CS-171 Final Review

- First-Order Logic, Knowledge Representation
 - (8.1-8.5, 9.1-9.2)
- Probability & Bayesian Networks
 - (13, 14.1-14.5)
- Machine Learning
 - (18.1-18.4)
- Questions on any topic
- Pre-mid-term material if time and class interest
- Please review your quizzes, mid-term, & old tests
 - At least one question from a prior quiz or old CS-171 test will appear on the Final Exam (and all other tests)

Knowledge Representation using First-Order Logic

- Propositional Logic is Useful --- but has Limited Expressive Power
- First Order Predicate Calculus (FOPC), or First Order Logic (FOL).
 - FOPC has greatly expanded expressive power, though still limited.
- New Ontology
 - The world consists of OBJECTS (for propositional logic, the world was facts).
 - OBJECTS have PROPERTIES and engage in RELATIONS and FUNCTIONS.
- New Syntax
 - Constants, Predicates, Functions, Properties, Quantifiers.
- New Semantics
 - Meaning of new syntax.
- Knowledge engineering in FOL

Review: Syntax of FOL: Basic elements

- Constants KingJohn, 2, UCI,...
- Predicates Brother, >,...
- Functions Sqrt, LeftLegOf,...
- Variables x, y, a, b,...
- Connectives \neg , \Rightarrow , \wedge , \vee , \Leftrightarrow
- Equality =
- Quantifiers ∀, ∃

Syntax of FOL: Basic syntax elements are symbols

- Constant Symbols:
 - Stand for objects in the world.
 - E.g., KingJohn, 2, UCI, ...
- Predicate Symbols
 - Stand for relations (maps a tuple of objects to a truth-value)
 - E.g., Brother(Richard, John), greater_than(3,2), ...
 - P(x, y) is usually read as "x is P of y."
 - E.g., Mother(Ann, Sue) is usually "Ann is Mother of Sue."
- Function Symbols
 - Stand for functions (maps a tuple of objects to an object)
 - E.g., Sqrt(3), LeftLegOf(John), ...
- Model (world) = set of domain objects, relations, functions
- Interpretation maps symbols onto the model (world)
 - Very many interpretations are possible for each KB and world!
 - Job of the KB is to rule out models inconsistent with our knowledge.

Syntax of FOL: Terms

- Term = logical expression that refers to an object
- There are two kinds of terms:
 - Constant Symbols stand for (or name) objects:
 - E.g., KingJohn, 2, UCI, Wumpus, ...
 - Function Symbols map tuples of objects to an object:
 - E.g., LeftLeg(KingJohn), Mother(Mary), Sqrt(x)
 - This is nothing but a complicated kind of name
 - No "subroutine" call, no "return value"

Syntax of FOL: Atomic Sentences

- Atomic Sentences state facts (logical truth values).
 - An atomic sentence is a Predicate symbol, optionally followed by a parenthesized list of any argument terms
 - E.g., Married(Father(Richard), Mother(John))
 - An atomic sentence asserts that some relationship (some predicate) holds among the objects that are its arguments.
- An Atomic Sentence is true in a given model if the relation referred to by the predicate symbol holds among the objects (terms) referred to by the arguments.

Syntax of FOL: Connectives & Complex Sentences

- Complex Sentences are formed in the same way, and are formed using the same logical connectives, as we already know from propositional logic
- The Logical Connectives:
 - − ⇔ biconditional
 - $\Rightarrow implication$
 - $\wedge and$
 - \vee or
 - − ¬ negation
- Semantics for these logical connectives are the same as we already know from propositional logic.

Syntax of FOL: Variables

- Variables range over objects in the world.
- A variable is like a term because it represents an object.
- A variable may be used wherever a term may be used.
 - Variables may be arguments to functions and predicates.
- A term with NO variables is called a ground term.
- All variables must be bound by a quantifier, ∀ or ∃
- (A variable not bound by a quantifier is called free.)
 - Used by mathematicians, not used in this class

Syntax of FOL: Logical Quantifiers

- There are two Logical Quantifiers:
 - **Universal:** \forall x P(x) means "For all x, P(x)."
 - The "upside-down A" reminds you of "ALL."
 - **Existential:** $\exists x P(x)$ means "There exists x such that, P(x)."
 - The "upside-down E" reminds you of "EXISTS."
- Syntactic "sugar" --- we really only need one quantifier.
 - $\forall x P(x) \equiv \neg \exists x \neg P(x)$
 - $\exists x P(x) \equiv \neg \forall x \neg P(x)$
 - You can ALWAYS convert one quantifier to the other.
- RULES: ∀ = ¬∃¬ and ∃ = ¬∀¬
- RULE: To move negation "in" across a quantifier, change the quantifier to "the other quantifier" and negate the predicate on "the other side."
 - $\neg \forall x P(x) \equiv \exists x \neg P(x)$
 - $\neg \exists x P(x) \equiv \forall x \neg P(x)$

Universal Quantification ∀

- ∀ means "for all"
- Allows us to make statements about all objects that have certain properties
- Can now state general rules:

```
    ∀ x King(x) => Person(x) "All kings are persons."
    ∀ x Person(x) => HasHead(x) "Every person has a head."
    ∀ i Integer(i) => Integer(plus(i,1)) "If i is an integer then i+1 is an integer."
```

Note that

 \forall x King(x) \land Person(x) is not correct! This would imply that all objects x are Kings and are People

 \forall x King(x) => Person(x) is the correct way to say this

Note that => is the natural connective to use with \forall .

Existential Quantification 3

- ∃ x means "there exists an x such that...." (at least one object x)
- Allows us to make statements about some object without naming it
- Examples:

```
\exists x \ \text{King}(x) \ \text{"Some object is a king."}
```

 \exists x Lives_in(John, Castle(x)) "John lives in somebody's castle."

∃ i Integer(i) ∧ GreaterThan(i,0) "Some integer is greater than zero."

Note that ∧ is the natural connective to use with ∃

(And remember that => is the natural connective to use with \forall)

Combining Quantifiers --- Order (Scope)

The order of "unlike" quantifiers is important.

$$\forall x \exists y Loves(x,y)$$

For everyone ("all x") there is someone ("exists y") whom they love

$$\exists y \forall x Loves(x,y)$$

- there is someone ("exists y") whom everyone loves ("all x")

Clearer with parentheses: $\exists y (\forall x Loves(x,y))$

The order of "like" quantifiers does not matter.

$$\forall x \ \forall y \ P(x, y) \equiv \forall y \ \forall x \ P(x, y)$$

 $\exists x \ \exists y \ P(x, y) \equiv \exists y \ \exists x \ P(x, y)$

De Morgan's Law for Quantifiers

De Morgan's Rule

$$P \wedge Q \equiv \neg (\neg P \vee \neg Q)$$

$$P \lor Q \equiv \neg (\neg P \land \neg Q)$$

$$\neg (P \land Q) \equiv \neg P \lor \neg Q$$

$$\neg (P \lor Q) \equiv \neg P \land \neg Q$$

Generalized De Morgan's Rule

$$\forall x P \equiv \neg \exists x (\neg P)$$

$$\exists x P \equiv \neg \forall x (\neg P)$$

$$\neg \forall x P \equiv \exists x (\neg P)$$

$$\neg \exists x P \equiv \forall x (\neg P)$$

Rule is simple: if you bring a negation inside a disjunction or a conjunction, always switch between them (or \rightarrow and, and \rightarrow or).

Fun with sentences

Brothers are siblings

 $\forall x, y \; Brother(x, y) \Rightarrow Sibling(x, y).$

"Sibling" is symmetric

 $\forall x, y \ Sibling(x, y) \Leftrightarrow Sibling(y, x).$

One's mother is one's female parent

 $\forall x, y \; Mother(x, y) \Leftrightarrow (Female(x) \land Parent(x, y)).$

A first cousin is a child of a parent's sibling

 $\forall \, x,y \;\; FirstCousin(x,y) \;\; \Leftrightarrow \;\; \exists \, p,ps \;\; Parent(p,x) \land Sibling(ps,p) \land Parent(ps,y)$

- "All persons are mortal."
- [Use: Person(x), Mortal (x)]
- $\forall x \ Person(x) \Rightarrow Mortal(x)$
- ∀x ¬Person(x) ∨ Mortal(x)
- Common Mistakes:
- ∀x Person(x) ∧ Mortal(x)
- Note that => is the natural connective to use with ∀.

- "Fifi has a sister who is a cat."
- [Use: Sister(Fifi, x), Cat(x)]

•

- ∃x Sister(Fifi, x) ∧ Cat(x)
- Common Mistakes:
- $\exists x \; Sister(Fifi, x) \Rightarrow Cat(x)$
- Note that ∧ is the natural connective to use with ∃

- "For every food, there is a person who eats that food."
- [Use: Food(x), Person(y), Eats(y, x)]
- All are correct:
- $\forall x \exists y \ Food(x) \Rightarrow [Person(y) \land Eats(y, x)]$
- ∀x Food(x) ⇒ ∃y [Person(y) ∧ Eats(y, x)]
- ∀x ∃y ¬Food(x) ∨ [Person(y) ∧ Eats(y, x)]
- $\forall x \exists y [\neg Food(x) \lor Person(y)] \land [\neg Food(x) \lor Eats(y, x)]$
- $\forall x \exists y [Food(x) \Rightarrow Person(y)] \land [Food(x) \Rightarrow Eats(y, x)]$
- Common Mistakes:
- $\forall x \exists y [Food(x) \land Person(y)] \Rightarrow Eats(y, x)$
- ∀x ∃y Food(x) ∧ Person(y) ∧ Eats(y, x)

```
"Every person eats every food."
                     [Use: Person (x), Food (y), Eats(x, y)]
        \forall x \ \forall y \ [ \ Person(x) \land Food(y) \ ] \Rightarrow Eats(x, y)
        \forall x \forall y \neg Person(x) \lor \neg Food(y) \lor Eats(x, y)
        \forall x \ \forall y \ \mathsf{Person}(x) \Rightarrow [\ \mathsf{Food}(y) \Rightarrow \mathsf{Eats}(x, y) \ ]
        \forall x \ \forall y \ Person(x) \Rightarrow [ \neg Food(y) \lor Eats(x, y) ]
        \forall x \forall y \neg Person(x) \lor [Food(y) \Rightarrow Eats(x, y)]
Common Mistakes:
        \forall x \ \forall y \ \mathsf{Person}(x) \Rightarrow [\mathsf{Food}(y) \land \mathsf{Eats}(x, y)]
        \forall x \ \forall y \ Person(x) \land Food(y) \land Eats(x, y)
```

```
    "All greedy kings are evil."
    [Use: King(x), Greedy(x), Evil(x)]
    ∀x [ Greedy(x) ∧ King(x) ] ⇒ Evil(x)
    ∀x ¬Greedy(x) ∨ ¬King(x) ∨ Evil(x)
    ∀x Greedy(x) ⇒ [ King(x) ⇒ Evil(x) ]
    Common Mistakes:
    ∀x Greedy(x) ∧ King(x) ∧ Evil(x)
```

```
"Everyone has a favorite food."
                                                                                          [Use: Person(x), Food(y), Favorite(y, x)]
                                  \forall x \exists y \ Person(x) \Rightarrow [ \ Food(y) \land Favorite(y, x) ]
                                  \forall x \ Person(x) \Rightarrow \exists y \ [ \ Food(y) \land Favorite(y, x) \ ]
                                   \forall x \exists y \neg Person(x) \lor [Food(y) \land Favorite(y, x)]
                                   \forall x \exists y [ \neg Person(x) \lor Food(y) ] \land [ \neg Person(x) \lor 
Favorite(y, x) ]
                                   \forall x \exists y [Person(x) \Rightarrow Food(y)] \land [Person(x) \Rightarrow Favorite(y, y)]
x) ]
Common Mistakes:
                                   \forall x \exists y [ Person(x) \land Food(y) ] \Rightarrow Favorite(y, x)
                                   \forall x \exists y \ Person(x) \land Food(y) \land Favorite(y, x)
```

Semantics: Interpretation

- An interpretation of a sentence (wff) is an assignment that maps
 - Object constant symbols to objects in the world,
 - n-ary function symbols to n-ary functions in the world,
 - n-ary relation symbols to n-ary relations in the world
- Given an interpretation, an atomic sentence has the value "true" if it denotes a relation that holds for those individuals denoted in the terms. Otherwise it has the value "false."
 - Example: Kinship world:
 - Symbols = Ann, Bill, Sue, Married, Parent, Child, Sibling, ...
 - World consists of individuals in relations:
 - Married(Ann, Bill) is false, Parent(Bill, Sue) is true, ...
- Your job, as a Knowledge Engineer, is to construct KB so it is true *exactly* for your world and intended interpretation.

Semantics: Models and Definitions

- An interpretation and possible world <u>satisfies</u> a wff (sentence) if the wff has the value "true" under that interpretation in that possible world.
- A domain and an interpretation that satisfies a wff is a model of that wff
- Any wff that has the value "true" in all possible worlds and under all interpretations is <u>valid</u>.
- Any wff that does not have a model under any interpretation is inconsistent or unsatisfiable.
- Any wff that is true in at least one possible world under at least one interpretation is <u>satisfiable</u>.
- If a wff w has a value true under all the models of a set of sentences KB then KB logically entails w.

Conversion to CNF

 Everyone who loves all animals is loved by someone:

$$\forall x \ [\forall y \ Animal(y) \Rightarrow Loves(x,y)] \Rightarrow [\exists y \ Loves(y,x)]$$

1. Eliminate biconditionals and implications

$$\forall x [\neg \forall y \neg Animal(y) \lor Loves(x,y)] \lor [\exists y Loves(y,x)]$$

2. Move ¬ inwards:

$$\neg \forall x p \equiv \exists x \neg p, \neg \exists x p \equiv \forall x \neg p$$

$$\forall x \ [\exists y \neg (\neg Animal(y) \lor Loves(x,y))] \lor [\exists y \ Loves(y,x)] \ \forall x \ [\exists y \neg \neg Animal(y) \land \neg Loves(x,y)] \lor [\exists y \ Loves(y,x)] \ \forall x \ [\exists y \ Animal(y) \land \neg Loves(x,y)] \lor [\exists y \ Loves(y,x)]$$

Conversion to CNF contd.

3. Standardize variables: each quantifier should use a different one

```
\forall x \ [\exists y \ Animal(y) \land \neg Loves(x,y)] \lor [\exists z \ Loves(z,x)]
```

4. Skolemize: a more general form of existential instantiation. Each existential variable is replaced by a Skolem function of the enclosing universally quantified variables:

$$\forall x \ [Animal(F(x)) \land \neg Loves(x,F(x))] \lor Loves(G(x),x)$$

- 5. Drop universal quantifiers: $[Animal(F(x)) \land \neg Loves(x,F(x))] \lor Loves(G(x),x)$
- 6. Distribute \vee over \wedge : $[Animal(F(x)) \vee Loves(G(x),x)] \wedge [\neg Loves(x,F(x)) \vee Loves(G(x),x)]$

Unification

- Recall: Subst(θ, p) = result of substituting θ into sentence p
- Unify algorithm: takes 2 sentences p and q and returns a unifier if one exists

Unify(p,q) =
$$\theta$$
 where Subst(θ , p) = Subst(θ , q)

• Example:

$$p = Knows(John,x)$$

q = Knows(John, Jane)

Unify
$$(p,q) = \{x/Jane\}$$

Unification examples

simple example: query = Knows(John,x), i.e., who does John know?

р	q	θ
Knows(John,x)	Knows(John,Jane)	{x/Jane}
Knows(John,x)	Knows(y,OJ)	{x/OJ,y/John}
Knows(John,x)	Knows(y,Mother(y))	{ y/John,x/Mother(John) }
Knows(John,x)	Knows(x,OJ)	{fail}

- Last unification fails: only because x can't take values John and OJ at the same time
 - But we know that if John knows x, and everyone (x) knows OJ, we should be able to infer that John knows OJ
- Problem is due to use of same variable x in both sentences
- Simple solution: Standardizing apart eliminates overlap of variables, e.g., Knows(z,OJ)

Unification

To unify Knows(John,x) and Knows(y,z),

```
\theta = \{y/John, x/z\} or \theta = \{y/John, x/John, z/John\}
```

- The first unifier is more general than the second.
- There is a single most general unifier (MGU) that is unique up to renaming of variables.

$$MGU = \{ y/John, x/z \}$$

General algorithm in Figure 9.1 in the text

Unification Algorithm

```
function UNIFY(x, y, \theta) returns a substitution to make x and y identical
  inputs: x, a variable, constant, list, or compound expression
           y, a variable, constant, list, or compound expression
           \theta, the substitution built up so far (optional, defaults to empty)
  if \theta = failure then return failure
  else if x = y then return \theta
  else if VARIABLE?(x) then return UNIFY-VAR(x, y, \theta)
  else if VARIABLE?(y) then return UNIFY-VAR(y, x, \theta)
  else if COMPOUND?(x) and COMPOUND?(y) then
      return UNIFY(x.ARGS, y.ARGS, UNIFY(x.OP, y.OP, \theta))
  else if LIST?(x) and LIST?(y) then
      return UNIFY(x.REST, y.REST, UNIFY(x.FIRST, y.FIRST, \theta))
  else return failure
function UNIFY-VAR(var, x, \theta) returns a substitution
  if \{var/val\} \in \theta then return UNIFY(val, x, \theta)
  else if \{x/val\} \in \theta then return UNIFY(var, val, \theta)
  else if OCCUR-CHECK?(var, x) then return failure
  else return add \{var/x\} to \theta
```

Figure 9.1 The unification algorithm. The algorithm works by comparing the structures of the inputs, element by element. The substitution θ that is the argument to UNIFY is built up along the way and is used to make sure that later comparisons are consistent with bindings that were established earlier. In a compound expression such as F(A, B), the OP field picks out the function symbol F and the ARGS field picks out the argument list (A, B).

Knowledge engineering in FOL

- 1. Identify the task
- 2. Assemble the relevant knowledge
- 3. Decide on a vocabulary of predicates, functions, and constants
- 4. Encode general knowledge about the domain
- 5. Encode a description of the specific problem instance
- 6. Pose queries to the inference procedure and get answers
- 7. Debug the knowledge base

- 1. Identify the task
 - Does the circuit actually add properly?
- 2. Assemble the relevant knowledge
 - Composed of wires and gates; Types of gates (AND, OR, XOR, NOT)

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- Irrelevant: size, shape, color, cost of gates

_

- 3. Decide on a vocabulary
 - Alternatives:

_

```
Type(X_1) = XOR (function)
Type(X_1, XOR) (binary predicate)
XOR(X_1)
(unary predicate)
```

- 4. Encode general knowledge of the domain
 - $\forall t_1, t_2 \text{ Connected}(t_1, t_2) \Rightarrow \text{Signal}(t_1) = \text{Signal}(t_2)$
 - $\forall t \ Signal(t) = 1 \lor Signal(t) = 0$
 - 1 \neq 0
 - $\forall t_1, t_2 \text{ Connected}(t_1, t_2) \Rightarrow \text{Connected}(t_2, t_1)$
 - $\forall g \text{ Type}(g) = OR \Rightarrow \text{Signal}(Out(1,g)) = 1 \Leftrightarrow \exists n \text{ Signal}(In(n,g)) = 1$
 - $\forall g \text{ Type}(g) = \text{AND} \Rightarrow \text{Signal}(\text{Out}(1,g)) = 0 \Leftrightarrow \exists n \text{ Signal}(\text{In}(n,g)) = 0$
 - ∀g Type(g) = XOR ⇒ Signal(Out(1,g)) = 1 ⇔ Signal(In(1,g)) ≠ Signal(In(2,g))
 - $\forall g \text{ Type}(g) = \text{NOT} \Rightarrow \text{Signal}(\text{Out}(1,g)) \neq \text{Signal}(\text{In}(1,g))$

5. Encode the specific problem instance

```
Type(X_1) = XOR Type(X_2) = XOR

Type(A_1) = AND Type(A_2) = AND

Type(O_1) = OR
```

Connected(Out(1, X_1),In(1, X_2))	Connected($In(1,C_1),In(1,X_1)$)
Connected(Out(1, X_1),In(2, A_2))	Connected($In(1,C_1),In(1,A_1)$)
Connected(Out(1, A_2),In(1,O ₁))	Connected($In(2,C_1),In(2,X_1)$)
Connected(Out(1, A_1),In(2, O_1))	Connected($In(2,C_1),In(2,A_1)$)
Connected(Out(1, X_2),Out(1, C_1))	Connected($In(3,C_1),In(2,X_2)$)
Connected(Out(1,O $_1$),Out(2,C $_1$))	Connected($In(3,C_1),In(1,A_2)$)

6. Pose queries to the inference procedure

What are the possible sets of values of all the terminals for the adder circuit?

$$\exists i_1, i_2, i_3, o_1, o_2 \text{ Signal}(In(1, C_1)) = i_1 \land \text{Signal}(In(2, C_1)) = i_2 \land \text{Signal}(In(3, C_1)) = i_3 \land \text{Signal}(Out(1, C_1)) = o_1 \land \text{Signal}(Out(2, C_1)) = o_2$$

Debug the knowledge base
 May have omitted assertions like 1 ≠ 0

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You will be expected to know

- Basic probability notation/definitions:
 - Probability model, unconditional/prior and conditional/posterior probabilities, factored representation (= variable/value pairs), random variable, (joint) probability distribution, probability density function (pdf), marginal probability, (conditional) independence, normalization, etc.
- Basic probability formulae:
 - Probability axioms, product rule, Bayes' rule.
- How to use Bayes' rule:
 - Naïve Bayes model (naïve Bayes classifier)

Syntax

- Basic element: random variable
- •Similar to propositional logic: possible worlds defined by assignment of values to random variables.
- Booleanrandom variables
 - e.g., Cavity (= do I have a cavity?)
- Discreterandom variables
 - e.g., Weather is one of <sunny,rainy,cloudy,snow>
- Domain values must be exhaustive and mutually exclusive
- •Elementary proposition is an assignment of a value to a random variable: e.g., Weather = sunny; Cavity = false(abbreviated as \neg cavity)
- Complex propositions formed from elementary propositions and standard logical connectives :
 - e.g., Weather = sunny V Cavity = false

Probability

- P(a) is the probability of proposition "a"
 - e.g., P(it will rain in London tomorrow)
 - The proposition a is actually true or false in the real-world

• **Probability Axioms**:

- $-0 \le P(a) \le 1$
- $P(NOT(a)) = 1 P(a) \qquad => \qquad \Sigma_A P(A) = 1$
- P(true) = 1
- P(false) = 0
- P(A OR B) = P(A) + P(B) P(A AND B)
- Any agent that holds degrees of beliefs that contradict these axioms will act irrationally in some cases
- Rational agents <u>cannot</u> violate probability theory.
 - Acting otherwise results in irrational behavior.

Conditional Probability

- P(a|b) is the conditional probability of proposition a, conditioned on knowing that b is true,
 - E.g., P(rain in London tomorrow | raining in London today)
 - P(a|b) is a "posterior" or conditional probability
 - The updated probability that a is true, now that we know b
 - $P(a|b) = P(a \land b) / P(b)$
 - Syntax: P(a | b) is the probability of a given that b is true
 - a and b can be any propositional sentences
 - e.g., p(John wins OR Mary wins | Bob wins AND Jack loses)
- P(a|b) obeys the same rules as probabilities,
 - E.g., P(a | b) + P(NOT(a) | b) = 1
 - All probabilities in effect are conditional probabilities
 - E.g., P(a) = P(a | our background knowledge)

Concepts of Probability

Unconditional Probability

- P(a), the probability of "a" being true, or P(a=True)
- Does not depend on anything else to be true (unconditional)
- Represents the probability prior to further information that may adjust it (prior)

Conditional Probability

- P(a|b), the probability of "a" being true, given that "b" is true
- Relies on "b" = true (conditional)
- Represents the prior probability adjusted based upon new information "b" (posterior)
- Can be generalized to more than 2 random variables:
 - e.g. P(a|b, c, d)

Joint Probability

- $P(a, b) = P(a \land b)$, the probability of "a" and "b" both being true
- Can be generalized to more than 2 random variables:
 - e.g. P(a, b, c, d)

Basic Probability Relationships

- $P(A) + P(\neg A) = 1$
 - Implies that $P(\neg A) = 1 P(A)$
- $P(A, B) = P(A \land B) = P(A) + P(B) P(A \lor B)$
 - Implies that $P(A \lor B) = P(A) + P(B) P(A \land B)$
- P(A | B) = P(A, B) / P(B)
 - Conditional probability; "Probability of A given B"
- P(A, B) = P(A | B) P(B)
 - Product Rule (Factoring); applies to any number of variables
 - P(a, b, c,...z) = P(a | b, c,...z) P(b | c,...z) P(c|...z)...P(z)
- $P(A) = \Sigma_{B,C} P(A, B, C) = \Sigma_{b \in B, c \in C} P(A, b, c)$
 - Sum Rule (Marginal Probabilities); for any number of variables
 - $P(A, D) = \Sigma_B \Sigma_C P(A, B, C, D) = \Sigma_{b \in B} \Sigma_{c \in C} P(A, b, c, D)$
- P(B | A) = P(A | B) P(B) / P(A)
 - Bayes' Rule; for any number of variables

You need to know these!

Summary of Probability Rules

Product Rule:

- P(a, b) = P(a|b) P(b) = P(b|a) P(a)
- Probability of "a" and "b" occurring is the same as probability of "a" occurring given "b" is true, times the probability of "b" occurring.
 - e.g., P(rain, cloudy) = P(rain | cloudy) * P(cloudy)
- <u>Sum Rule</u>: (AKA Law of Total Probability)
 - $P(a) = \Sigma_b P(a, b) = \Sigma_b P(a|b) P(b)$, where B is any random variable
 - Probability of "a" occurring is the same as the sum of all joint probabilities including the event, provided the joint probabilities represent all possible events.
 - Can be used to "marginalize" out other variables from probabilities, resulting in prior probabilities also being called marginal probabilities.
 - e.g., $P(rain) = \Sigma_{Windspeed} P(rain, Windspeed)$ where Windspeed = {0-10mph, 10-20mph, 20-30mph, etc.}

• Bayes' Rule:

- P(b|a) = P(a|b) P(b) / P(a)
- Acquired from rearranging the product rule.
- Allows conversion between conditionals, from P(a|b) to P(b|a).
 - e.g., b = disease, a = symptomsMore natural to encode knowledge as P(a|b) than as P(b|a).

Full Joint Distribution

- We can fully specify a probability space by constructing a full joint distribution:
 - A full joint distribution contains a probability for every possible combination of variable values.
 - E.g., P(J=f, M=t, A=t, B=t, E=f)
- From a full joint distribution, the product rule, sum rule, and Bayes' rule can create any desired joint and conditional probabilities.

Computing with Probabilities: Law of Total Probability

Law of Total Probability (aka "summing out" or marginalization)

$$P(a) = \Sigma_b P(a, b)$$

= $\Sigma_b P(a | b) P(b)$ where B is any random variable

Why is this useful?

Given a joint distribution (e.g., P(a,b,c,d)) we can obtain any "marginal" probability (e.g., P(b)) by summing out the other variables, e.g.,

$$P(b) = \sum_{a} \sum_{c} \sum_{d} P(a, b, c, d)$$

We can compute any conditional probability given a joint distribution, e.g.,

$$P(c \mid b) = \sum_{a} \sum_{d} P(a, c, d \mid b)$$

$$= \sum_{a} \sum_{d} P(a, c, d, b) / P(b)$$
where P(b) can be computed as above

Computing with Probabilities: The Chain Rule or Factoring

We can always write

$$P(a, b, c, ... z) = P(a | b, c, ... z) P(b, c, ... z)$$
(by definition of joint probability)

Repeatedly applying this idea, we can write

$$P(a, b, c, ... z) = P(a | b, c, ... z) P(b | c, ... z) P(c | ... z)...P(z)$$

This factorization holds for any ordering of the variables

This is the chain rule for probabilities

Independence

Formal Definition:

2 random variables A and B are independent iff:

$$P(a, b) = P(a) P(b)$$
, for all values a, b

Informal Definition:

2 random variables A and B are independent iff:

$$P(a \mid b) = P(a)$$
 OR $P(b \mid a) = P(b)$, for all values a, b

- P(a | b) = P(a) tells us that knowing b provides no change in our probability for a, and thus b contains no information about a.
- Also known as marginal independence, as all other variables have been marginalized out.
- In practice true independence is very rare:
 - "butterfly in China" effect
 - Conditional independence is much more common and useful

Conditional Independence

Formal Definition:

2 random variables A and B are conditionally independent given C iff:
 P(a, b|c) = P(a|c) P(b|c), for all values a, b, c

• Informal Definition:

- 2 random variables A and B are conditionally independent given C iff:
 - P(a|b,c) = P(a|c) OR P(b|a,c) = P(b|c), for all values a, b, c
- P(a|b, c) = P(a|c) tells us that learning about b, given that we already know c, provides no change in our probability for a, and thus b contains no information about a beyond what c provides.

• Naïve Bayes Model:

- Often a single variable can directly influence a number of other variables, all
 of which are conditionally independent, given the single variable.
- E.g., k different symptom variables X_1 , X_2 , ... X_k , and C = disease, reducing to: $P(X_1, X_2, ..., X_K \mid C) = P(C) \prod P(X_i \mid C)$

Examples of Conditional Independence

H=Heat, S=Smoke, F=Fire

- P(H, S | F) = P(H | F) P(S | F)
- P(S | F, S) = P(S | F)
- If we know there is/is not a fire, observing heat tells us no more information about smoke

F=Fever, R=RedSpots, M=Measles

- P(F, R | M) = P(F | M) P(R | M)
- $P(R \mid M, F) = P(R \mid M)$
- If we know we do/don't have measles, observing fever tells us no more information about red spots

C=SharpClaws, F=SharpFangs, S=Species

- P(C, F | S) = P(C | S) P(F | S)
- P(F | S, C) = P(F | S)
- If we know the species, observing sharp claws tells us no more information about sharp fangs

Review Bayesian Networks (Chapter 14.1-5)

You will be expected to know:

- Basic concepts and vocabulary of Bayesian networks.
 - Nodes represent random variables.
 - Directed arcs represent (informally) direct influences.
 - Conditional probability tables, P(Xi | Parents(Xi)).
- Given a Bayesian network:
 - Write down the full joint distribution it represents.
 - Inference by Variable Elimination
- Given a full joint distribution in factored form:
 - Draw the Bayesian network that represents it.
- Given a variable ordering and background assertions of conditional independence among the variables:
 - Write down the factored form of the full joint distribution, as simplified by the conditional independence assertions.

Bayesian Networks

- Represent dependence/independence via a directed graph
 - Nodes = random variables
 - Edges = direct dependence
- Recall the chain rule of repeated conditioning:

$$P(X_1, X_2, X_3..., X_N) = P(X_1 | X_2, X_3..., X_N) P(X_2 | X_3, ..., X_N) \cdots P(X_N)$$

$$P(X_1, X_2, X_3..., X_N) = \prod_{i=1}^n P(X_i | parents(X_i))$$

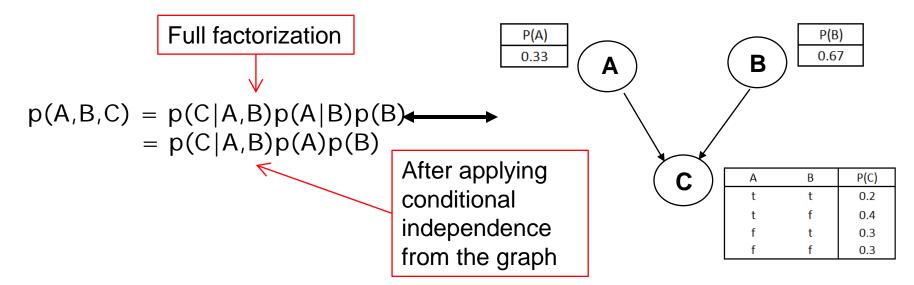
The full joint distribution

The graph-structured approximation

- Requires that graph is acyclic (no directed cycles)
- 2 components to a Bayesian network
 - The graph structure (conditional independence assumptions)
 - The numerical probabilities (of each variable given its parents)

Bayesian Network

A Bayesian network specifies a joint distribution in a structured form:



- Dependence/independence represented via a directed graph:
 - Node = random variable
 - = conditional dependence
 - Directed EdgeAbsence of Edge = conditional independence
- •Allows concise view of joint distribution relationships:
 - Graph nodes and edges show conditional relationships between variables.
 - Tables provide probability data.

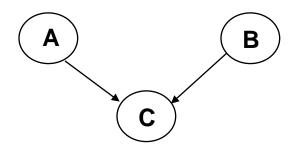
Examples of 3-way Bayesian Networks

Independent Causes

A Earthquake

B Burglary

C Alarm



Independent Causes: p(A,B,C) = p(C|A,B)p(A)p(B)

"Explaining away" effect:

Given C, observing A makes B less likely e.g., earthquake/burglary/alarm example

A and B are (marginally) independent but become dependent once C is known

You heard alarm, and observe Earthquake It explains away burglary

Nodes: Random Variables

A, B, C

Edges: P(Xi | Parents) → Directed edge from parent nodes to Xi

 $A \rightarrow C$

 $B \rightarrow C$

Examples of 3-way Bayesian Networks





Marginal Independence: p(A,B,C) = p(A) p(B) p(C)

Nodes: Random Variables

A, B, C

Edges: P(Xi | Parents) → Directed edge from parent nodes to Xi

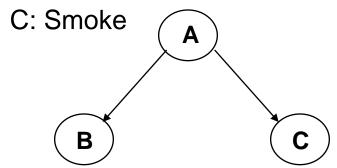
No Edge!

Extended example of 3-way Bayesian Networks

Common Cause

A: Fire

B: Heat



Conditionally independent effects:

p(A,B,C) = p(B|A)p(C|A)p(A)

B and C are conditionally independent Given A

"Where there's Smoke, there's Fire."

If we see Smoke, we can infer Fire.

If we see Smoke, observing Heat tells us very little additional information.

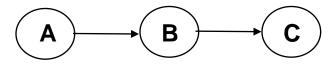
Examples of 3-way Bayesian Networks

Markov Dependence

A Rain on Mon

B Ran on Tue

C Rain on Wed



Markov dependence: p(A,B,C) = p(C|B) p(B|A)p(A)

A affects B and B affects C Given B, A and C are independent

e.g.

If it rains today, it will rain tomorrow with 90%

On Wed morning...
If you know it rained yesterday,
it doesn't matter whether it rained on Mon

Nodes: Random Variables

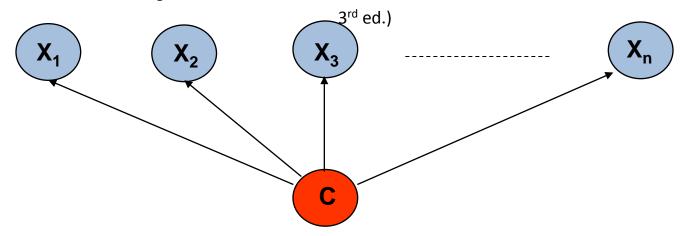
A, B, C

Edges: P(Xi | Parents) → Directed edge from parent nodes to Xi

 $A \rightarrow B$

 $B \rightarrow C$

Naïve Bayes Model



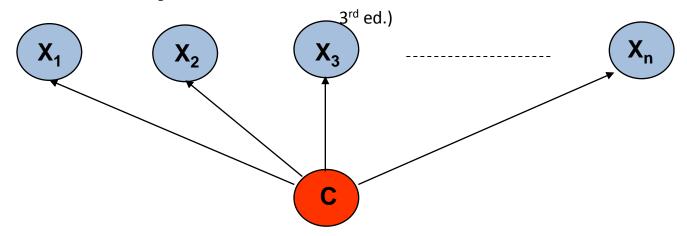
Basic Idea: We want to estimate $P(C \mid X_1,...X_n)$, but it's hard to think about computing the probability of a class from input attributes of an example.

Solution: Use Bayes' Rule to turn $P(C \mid X_1,...X_n)$ into a proportionally equivalent expression that involves only P(C) and $P(X_1,...X_n \mid C)$. Then assume that feature values are conditionally independent given class, which allows us to turn $P(X_1,...X_n \mid C)$ into Π_i $P(X_i \mid C)$.

We estimate P(C) easily from the frequency with which each class appears within our training data, and we estimate $P(X_i \mid C)$ easily from the frequency with which each X_i appears in each class C within our training data.

(section 20.2.2 R&N

Naïve Bayes Model



Bayes Rule: $P(C \mid X_1,...X_n)$ is proportional to $P(C) \mid \Pi_i \mid P(X_i \mid C)$ [note: denominator $P(X_1,...X_n)$ is constant for all classes, may be ignored.]

Features Xi are conditionally independent given the class variable C

- choose the class value c_i with the highest $P(c_i \mid x_1,...,x_n)$
- simple to implement, often works very well
- e.g., spam email classification: X's = counts of words in emails

Conditional probabilities $P(X_i \mid C)$ can easily be estimated from labeled date

- Problem: Need to avoid zeroes, e.g., from limited training data
- Solutions: Pseudo-counts, beta[a,b] distribution, etc.

Naïve Bayes Model (2)

$$P(C \mid X_1,...X_n) = \alpha P(C) \Pi_i P(X_i \mid C)$$

Probabilities P(C) and $P(X_i \mid C)$ can easily be estimated from labeled data

 $P(C = c_i) \approx \#(Examples \text{ with class label } C = c_i) / \#(Examples)$

$$P(X_i = x_{ik} \mid C = c_j)$$

$$\approx \#(\text{Examples with attribute value } X_i = x_{ik} \text{ and class label } C = c_j)$$

$$/ \#(\text{Examples with class label } C = c_i)$$

Usually easiest to work with logs

$$\log [P(C \mid X_1,...X_n)]$$

$$= \log \alpha + \log P(C) + \sum \log P(X_i \mid C)$$

DANGER: What if ZERO examples with value $X_i = x_{ik}$ and class label $C = c_j$? An unseen example with value $X_i = x_{ik}$ will NEVER predict class label $C = c_j$!

Practical solutions: Pseudocounts, e.g., add 1 to every #(), etc. Theoretical solutions: Bayesian inference, beta distribution, etc.

Bigger Example

- Consider the following 5 binary variables:
 - B = a burglary occurs at your house
 - E = an earthquake occurs at your house
 - A = the alarm goes off
 - J = John calls to report the alarm
 - M = Mary calls to report the alarm
- Sample Query: What is P(B|M, J) ?
- Using full joint distribution to answer this question requires
 - $2^5 1 = 31$ parameters
- Can we use prior domain knowledge to come up with a Bayesian network that requires fewer probabilities?

Constructing a Bayesian Network: Step 1

Order the variables in terms of influence (may be a partial order)

e.g.,
$$\{E, B\} \rightarrow \{A\} \rightarrow \{J, M\}$$

• P(J, M, A, E, B) = P(J, M | A, E, B) P(A | E, B) P(E, B)

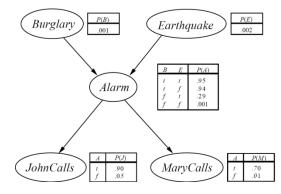
$$\approx$$
 P(J, M | A) P(A| E, B) P(E) P(B)

$$\approx$$
 P(J | A) P(M | A) P(A| E, B) P(E) P(B)

These conditional independence assumptions are reflected in the graph structure of the Bayesian network

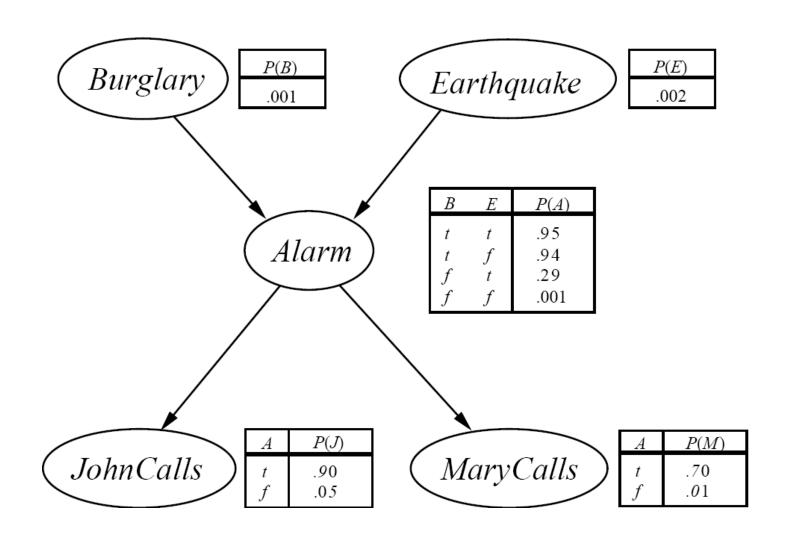
Constructing this Bayesian Network: Step 2

• P(J, M, A, E, B) = P(J | A) P(M | A) P(A | E, B) P(E) P(B)

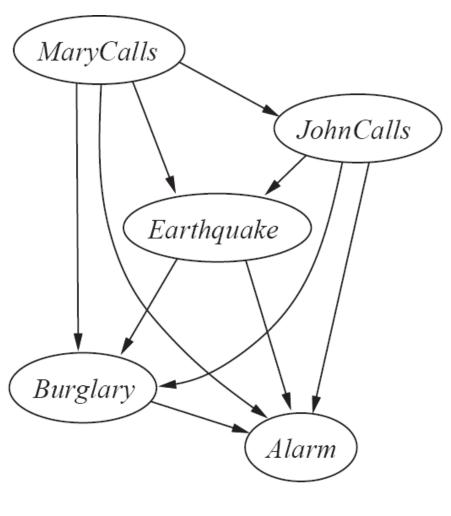


- There are 3 conditional probability tables (CPDs) to be determined:
 P(J | A), P(M | A), P(A | E, B)
 - Requiring 2 + 2 + 4 = 8 probabilities
- And 2 marginal probabilities P(E), P(B) -> 2 more probabilities
- Where do these probabilities come from?
 - Expert knowledge
 - From data (relative frequency estimates)
 - Or a combination of both see discussion in Section 20.1 and 20.2 (optional)

The Resulting Bayesian Network

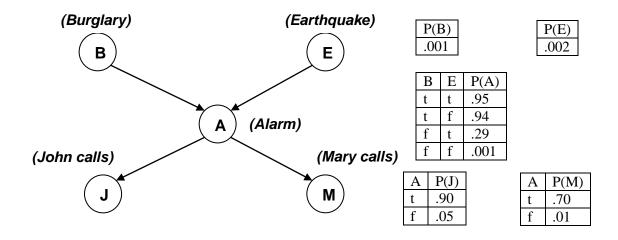


The Bayesian Network from a different Variable Ordering



Computing Probabilities from a Bayesian Network

Shown below is the Bayesian network for the Burglar Alarm problem, i.e., $P(J,M,A,B,E) = P(J \mid A) P(M \mid A) P(A \mid B, E) P(B) P(E)$.



Suppose we wish to compute P($J=f \land M=t \land A=t \land B=t \land E=f$):

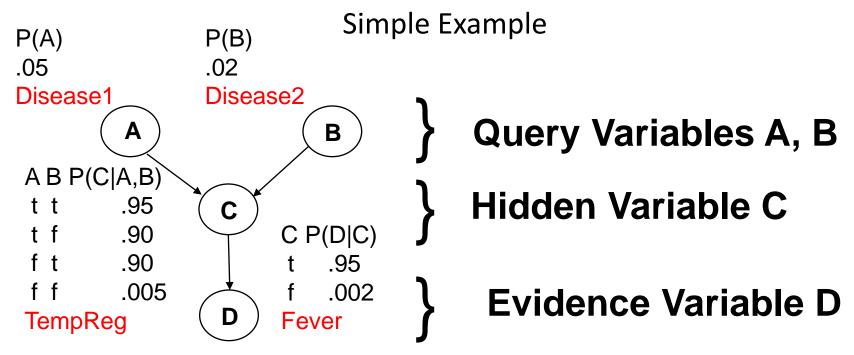
$$P(J=f \land M=t \land A=t \land B=t \land E=f)$$

= $P(J=f \mid A=t) * P(M=t \mid A=t) * P(A=t \mid B=t \land E=f) * P(B=t) * P(E=f)$
= .10 * .70 * .94 * .001 * .998

Note:
$$P(E=f) = [1 - P(E=t)] = [1 - .002)] = .998$$

 $P(J=f | A=t) = [1 - P(J=t | A=t)] = .10$

Inference in Bayesian Networks



(A=True, B=False | D=True): Probability of getting Disease1 when we observe Fever

Note: Not an anatomically correct model of how diseases cause fever!

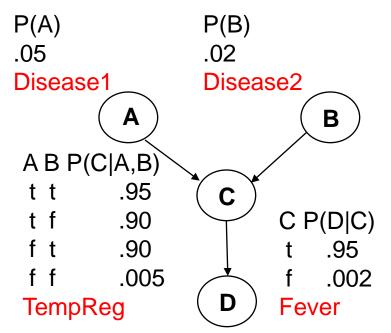
Suppose that two different diseases influence some imaginary internal body temperature regulator, which in turn influences whether fever is present.

Inference in Bayesian Networks

- $X = \{X1, X2, ..., Xk\} =$ query variables of interest
- **E** = { E1, ..., El } = **evidence variables** that are observed
- **Y** = { *Y1, ..., Ym* } = **hidden variables** (nonevidence, nonquery)

- What is the posterior distribution of X, given E?
 - $P(X \mid e) = \alpha \Sigma_y P(X, y, e)$ Normalizing constant $\alpha = \Sigma_x \Sigma_y P(X, y, e)$
- What is the most likely assignment of values to X, given E?
 - $\operatorname{argmax}_{x} P(x \mid e) = \operatorname{argmax}_{x} \Sigma_{y} P(x, y, e)$

Inference by Variable Elimination



What is the posterior conditional distribution of our query variables, given that fever was observed?

 $P(A,B|d) = \alpha \Sigma_{c} P(A,B,c,d)$ $= \alpha \Sigma_{c} P(A)P(B)P(c|A,B)P(d|c)$ $= \alpha P(A)P(B) \Sigma_{c} P(c|A,B)P(d|c)$

```
\begin{split} P(a,b|d) &= \alpha \ P(a)P(b) \ \Sigma_c \ P(c|a,b)P(d|c) = \alpha \ P(a)P(b) \{ \ P(c|a,b)P(d|c) + P(\neg c|a,b)P(d|\neg c) \ \} \\ &= \alpha \ .05x.02x \{ .95x.95 + .05x.002 \} \approx \alpha \ .000903 \approx .014 \\ P(\neg a,b|d) &= \alpha \ P(\neg a)P(b) \ \Sigma_c \ P(c|\neg a,b)P(d|c) = \alpha \ P(\neg a)P(b) \{ \ P(c|\neg a,b)P(d|c) + P(\neg c|\neg a,b)P(d|\neg c) \ \} \\ &= \alpha \ .95x.02x \{ .90x.95 + .10x.002 \} \approx \alpha \ .0162 \approx .248 \\ P(a,\neg b|d) &= \alpha \ P(a)P(\neg b) \ \Sigma_c \ P(c|a,\neg b)P(d|c) = \alpha \ P(a)P(\neg b) \{ \ P(c|a,\neg b)P(d|c) + P(\neg c|a,\neg b)P(d|\neg c) \ \} \\ &= \alpha \ .05x.98x \{ .90x.95 + .10x.002 \} \approx \alpha \ .0419 \approx .642 \\ P(\neg a,\neg b|d) &= \alpha \ P(\neg a)P(\neg b) \ \Sigma_c \ P(c|\neg a,\neg b)P(d|c) = \alpha \ P(\neg a)P(\neg b) \{ \ P(c|\neg a,\neg b)P(d|c) + P(\neg c|\neg a,\neg b)P(d|\neg c) \ \} \\ &= \alpha \ .95x.98x \{ .005x.95 + .995x.002 \} \approx \alpha \ .00627 \approx .096 \\ \alpha \approx 1 \ / \ (.000903 + .0162 + .0419 + .00627) \approx 1 \ / \ .06527 \approx 15.32 \quad \text{[Note: } \alpha = \text{normalization constant, p. 493]} \end{split}
```

CS-171 Final Review

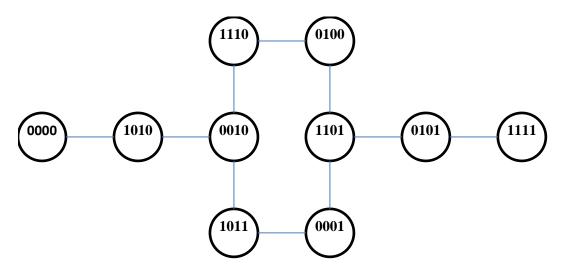
- First-Order Logic, Knowledge Representation
 - (8.1-8.5, 9.1-9.2)
- Probability & Bayesian Networks
 - (13, 14.1-14.5)
- Machine Learning
 - (18.1-18.12, 20.1-20.2)
- Questions on any topic
- Pre-mid-term material if time and class interest
- Please review your quizzes, mid-term, & old tests
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The importance of a good representation

- Properties of a good representation:
- Reveals important features
- Hides irrelevant detail
- Exposes useful constraints
- Makes frequent operations easy-to-do
- Supports local inferences from local features
 - Called the "soda straw" principle or "locality" principle
 - Inference from features "through a soda straw"
- Rapidly or efficiently computable
 - It's nice to be fast

Reveals important features / Hides irrelevant detail

- "You can't learn what you can't represent." --- G. Sussman
- In search: A man is traveling to market with a fox, a goose, and a bag of oats. He comes to a river. The only way across the river is a boat that can hold the man and exactly one of the fox, goose or bag of oats. The fox will eat the goose if left alone with it, and the goose will eat the oats if left alone with it.
- A good representation makes this problem easy:



Terminology

- Attributes
 - Also known as features, variables, independent variables, covariates
- Target Variable
 - Also known as goal predicate, dependent variable, ...
- Classification
 - Also known as discrimination, supervised classification, ...
- Error function
 - Objective function, loss function, ...

Inductive learning

- Let x represent the input vector of attributes
- Let f(x) represent the value of the target variable for x
 - The implicit mapping from x to f(x) is unknown to us
 - We just have training data pairs, $D = \{x, f(x)\}$ available
- We want to learn a mapping from x to f, i.e.,
 h(x; θ) is "close" to f(x) for all training data points x
 - θ are the parameters of our predictor h(..)
- Examples:
 - $h(x; \theta) = sign(w_1x_1 + w_2x_2 + w_3)$
 - $h_k(x) = (x1 \text{ OR } x2) \text{ AND } (x3 \text{ OR NOT}(x4))$

Empirical Error Functions

Empirical error function:

$$E(h) = \Sigma_X \text{ distance}[h(x; \theta), f]$$

e.g., distance = squared error if h and f are real-valued (regression) distance = delta-function if h and f are categorical (classification)

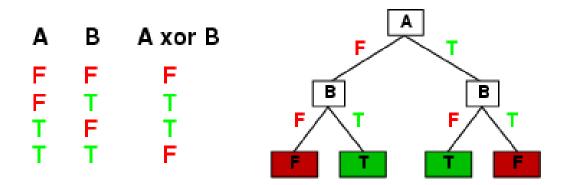
Sum is over all training pairs in the training data D

In learning, we get to choose

- 1. what class of functions h(..) that we want to learn
 - potentially a huge space! ("hypothesis space")
 - 2. what error function/distance to use
 - should be chosen to reflect real "loss" in problem
 - but often chosen for mathematical/algorithmic convenience

Decision Tree Representations

- Decision trees are fully expressive
 - can represent any Boolean function
 - Every path in the tree could represent 1 row in the truth table
 - Yields an exponentially large tree
 - Truth table is of size 2^d, where d is the number of attributes



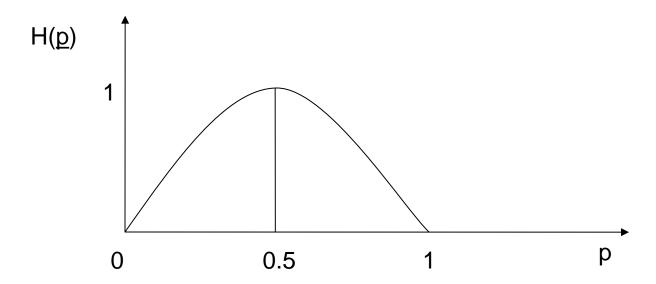
Pseudocode for Decision tree learning

```
function DTL(examples, attributes, default) returns a decision tree if examples is empty then return default else if all examples have the same classification then return the classification else if attributes is empty then return Mode(examples) else best \leftarrow \texttt{Choose-Attribute}(attributes, examples) \\ tree \leftarrow \texttt{a} \text{ new decision tree with root test } best \\ \textbf{for each value } v_i \text{ of } best \textbf{ do} \\ examples_i \leftarrow \{\text{elements of } examples \text{ with } best = v_i\} \\ subtree \leftarrow \texttt{DTL}(examples_i, attributes - best, \texttt{Mode}(examples)) \\ \texttt{add a branch to } tree \text{ with label } v_i \text{ and subtree } subtree \\ \textbf{return } tree
```

Entropy with only 2 outcomes

Consider 2 class problem: p = probability of class 1, 1 - p = probability of class 2

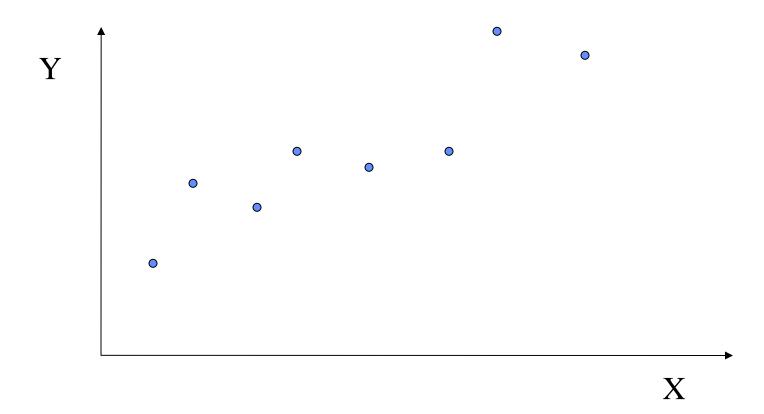
In binary case, $H(p) = -p \log p - (1-p) \log (1-p)$



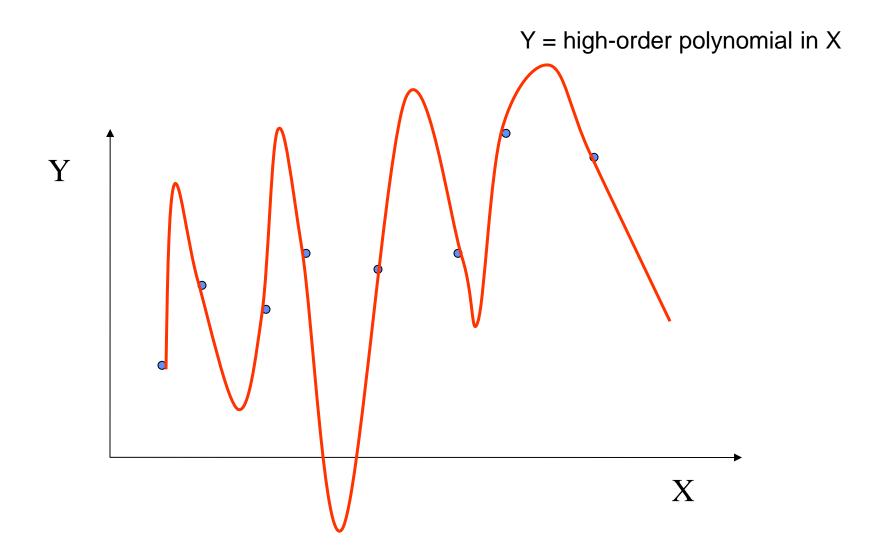
Information Gain

- H(p) = entropy of class distribution at a particular node
- H(p | A) = conditional entropy = average entropy of conditional class distribution, after we have partitioned the data according to the values in A
- $Gain(A) = H(p) H(p \mid A)$
- Simple rule in decision tree learning
 - At each internal node, split on the node with the largest information gain (or equivalently, with smallest H(p|A))
- Note that by definition, conditional entropy can't be greater than the entropy

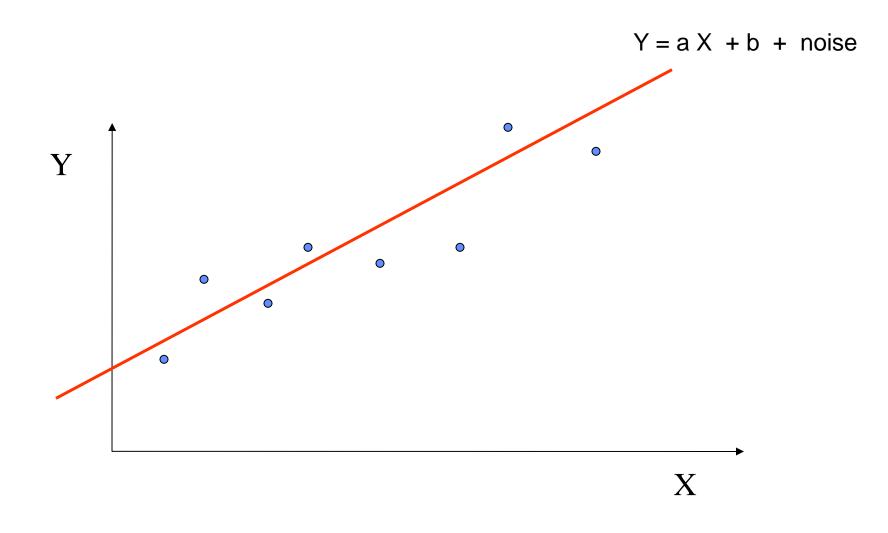
Overfitting and Underfitting



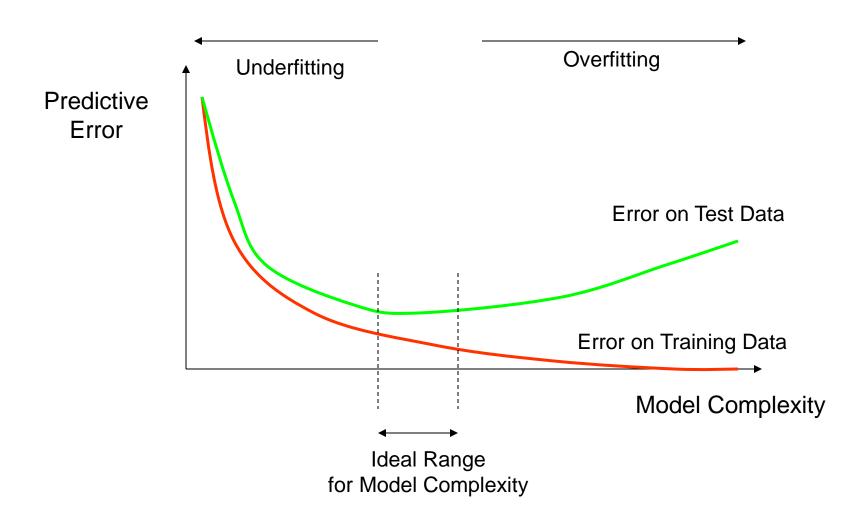
A Complex Model



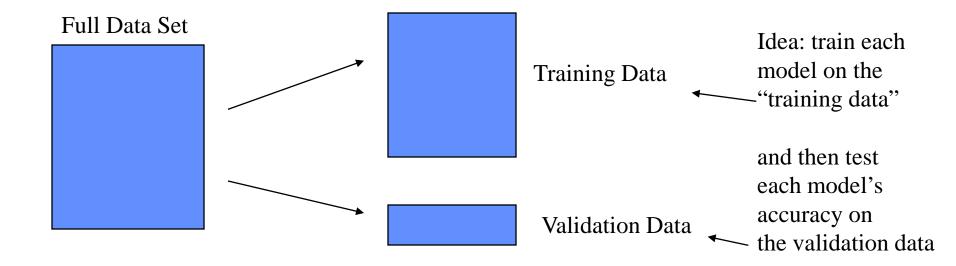
A Much Simpler Model



How Overfitting affects Prediction



Training and Validation Data



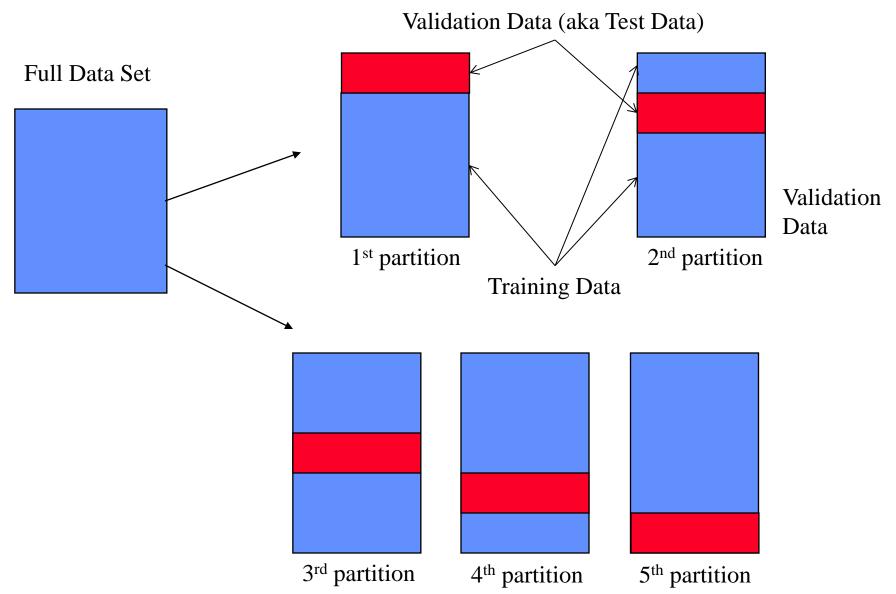
The k-fold Cross-Validation Method

- Why just choose one particular 90/10 "split" of the data?
 - In principle we could do this multiple times
- "k-fold Cross-Validation" (e.g., k=10)
 - randomly partition our full data set into k disjoint subsets (each roughly of size n/k, n = total number of training data points)

```
for i = 1:10 (here k = 10)train on 90% of data,-Acc(i) = accuracy on other 10%
```

- end
- •Cross-Validation-Accuracy = $1/k \sum_{i} Acc(i)$
- choose the method with the highest cross-validation accuracy
- common values for k are 5 and 10
- Can also do "leave-one-out" where k = n

Disjoint Validation Data Sets



CS-171 Final Review

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