

Intro Linear Algebra 3A: midterm 1

Wednesday April 20, 2:00- 2:50pm

There are 3 exercises, worth a total of $100 = 42 + 28 + 30$ points.

Non-graphical calculators allowed. No books or notes allowed.

Provide computations and or explanations, unless stated otherwise.

Name:

Student ID:

Exercise 1 ($42 = 6 + 16 + 8 + 5 + 7$ pts)

Let

$$A = \begin{bmatrix} -1 & 1 & 0 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \\ -3 & 0 & -1 & 0 & 1 \end{bmatrix}, \mathbf{b} = \begin{bmatrix} 2 \\ 5 \\ -3 \end{bmatrix}, C = \begin{bmatrix} 1 & 1 \\ 0 & -1 \\ 0 & 1 \\ 1 & -1 \\ 2 & 0 \end{bmatrix}.$$

- (a) Compute AC .
- (b) Compute the reduced row echelon form of the augmented matrix $[A|\mathbf{b}]$.
- (c) Solve $A\mathbf{x} = \mathbf{b}$ in parametric vector form.
- (d) Is the linear map corresponding to A onto?
- (e) Are the columns of A linearly independent? If they are dependent, find a linear dependence relation among the columns of A .

Solution:

(a)

$$\begin{bmatrix} 2 & -3 \\ 4 & 0 \\ -1 & -4 \end{bmatrix}.$$

(b)

$$\begin{bmatrix} 1 & 0 & 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 0 & 2 & 3 \end{bmatrix}.$$

(c) $x_4[0, -1, 0, 1, 0]^T + x_5[1, 0, -2, 0, 1]^T + [0, 2, 3, 0, 0]^T$.(d) Yes, pivot in every row of reduced row echelon form of A (no zero rows in RREF of A).(e) No. For example, second column minus fourth column is 0 (find any vector in null space: you can find null space from c, which is just $x_4[0, -1, 0, 1, 0]^T + x_5[1, 0, -2, 0, 1]^T$).

Exercise 2 ($28 = 7 + 15 + 6$ pts)

Consider the vectors

$$\mathbf{u}_1 = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}, \mathbf{u}_2 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \mathbf{u}_3 = \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}$$

in $\mathbf{R}^3$.

- Show that $\mathbf{e}_1 = [1, 0, 0]^T$, $\mathbf{e}_2 = [0, 1, 0]^T$ and $\mathbf{e}_3 = [0, 0, 1]^T$ are in the span of $\mathbf{u}_1$, $\mathbf{u}_2$ and $\mathbf{u}_3$.
- Construct a 2×3 matrix A such that $A\mathbf{u}_1 = [0, 1]^T$, $A\mathbf{u}_2 = [1, 0]^T$ and $A\mathbf{u}_3 = [1, 1]^T$.
- How many linear maps $T : \mathbf{R}^3 \rightarrow \mathbf{R}^2$ satisfy $T(\mathbf{u}_1) = [0, 1]^T$, $T(\mathbf{u}_2) = [1, 0]^T$ (choose from 0, 1, or infinitely many)? Explain.

Solution:

- One can compute the RREF of $[\mathbf{u}_1 \mathbf{u}_2 \mathbf{u}_3]$, which is the identity: this means that any augmented system is consistent. In fact, one has:

$$\mathbf{e}_1 = -\mathbf{u}_2 + \mathbf{u}_3$$

$$\mathbf{e}_2 = -\mathbf{u}_1 + 3\mathbf{u}_2 - \mathbf{u}_3$$

$$\mathbf{e}_3 = 2\mathbf{u}_2 - \mathbf{u}_3.$$

(these are unique solutions).

- There are multiple ways of solving this, one is by using 6 variables for the matrix system, and then solving it. But, in our case, we can use our expressions from (a) to find:

$$\begin{bmatrix} 0 & 2 & 1 \\ 1 & -2 & -1 \end{bmatrix}.$$

This matrix satisfies the required properties, and is unique.

- Infinitely many. If one makes a system, one gets a system in 6 variables with 4 equations which is consistent by (b). Hence there are at least 2 free variables and infinitely many solutions.

Exercise 3 (30 pts)

True or false? **No** explanation required. Points is $-10 + 4 \cdot \# \text{correct}$.

- (1) The vectors $[1, 2, 3]^T$ and $[2, 4, 5]^T$ are linearly dependent.

- (2) Let $T : \mathbf{R}^n \rightarrow \mathbf{R}^m$ be a linear transformation. Then there is a unique $n \times m$ matrix A such that $T(\mathbf{x}) = A\mathbf{x}$ for all $\mathbf{x} \in \mathbf{R}^n$.

- (3) The map $\mathbf{R}^3 \rightarrow \mathbf{R}^3$ given by $(x, y, z) \mapsto (xy + 1 - yx - 1 + x + y, y + z, z)$ is not linear.

- (4) Let T be the linear map on the xy -plane which is the reflection in the x -axis. Then T is one-to-one.

- (5) Let A be an $n \times n$ matrix and let $\mathbf{x} \in \mathbf{R}^n$ be such that $A\mathbf{x} = \lambda\mathbf{x}$ for some $\lambda \in \mathbf{R}$. Then one has $A^{42}\mathbf{x} = \lambda^{42}\mathbf{x}$.

- (6) Let A be a matrix with n columns, p pivots and f free variables. Then one has $n = p + f$.

- (7) Let $T : \mathbf{R}^7 \rightarrow \mathbf{R}^3$ be a linear map. Then T is onto.

- (8) There is a linear map $T : \mathbf{R}^2 \rightarrow \mathbf{R}^2$ with

$$T([1, 0]^T) = [1, 0]^T, \quad T([0, 1]^T) = [1, 1]^T, \quad T([1, -1]^T) = [0, 1]^T.$$

- (9) The linear map corresponding to the matrix

$$\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$$
 is the projection onto the x_1 -axis.

- (10) Let A, B be square matrices such that $AB = BA$. Then one has $(A + B)^3 = A^3 + 3A^2B + 3AB^2 + B^3$.

Solution:

- (1) False, not multiple of each other.
- (2) False, it is an $m \times n$ matrix.
- (3) False, it is linear, just $(x, y, z) \mapsto (x + y, y + z, z)$.
- (4) True (if $T\mathbf{x} = T\mathbf{y}$, then $\mathbf{x} = T^2\mathbf{x} = T^2\mathbf{y} = \mathbf{y}$).

- (5) True, $A^{42}\mathbf{x} = \lambda A^{41}\mathbf{x} = \dots = \lambda^{42}\mathbf{x}$.
- (6) True, one sees this from the definition.
- (7) False, 0 matrix is not onto.
- (8) False, the first two equations show that the matrix would be

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}.$$

But this matrix has $A[1, -1]^T = [0, -1]^T$, which is not $[0, 1]^T$. So no such map exists.

- (9) False, the map is given by

$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}.$$

- (10) True, one can just work out the product and use $AB = BA$.