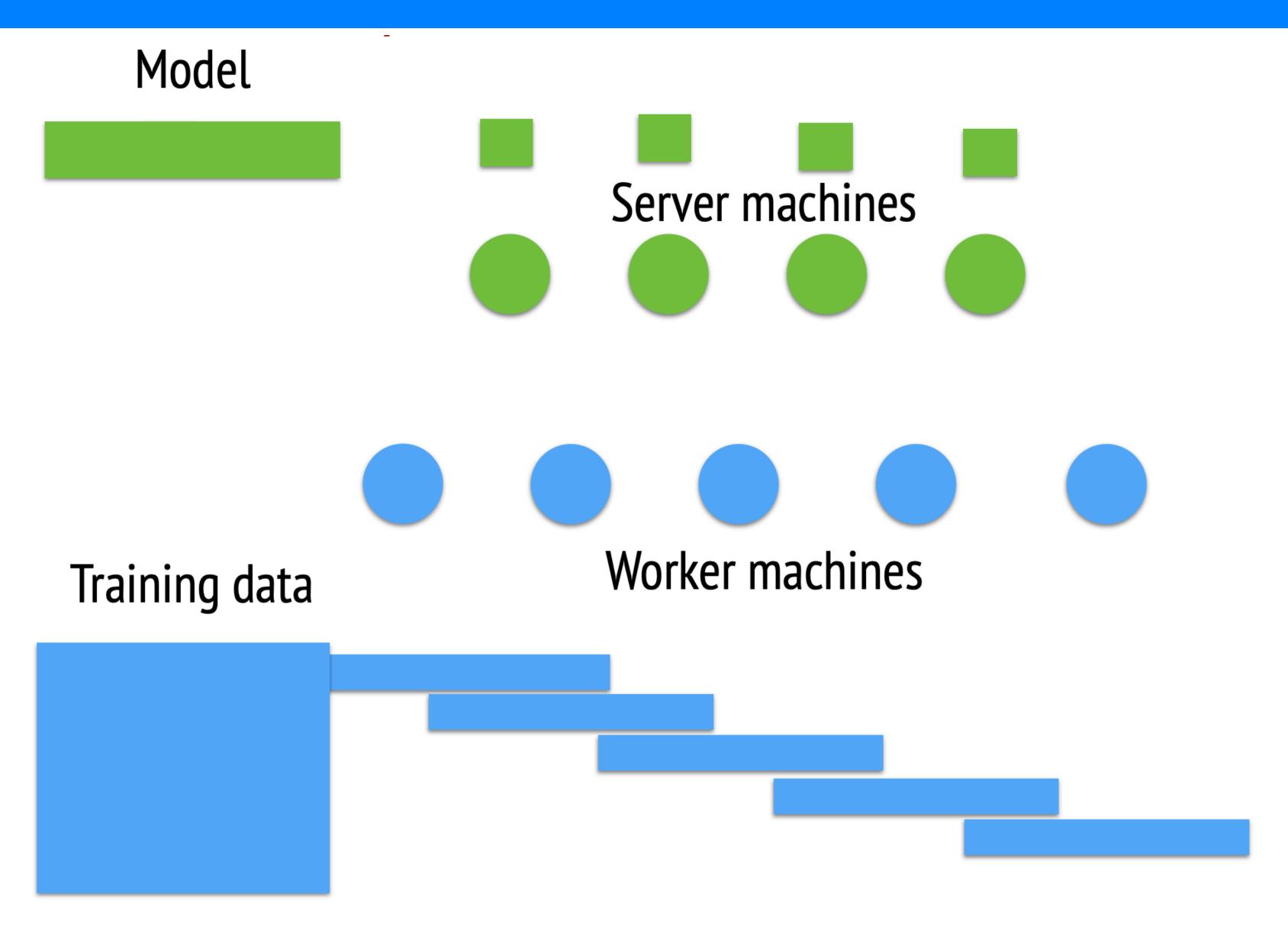
- Goals
  - Scale to industry-scale problems
    - billions of samples and features
    - hundreds of machines
  - Enable efficient communication
  - Fault tolerance
  - Easy to use



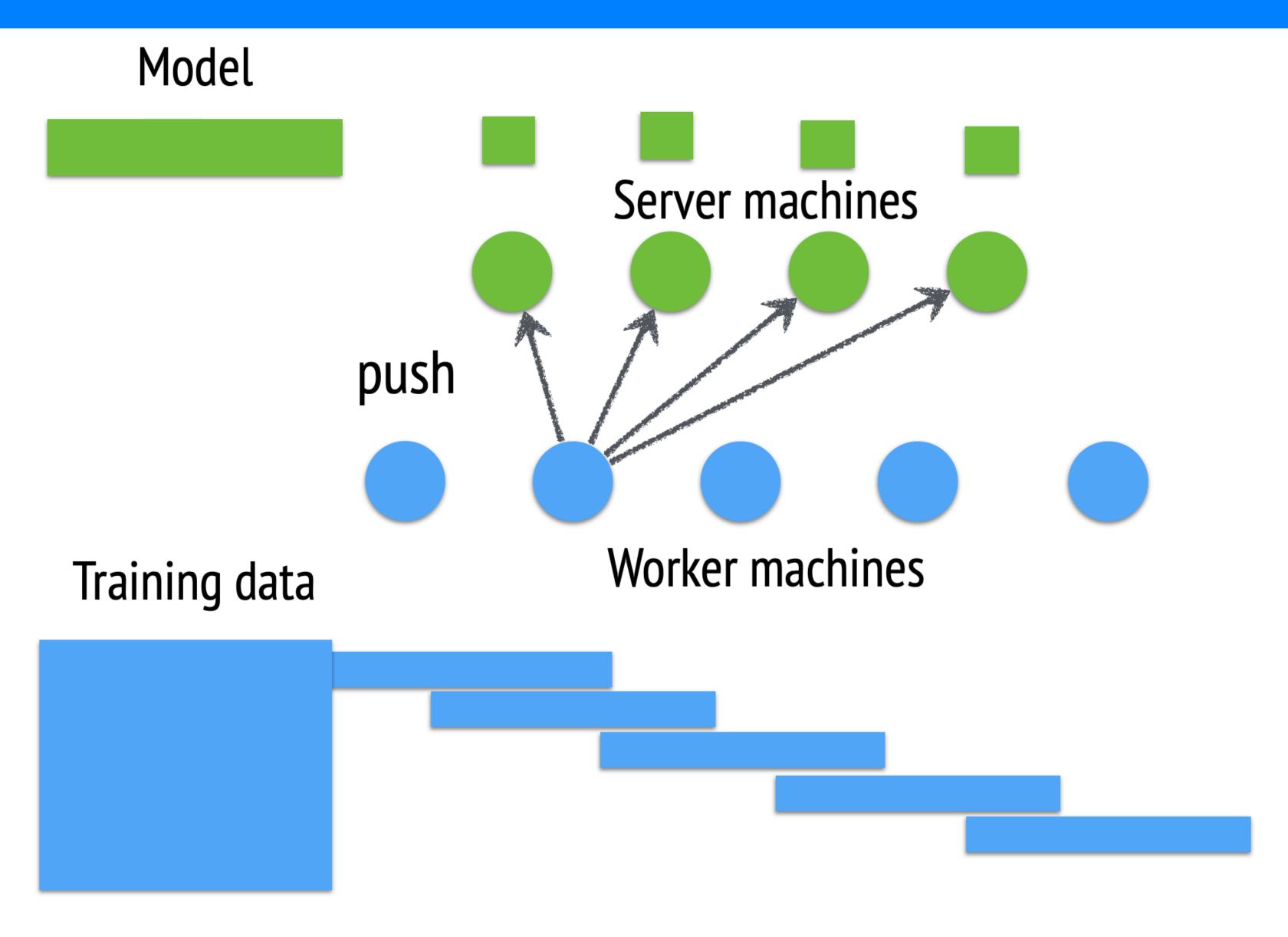
Training data



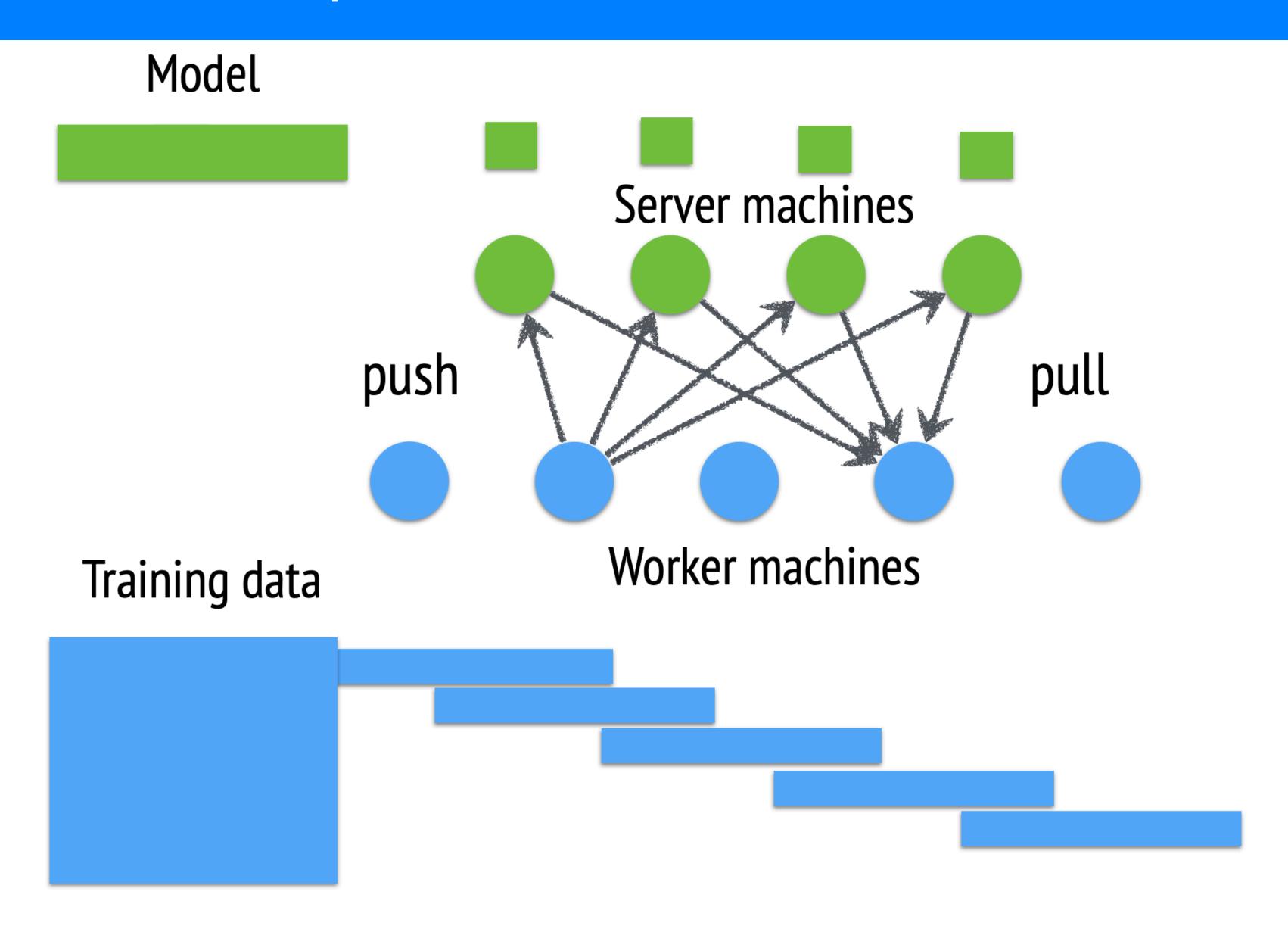




## Communication Operations



## Communication Operations

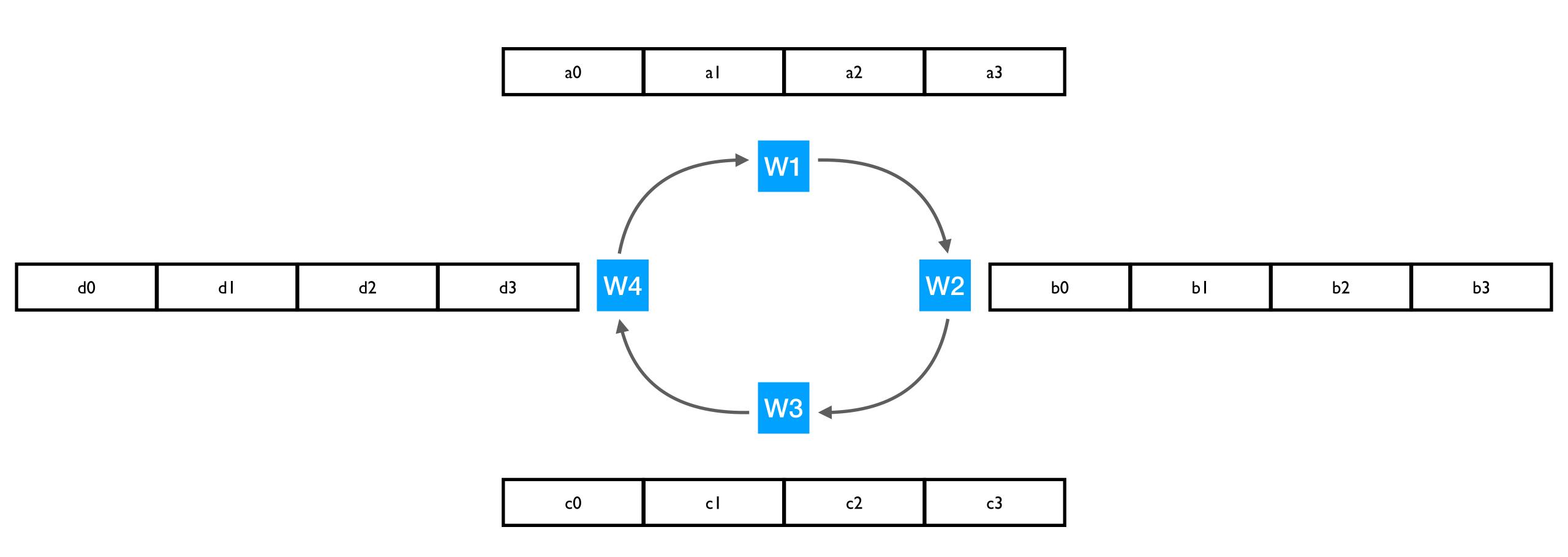


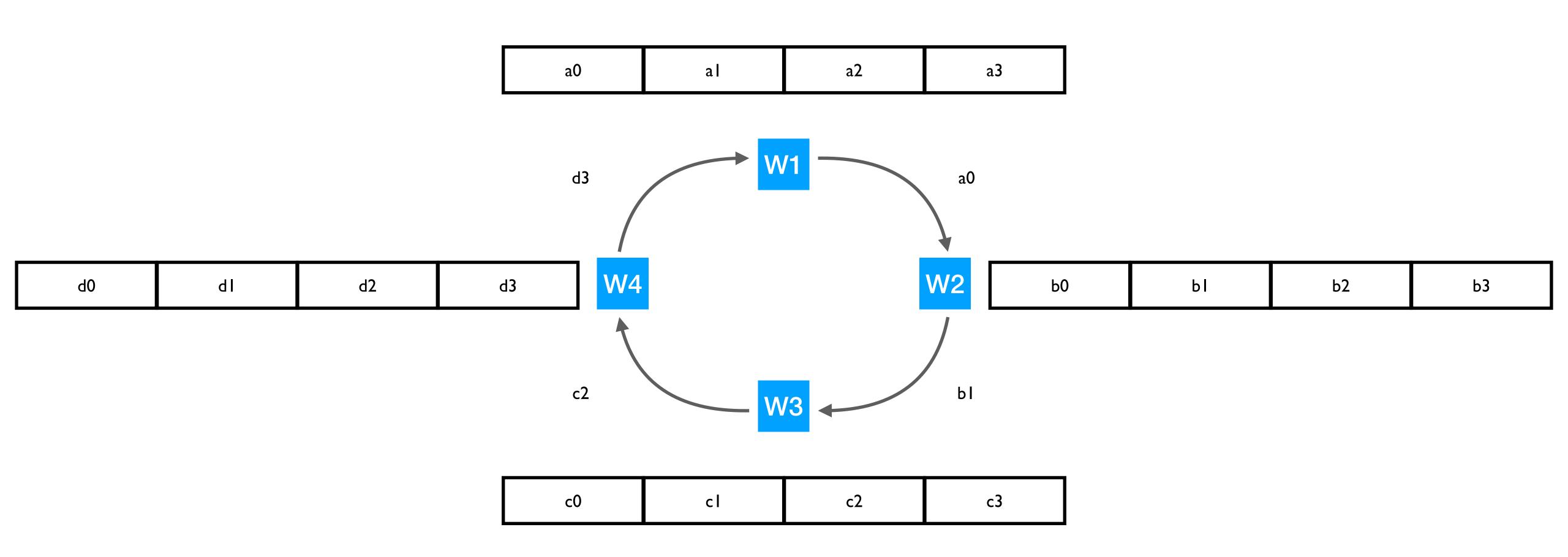
#### Issue with Parameter Server

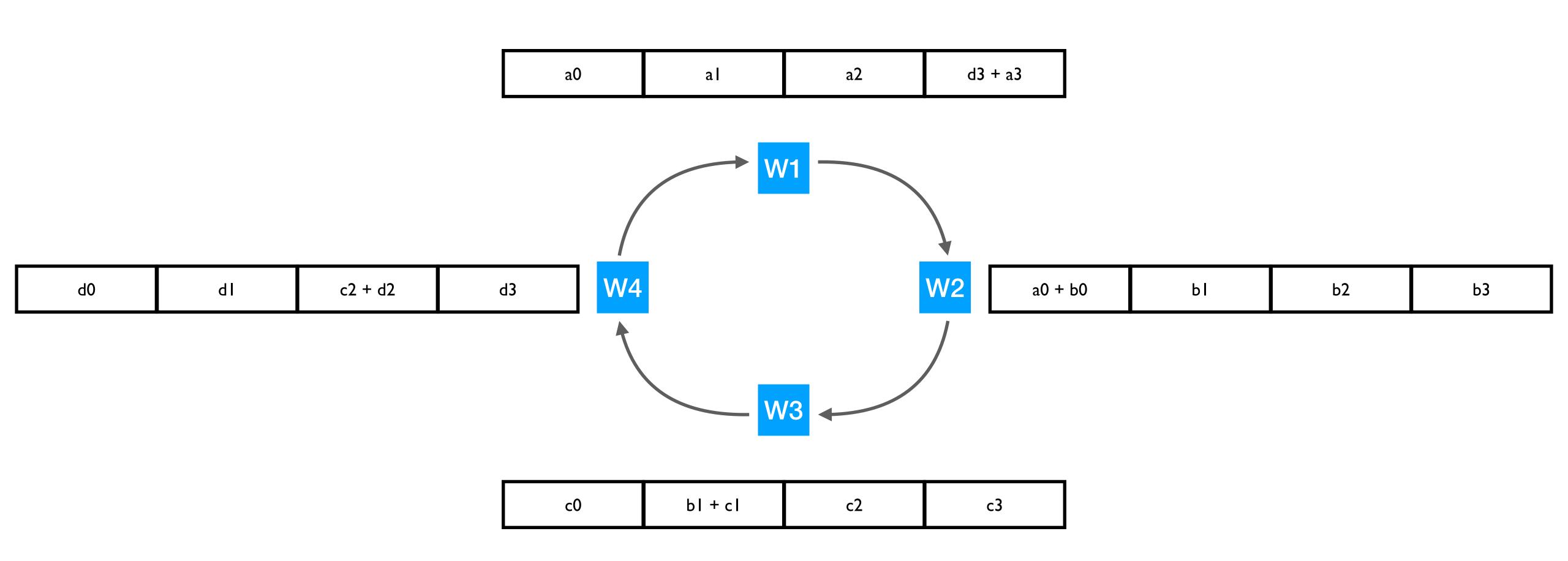
Even with distributed PS architecture, there can be network congestion at the parameter servers

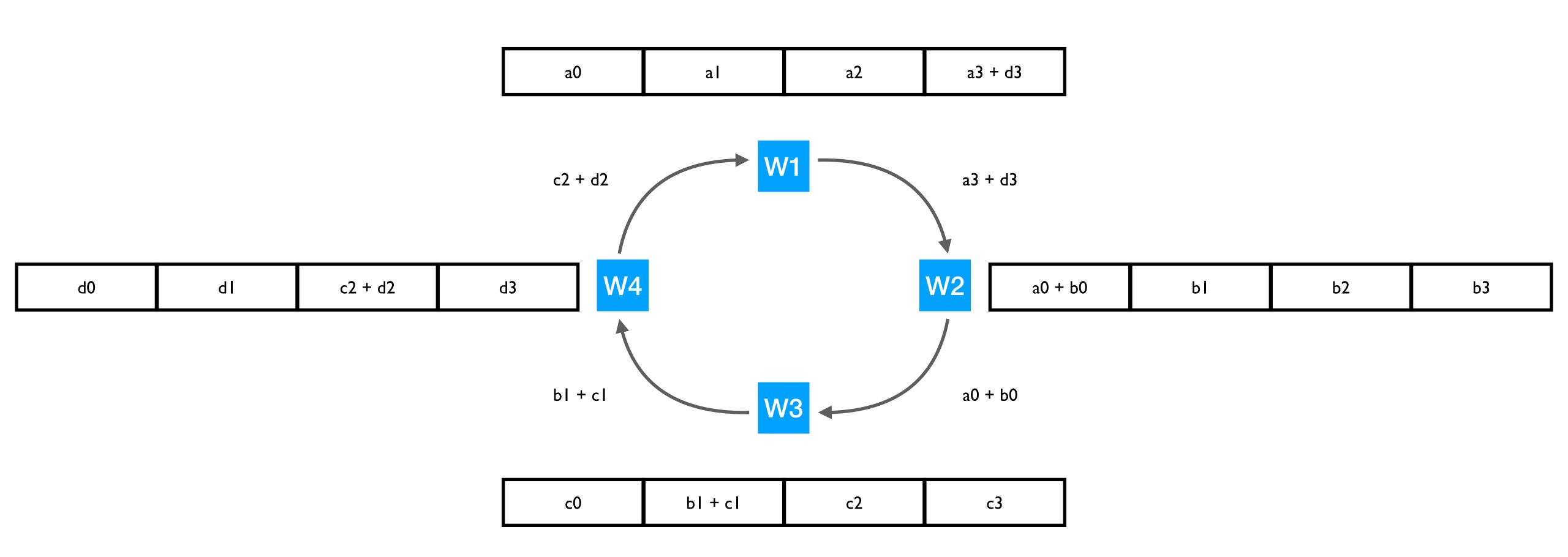
Solution: Decentralized Aggregation

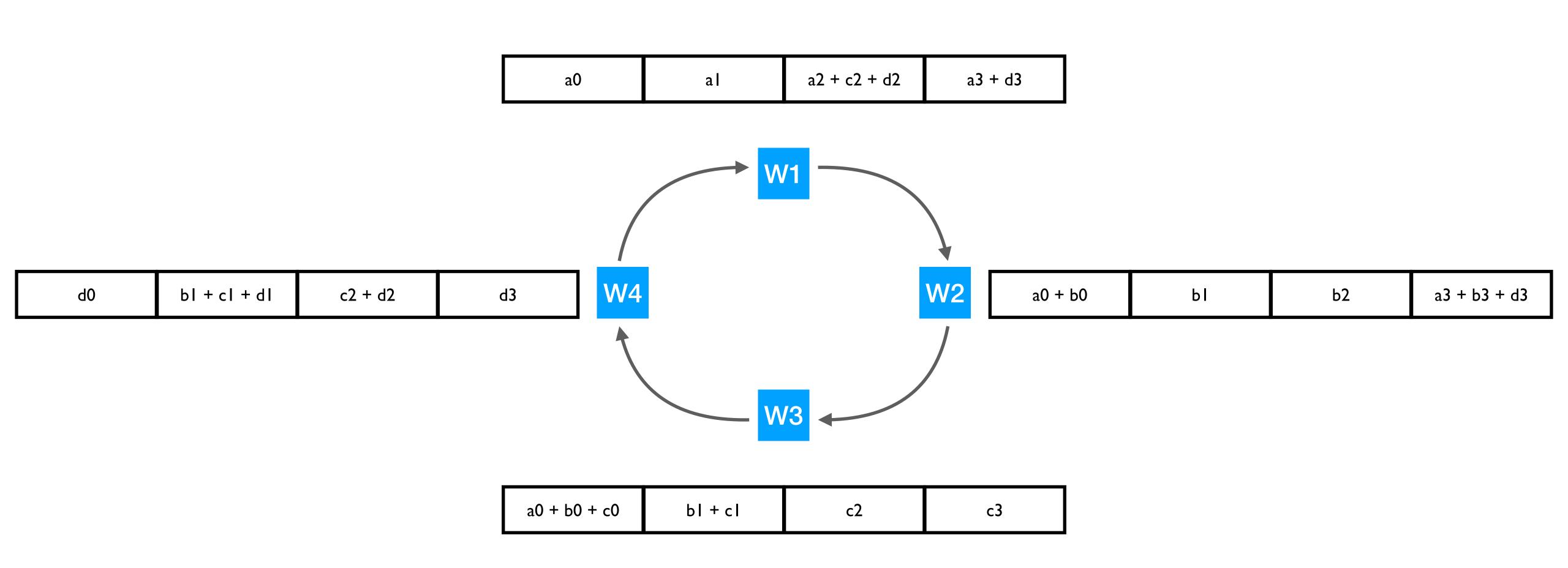
# Ring AllReduce - Decentralized Aggregation

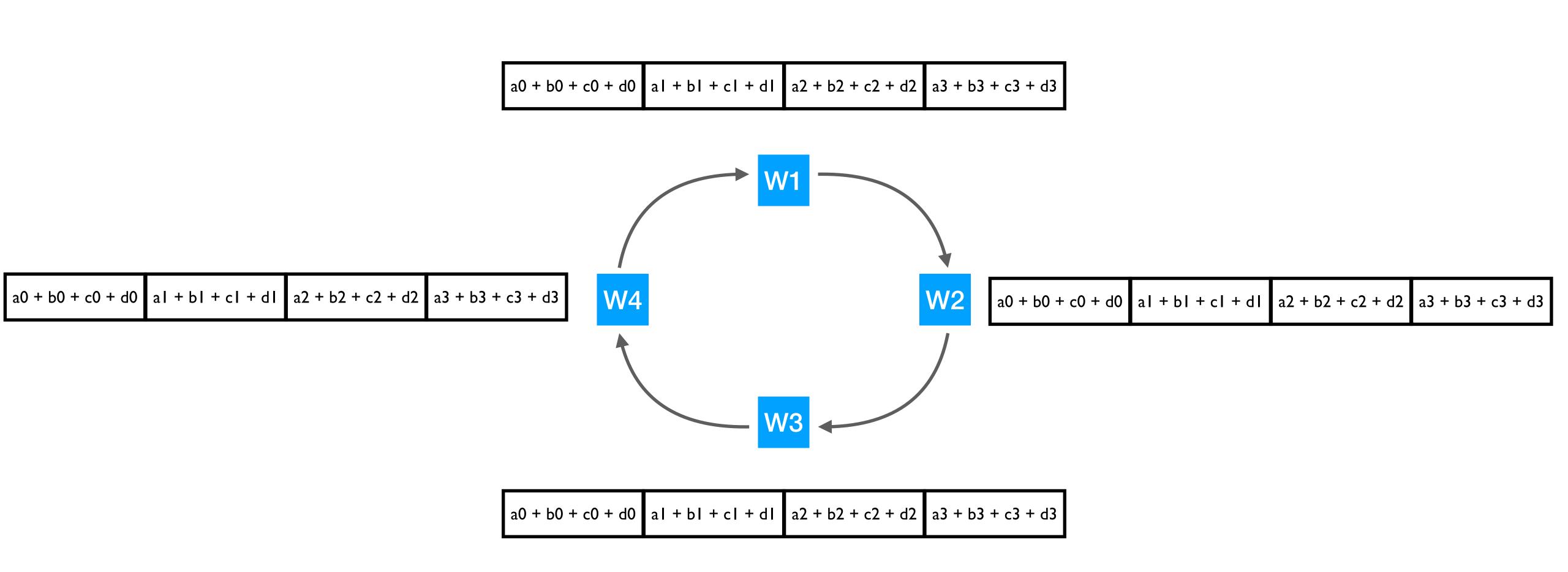




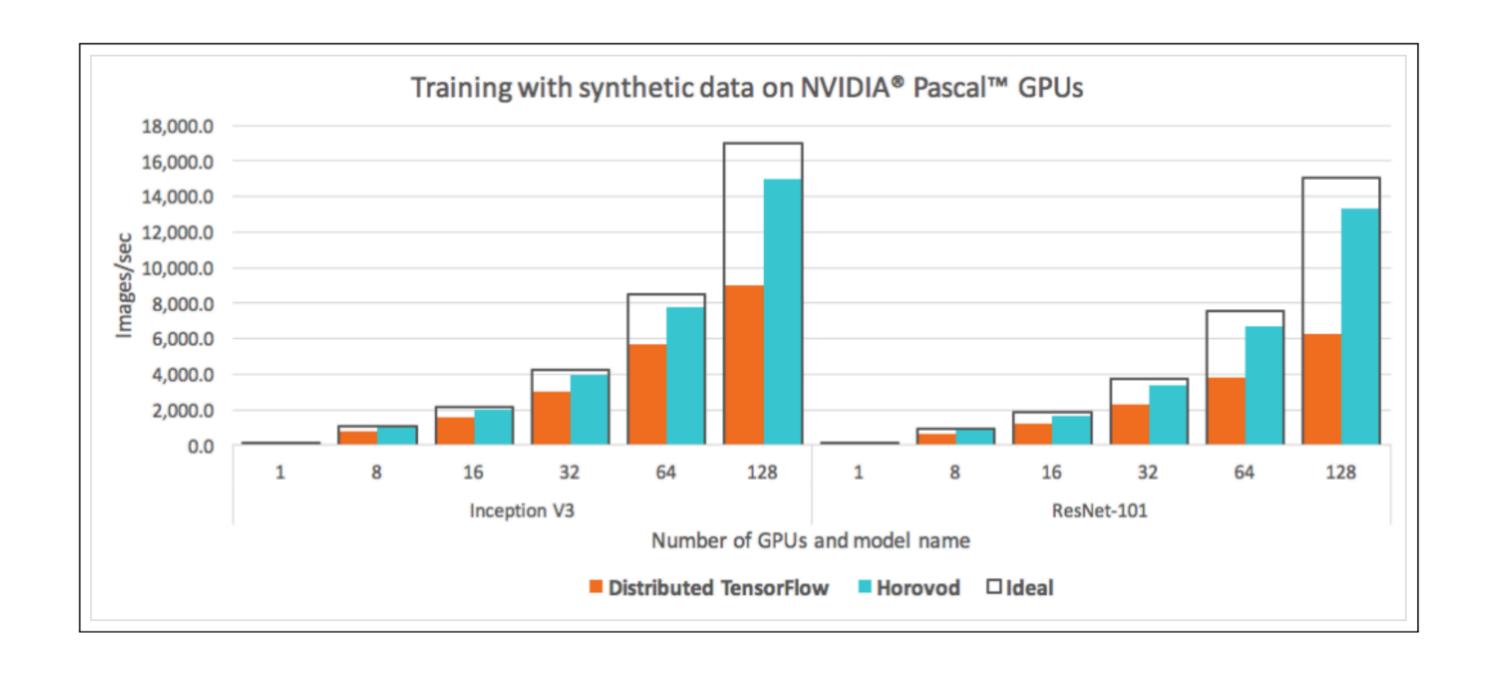




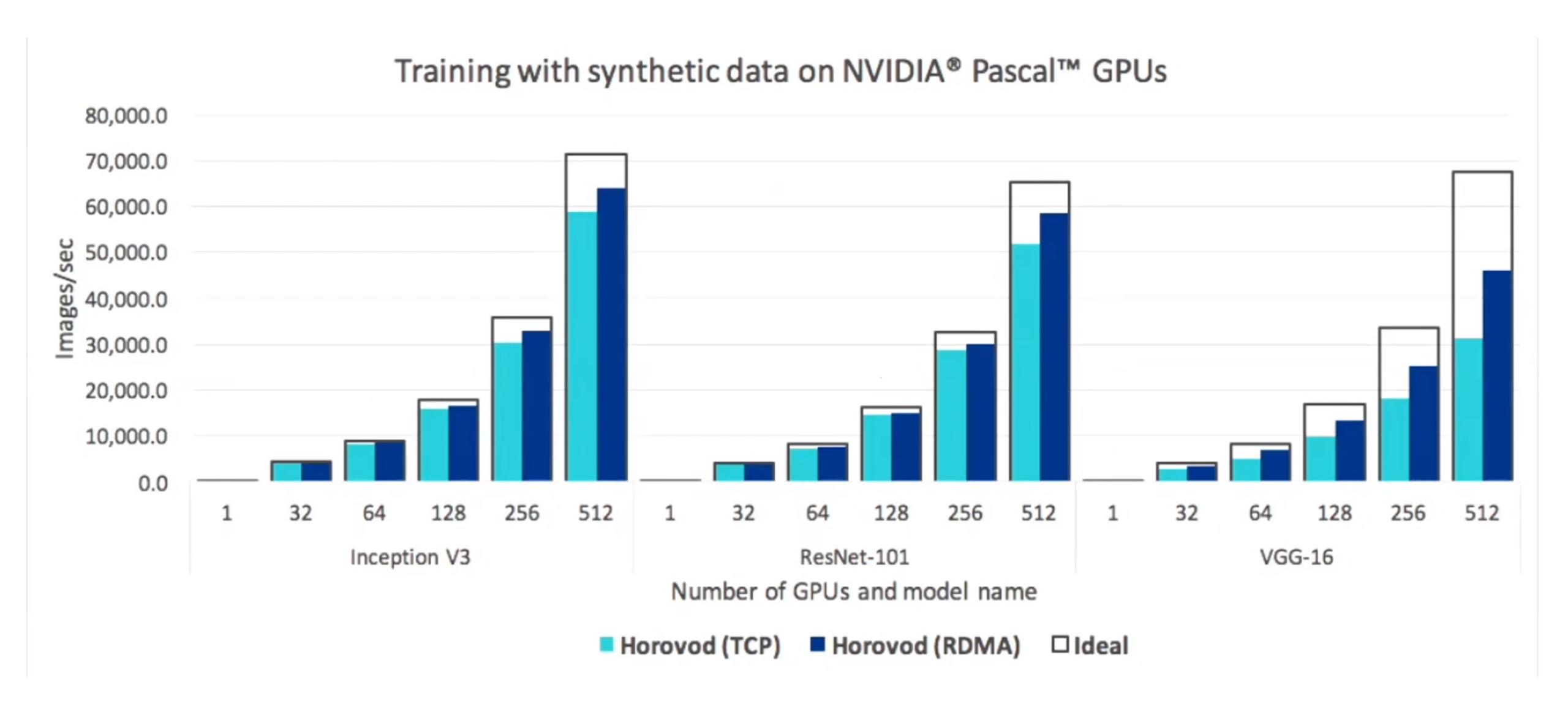




#### Performance



#### Performance



## AllReduce advantages

• Better performance

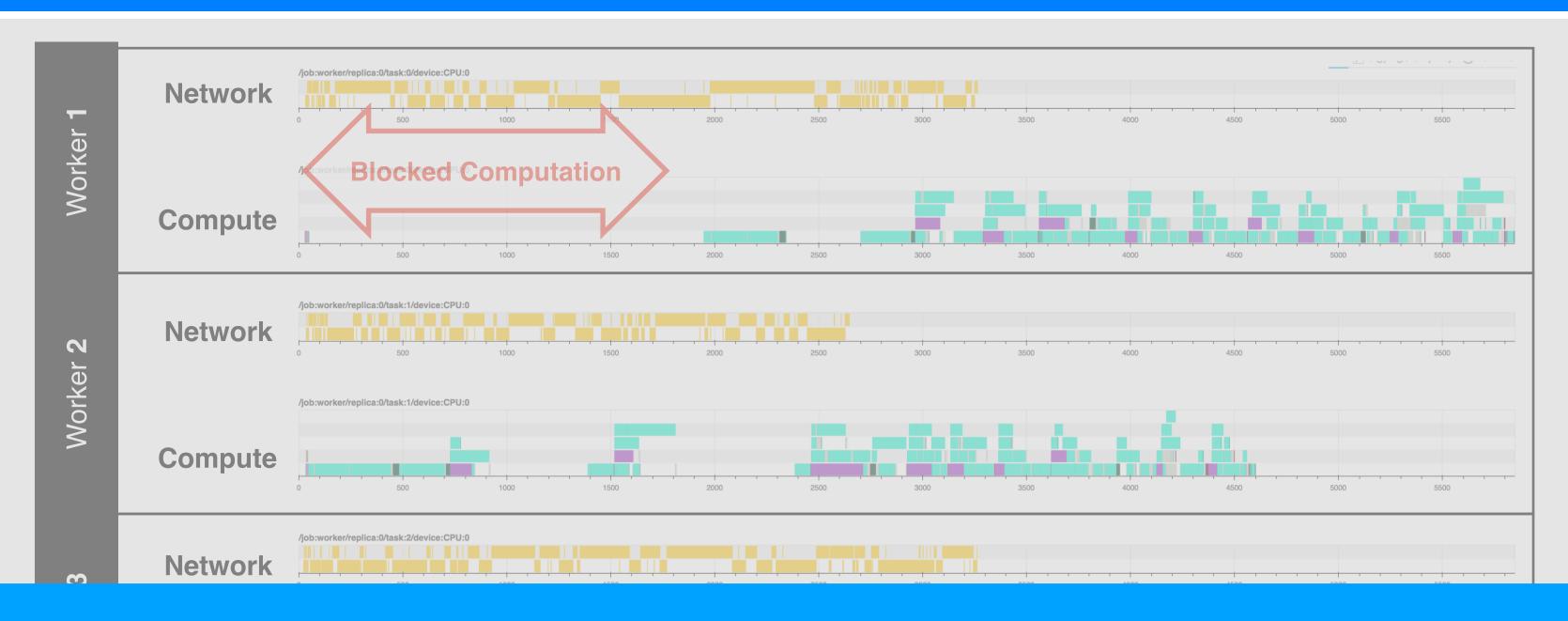
More scalable

• Fits well with Torus topology

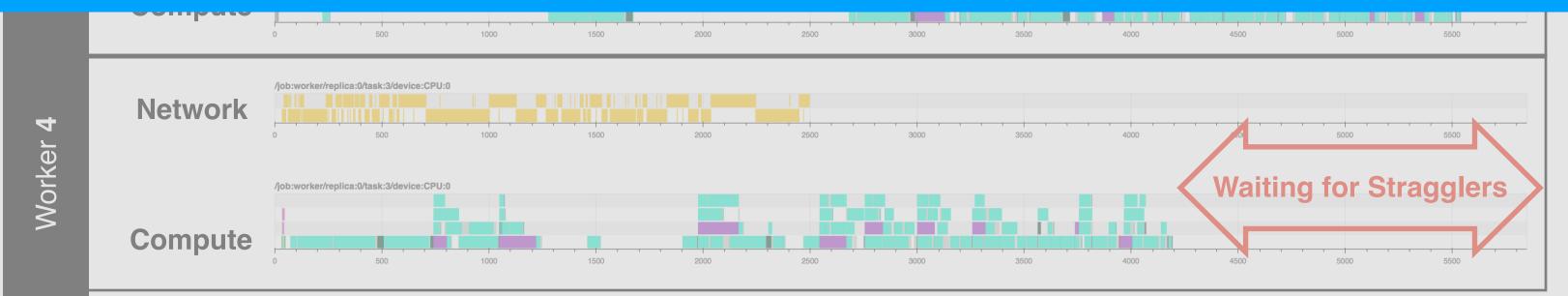
#### An issue with both PS and AllReduce

# Compute under-utilization

#### Understanding Compute Underutilization



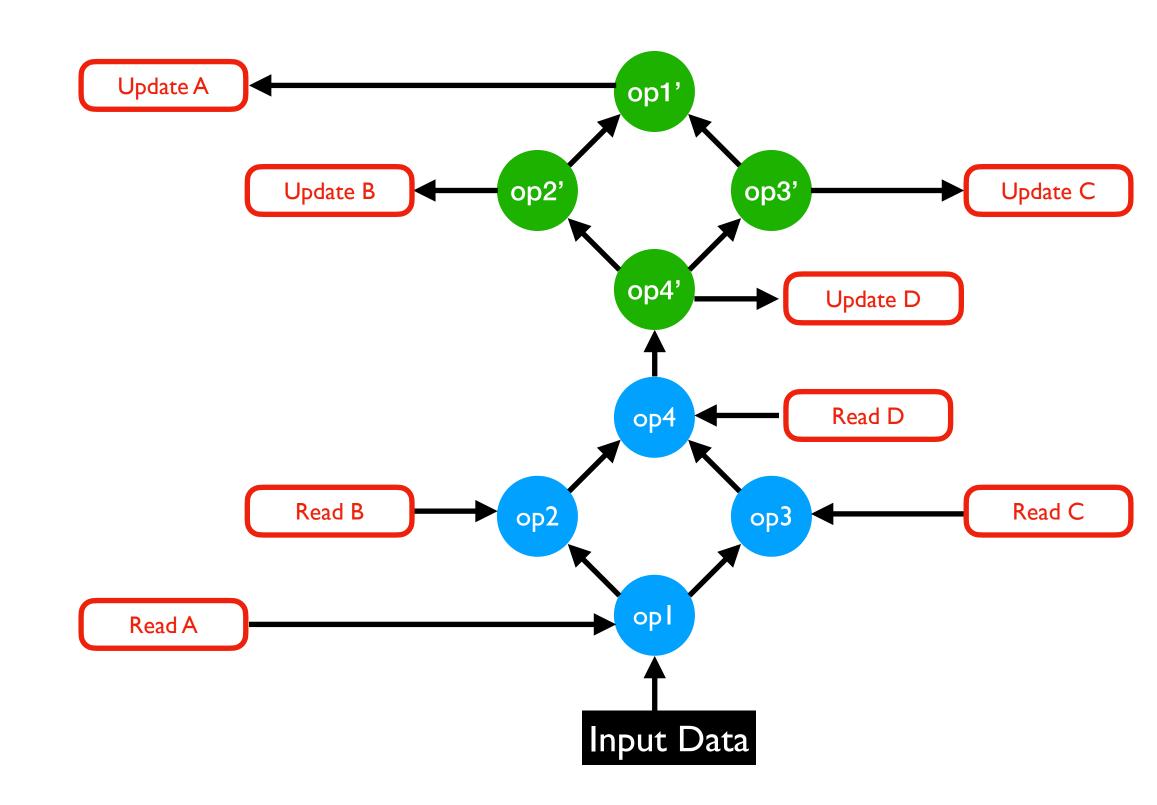
#### Training can be accelerated through better communication-computation overlap



Inception v3
Data-Parallel with Parameter Server
TensorFlow
Mustang: CPU

#### Cause: Random Order of Parameter Transfers

- In this example, the computation cannot start until parameter A is received
- B, C, or D may be transferred before A, thereby blocking the computation
- To make things worse, parameters that are updated last are consumed first



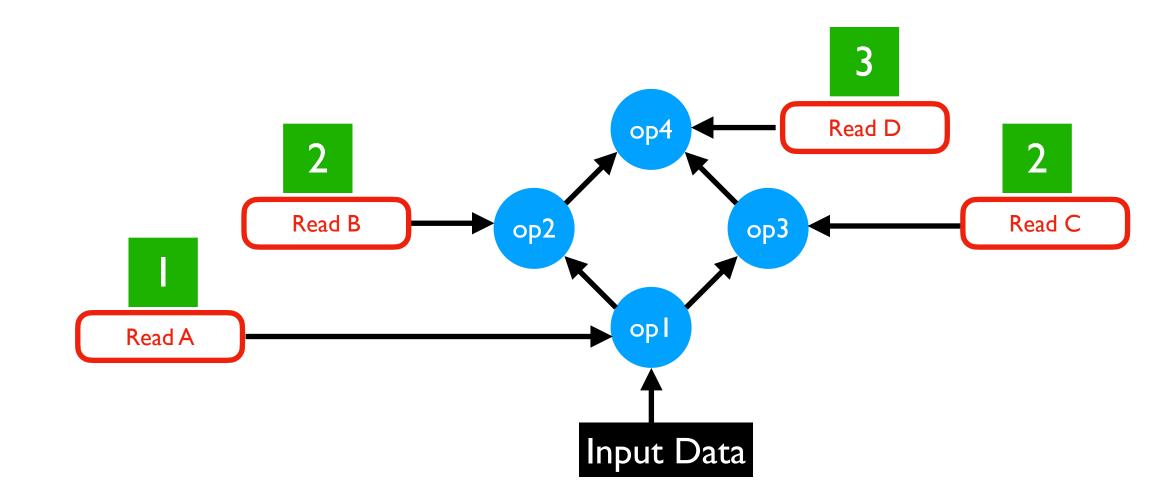
#### TicTac and P3 [MLSys'19] High-level idea

• Improve iteration time through better communication-computation overlap in Parameter Server based aggregation

Achieved through parameter transfer scheduling

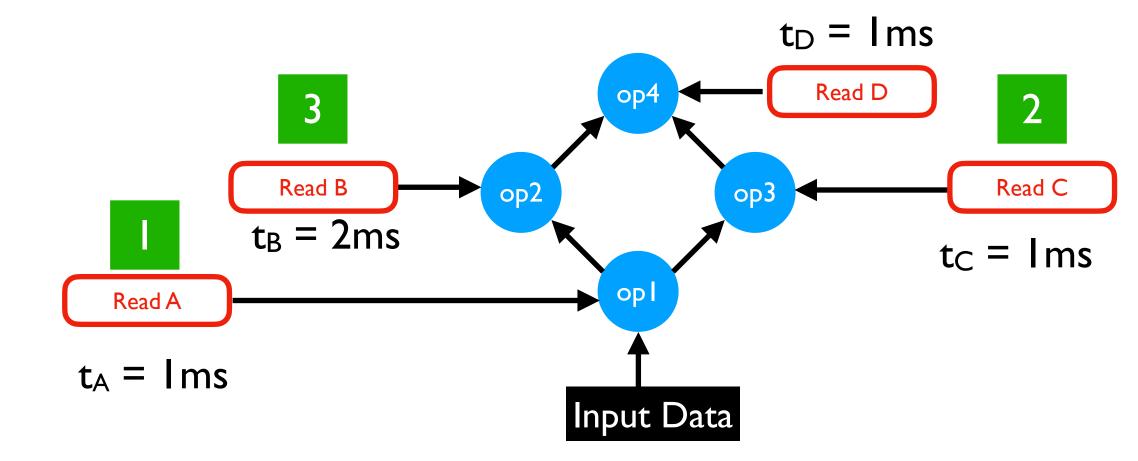
#### Timing Independent Computation Scheduling

- Uses DAG structure only
- Assign priorities based on the number of communication operations dependent on a given transfer
- In the e.g, A has no other transfers dependent on it. Hence, it gets the highest priority
- B and C each have one dependency.
   Hence, the next priority
- D assigned lowest priority



## Timing Aware Computation Scheduling

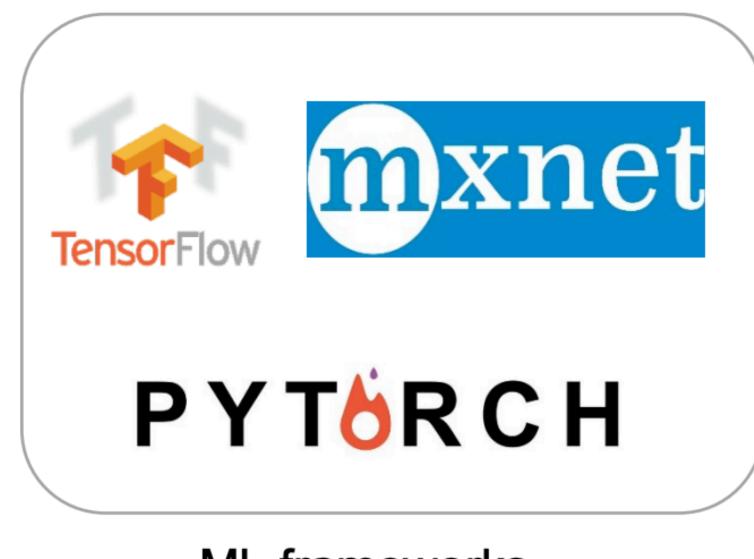
- Uses DAG structure and time taken by each operation
- Reduce blocking on the critical path
- A assigned highest priority
- C is the next smallest blocking transfer
- Followed by B, then D



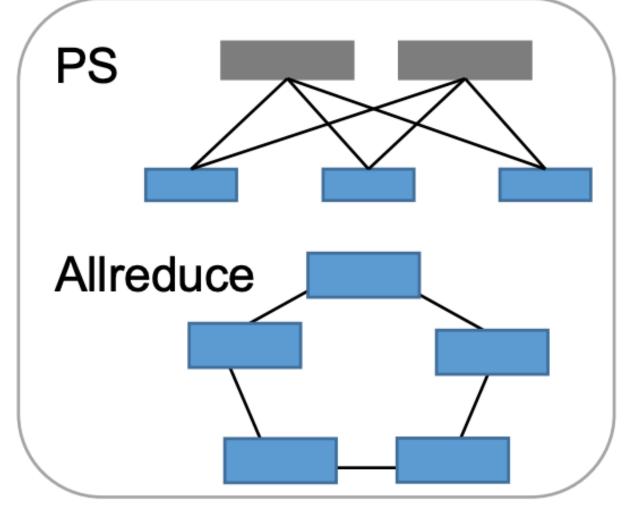
#### Limitations of Past Work

 Coupled with specific framework implementations, e.g., P3 for MXNet PS and TicTac for TensorFlow PS

#### Many different setups in distributed DNN training:







Communication architectures



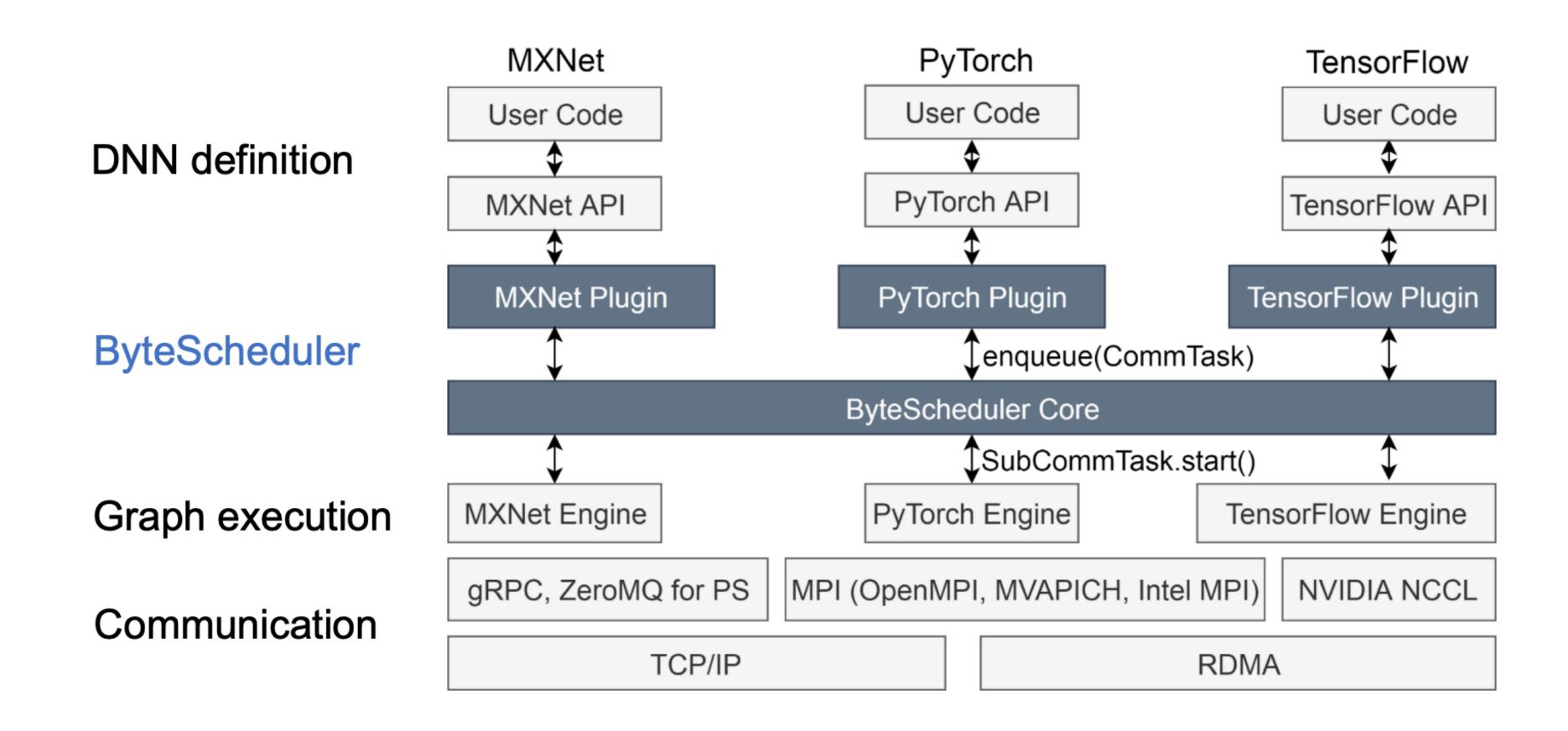
Network protocols

## ByteScheduler [SOSP'19]

• Observation: The dependency graph structure is intrinsic for DNN training (regardless of training frameworks, communication architectures, or network protocols)

• ByteScheduler: A generic tensor scheduling framework for deep learning DAGs

#### Unified Scheduler Across Frameworks



Plugin: Wrap each communication operation as a CommTask

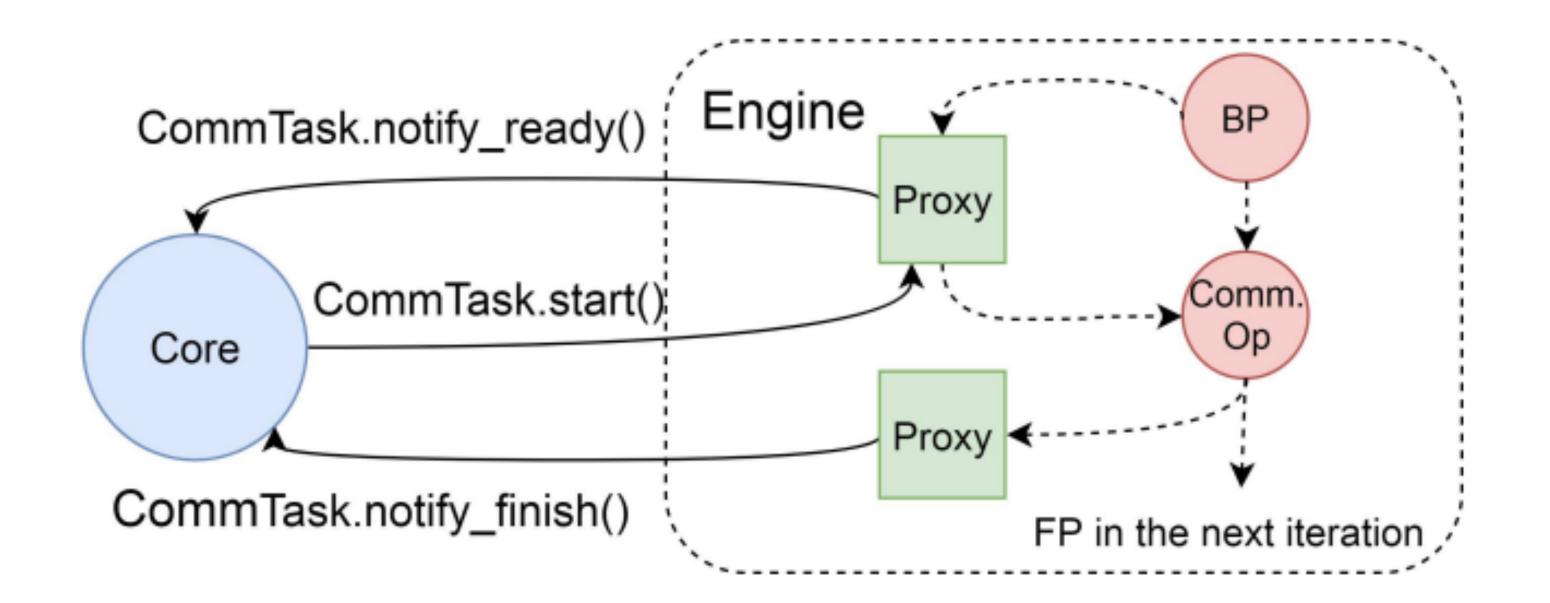
Core: Partition and schedule CommTasks

#### CommTask: A Unified Abstraction

- CommTask: A wrapped communication operation, e.g., push one tensor, all reduce one tensor
- CommTask APIs implemented in framework plugins:
  - partition(size): partition a CommTask into SubCommTasks with tensors no larger than a threshold size
  - notify\_ready(): notify Core about the readiness of a CommTask
  - start(): start a CommTask by calling the underlying push/pull/all-reduce
  - notify\_finish(): notify Core about the completion of a CommTask

#### Dependency Proxy: Get the Scheduling Control

An operator to get the scheduling control from the frameworks to the Core



#### Optimal Scheduling Theorem

- For PS, prioritize  $push_i$  over  $push_j$ , and  $pull_i$  over  $pull_j$ ,  $\forall i < j$
- For all-reduce, prioritize  $allreduce_i$  over  $allreduce_i$ ,  $\forall i < j$

#### Other Research Directions / Challenges

- Training in Heterogeneous GPU/CPU Clusters
- Federated Machine Learning over the Wide Area Network
- In-Network Aggregation
- Topology adaptation for DNN training workloads

# Thanks!